

Rapid Forecasts of Earthquake Hazards from Crustal Deformation Patterns





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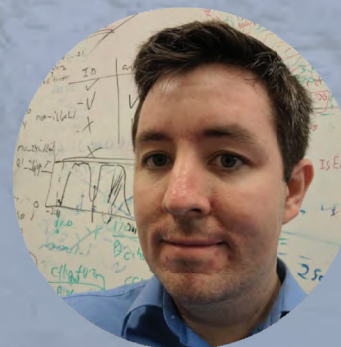
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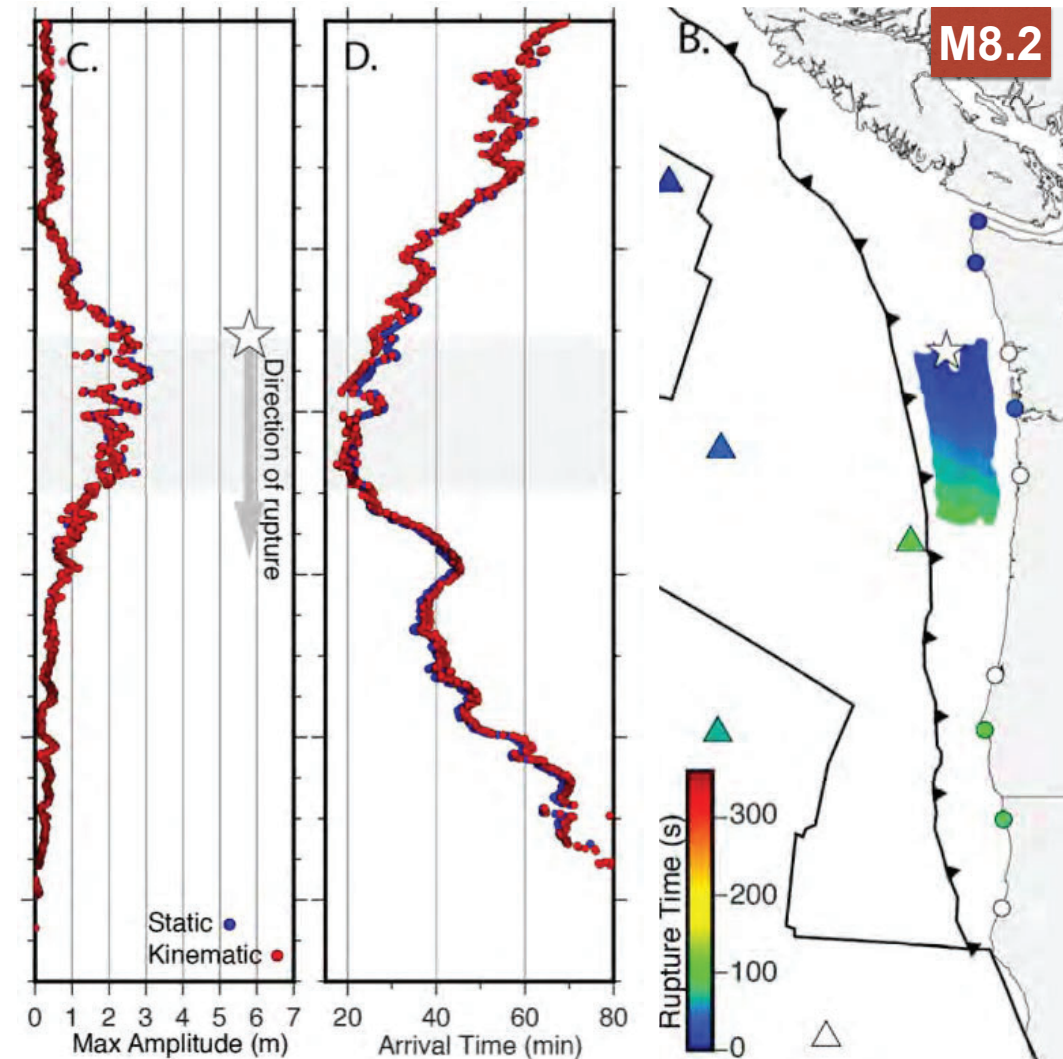


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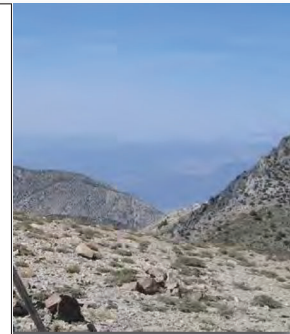
The problem: Local tsunami warning

- Local warning is forecasting tsunami hazards **before** they impact the coastlines adjacent to a rupture.
- It requires characterizing the tsunami in **minutes**
- It remains a challenging problem in **all tsunami prone regions**

Williamson et al., JGR, 2019



Our solution: Land-based GNSS



Preliminary GPS time series provided by the ABIA team at JPL and Caltech. All original GEONET B1BEX data provided to Caltech by the Geospatial Information Authority (GSI) of Japan.

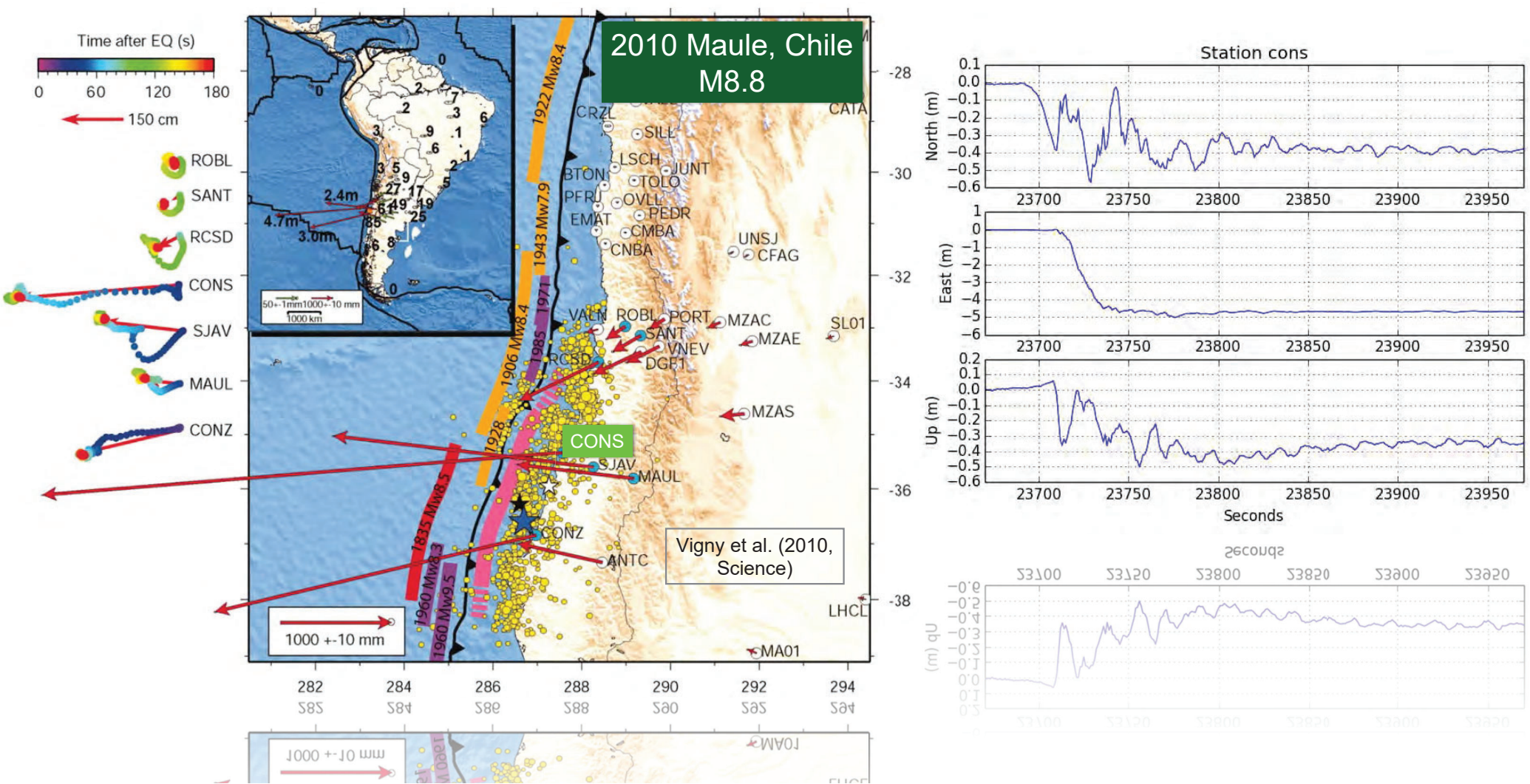
1 m →

Geophysical Institute, Univ. Alaska Fairbanks

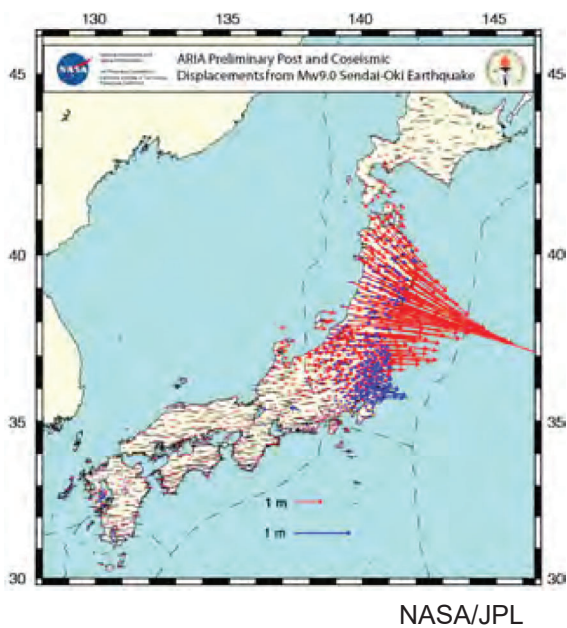
0.2 m

500 km

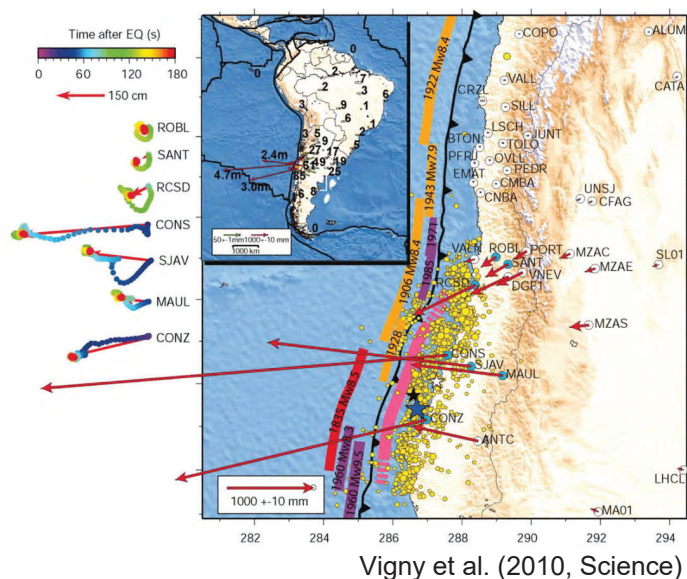
Our solution: Land-based GNSS



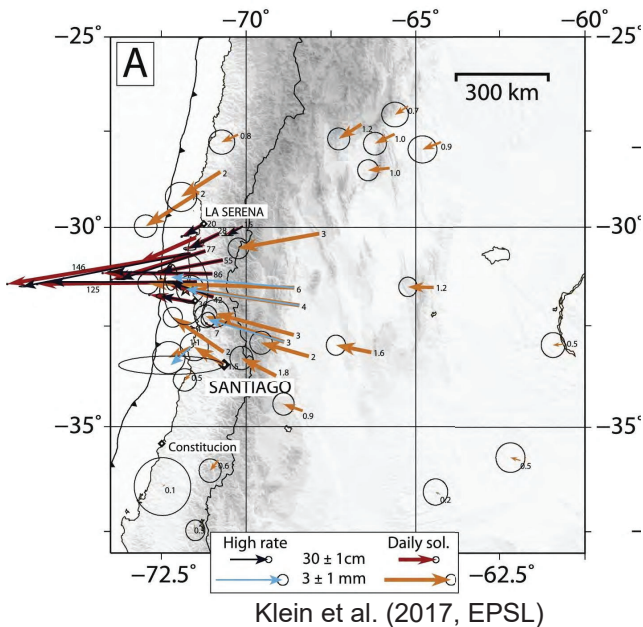
GNSS correlates to tsunami impacts



2011 M9.0 Tohoku-oki
5m displacements
30m+ tsunami



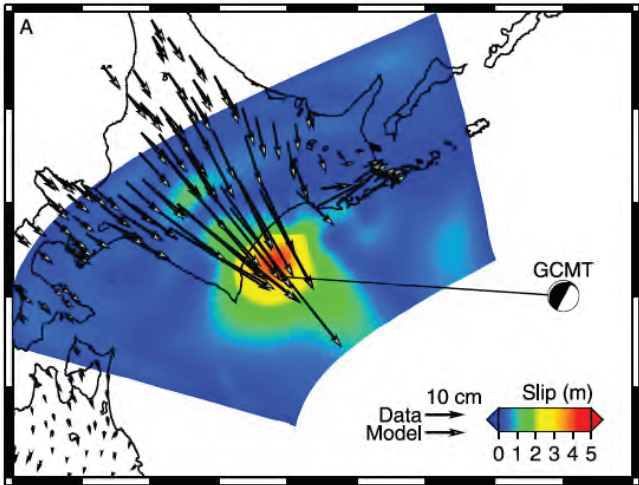
2010 8.8 Maule
5m displacements
20m tsunami



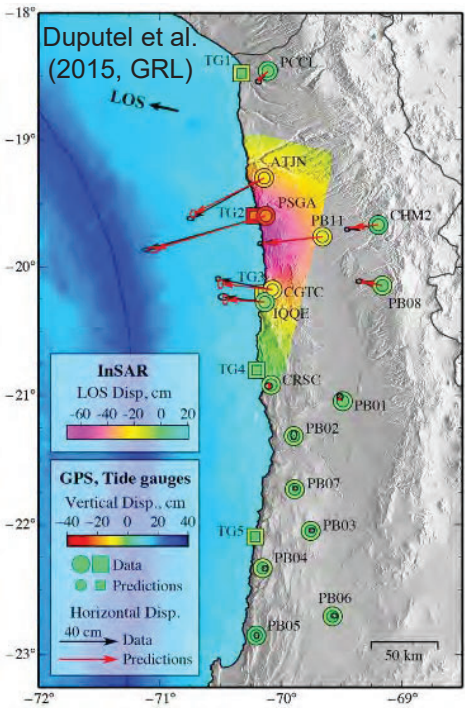
2015 8.3 Illapel
2m displacements
10m tsunami

GNSS correlates to tsunami impacts

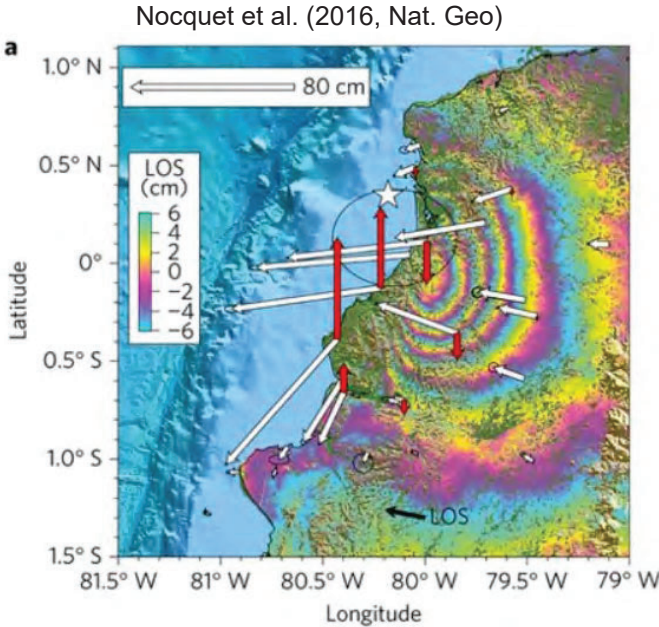
Crowell et al. (2012, GRL)



2003 M8.3 Tokachi-oki
0.5m displacements
1m tsunami

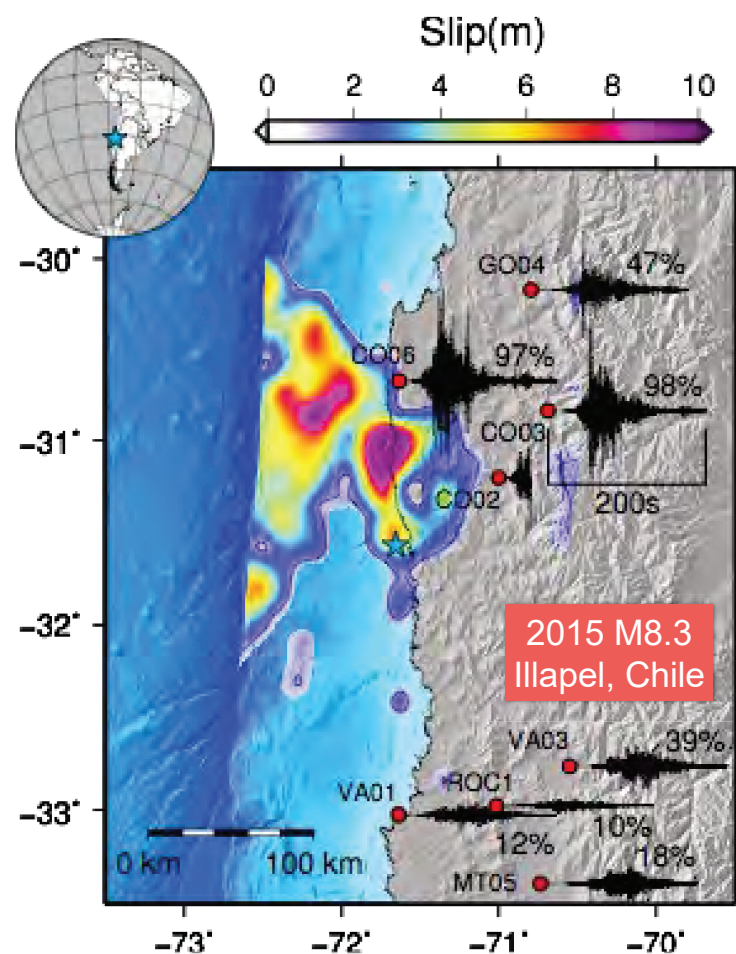
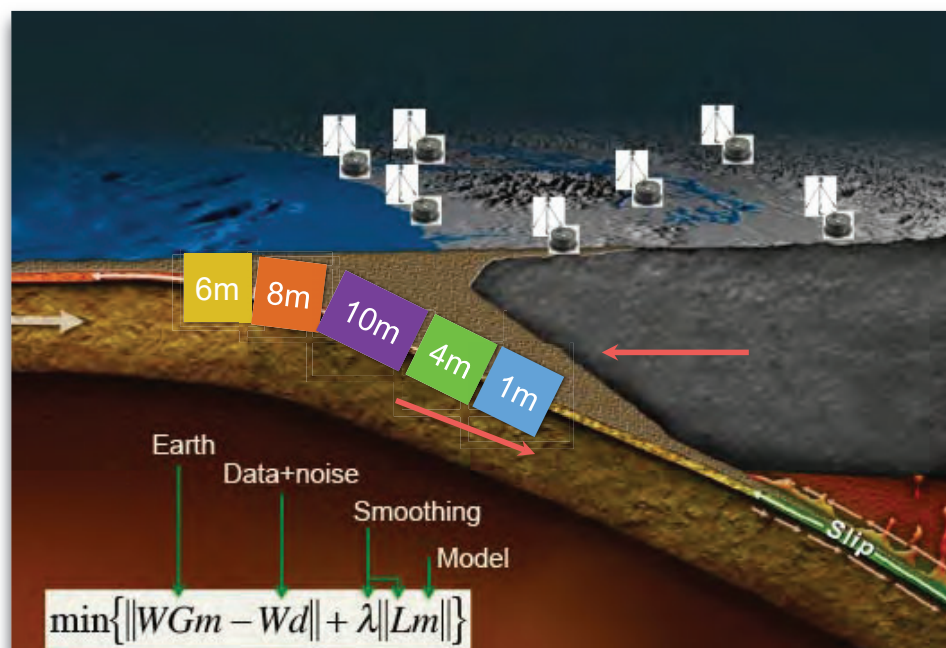


2014 M8.1 Iquique
1-2m displacements
2m tsunami



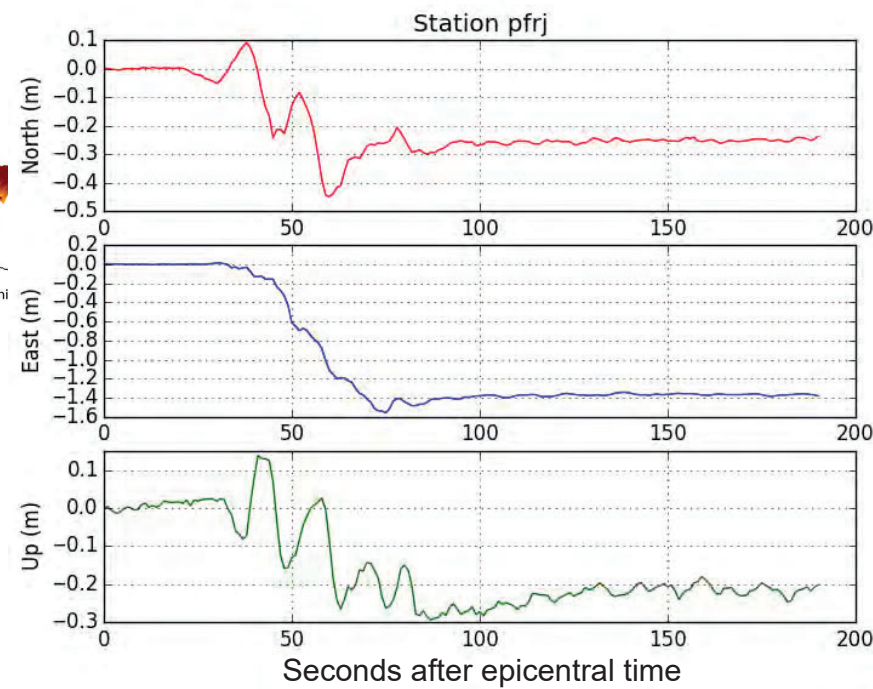
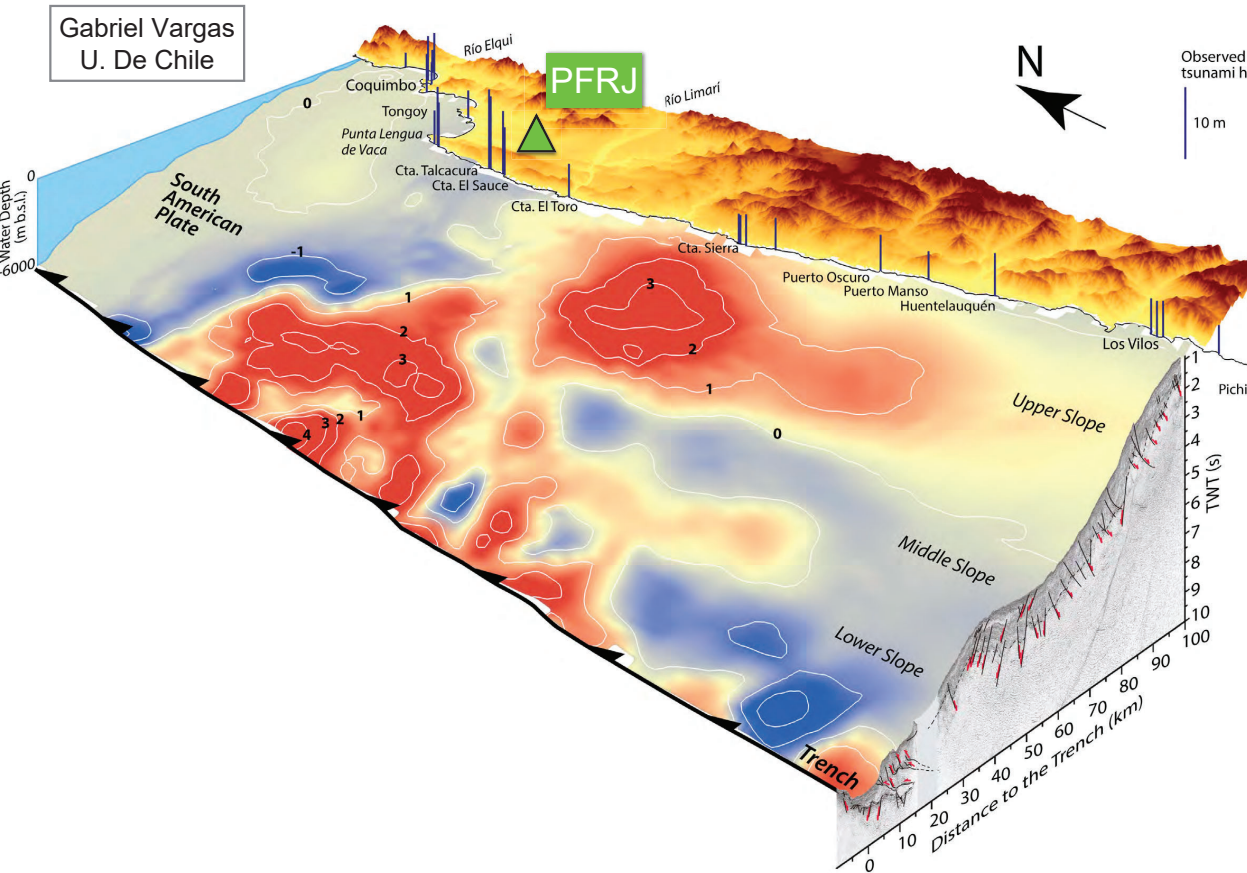
2016 M7.8 Ecuador
1m displacements
1m tsunami

The correlation is complex

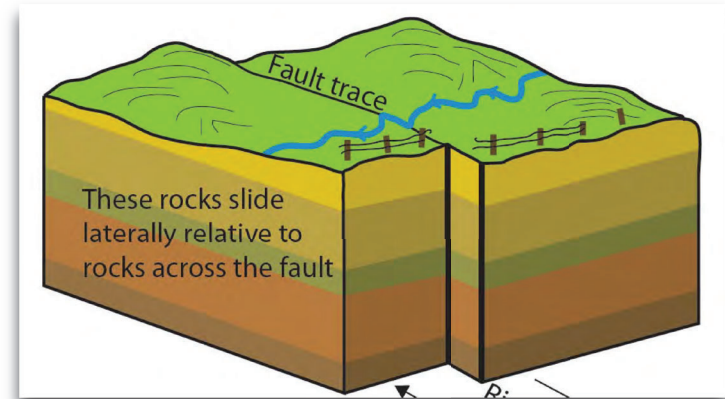
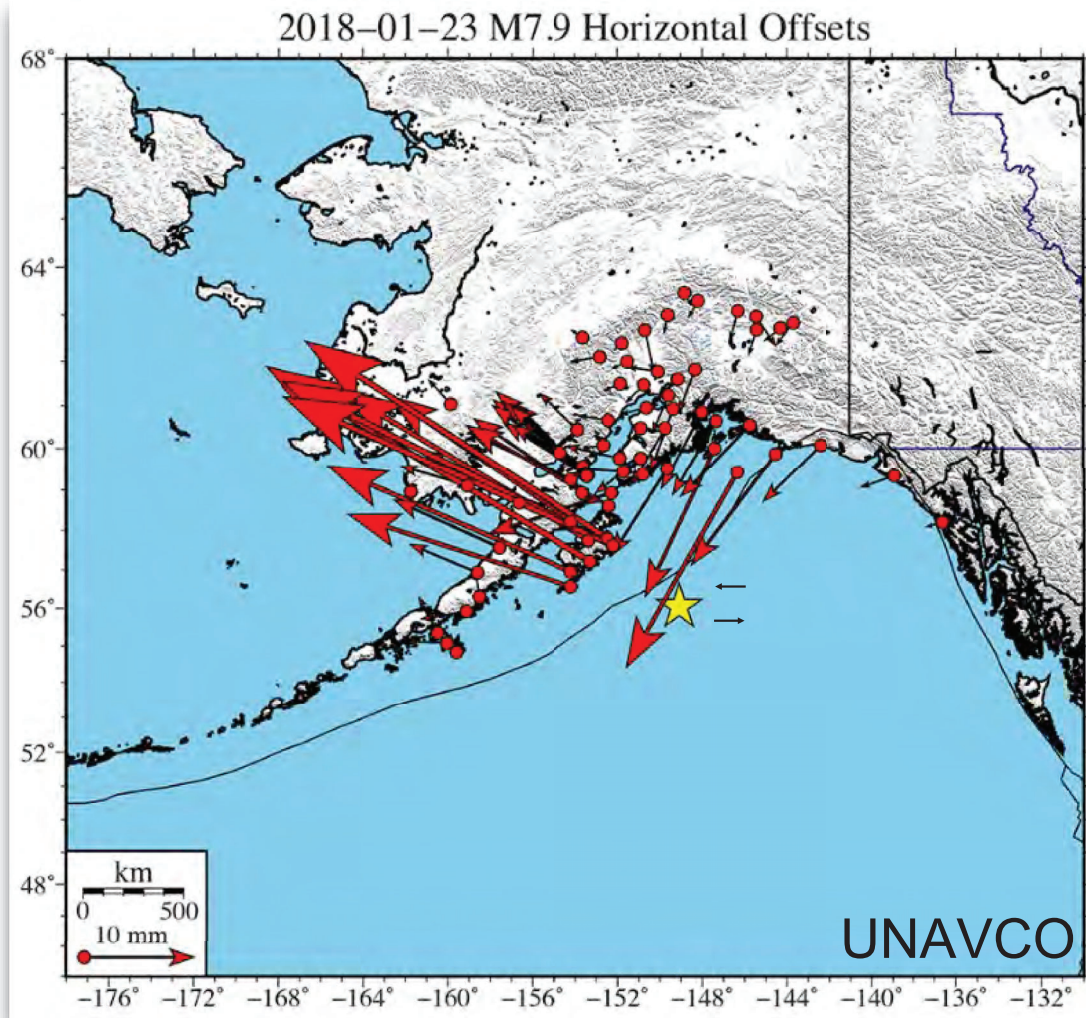


Melgar et al. (2016, GRL)

The correlation is complex



GNSS identifies non-events as well



- ▶ Large **near-trench** earthquake
- ▶ **Strike-slip** mechanism
- ▶ Tsunami < **20cm**
- ▶ PTWC **issued warning** for Alaska & U.S. West Coast

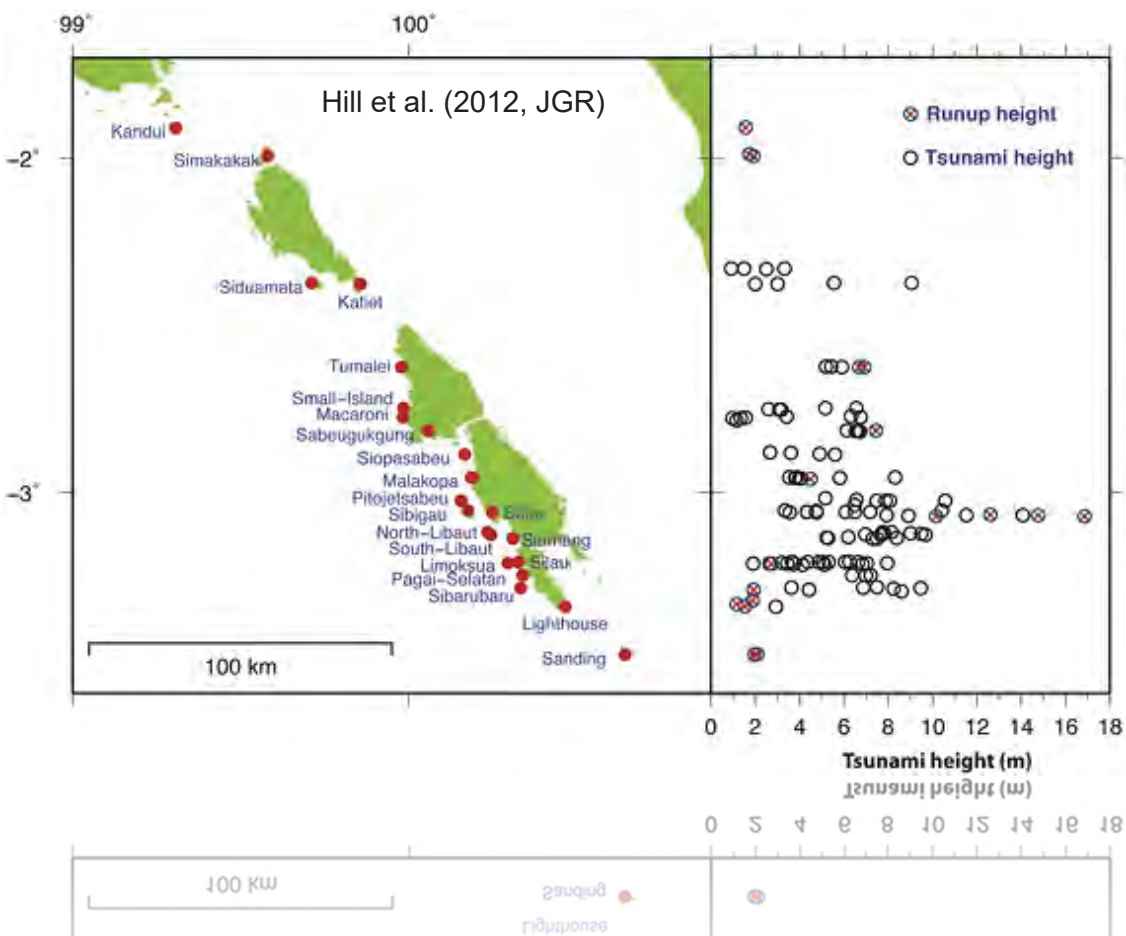
GNSS identifies tsunami earthquakes too

A *tsunami earthquake* produces a tsunami **much larger** than what would be **expected for its magnitude**



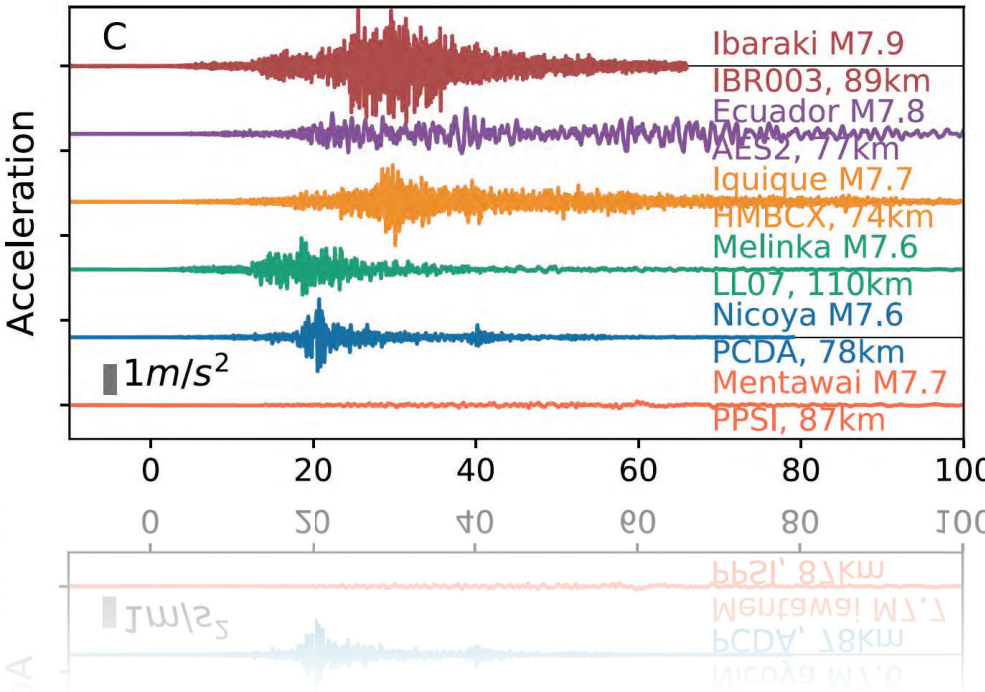
- 2010 M7.8 Mentawai, Indonesia
- ~15m tsunami

GNSS identifies tsunami earthquakes too



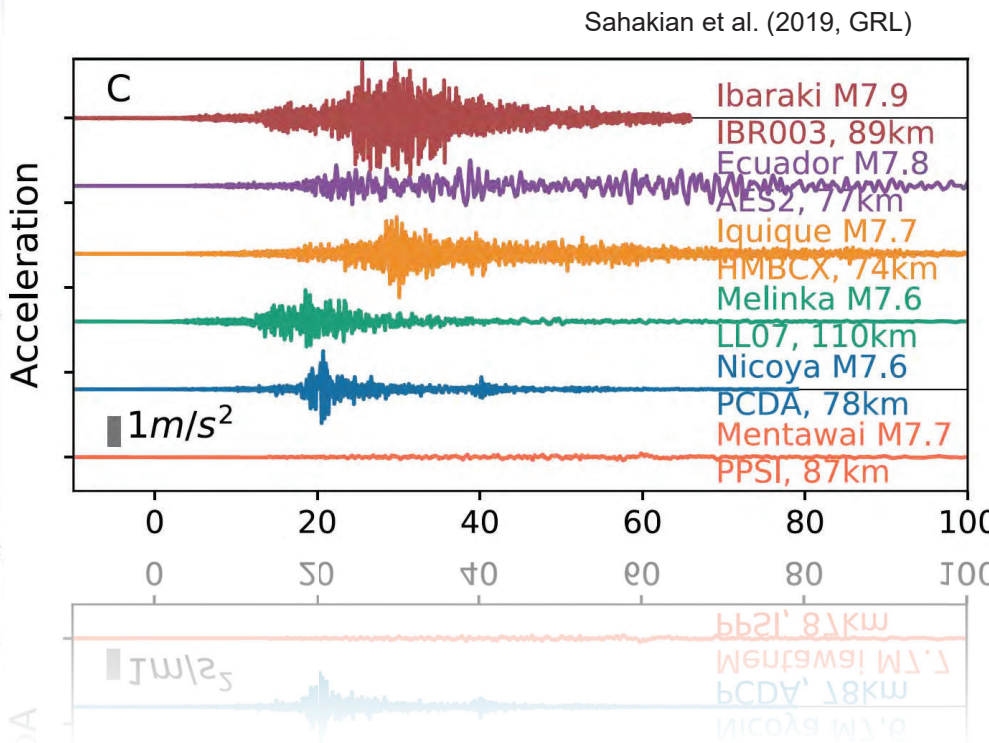
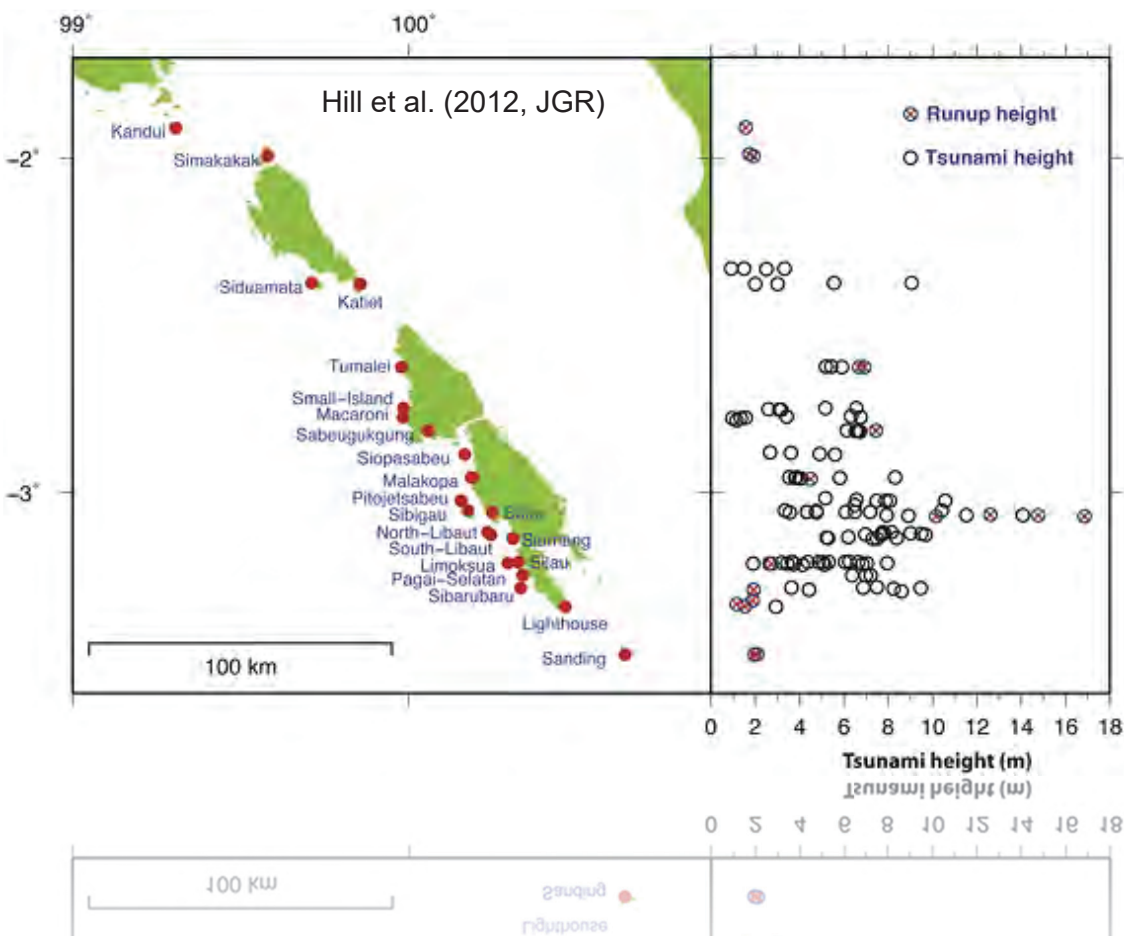
2010 M7.8
Mentawai, Indonesia

Sahakian et al. (2019, GRL)

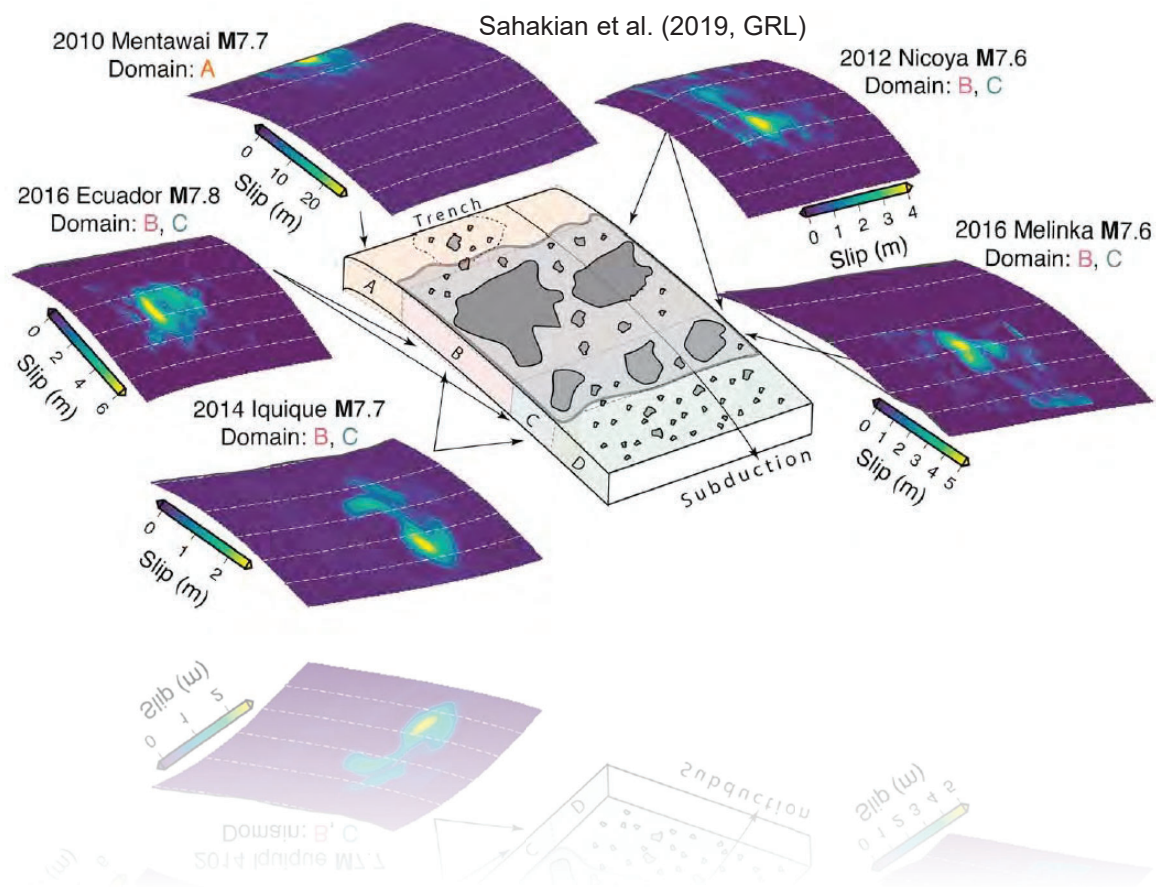


GNSS identifies tsunami earthquakes too

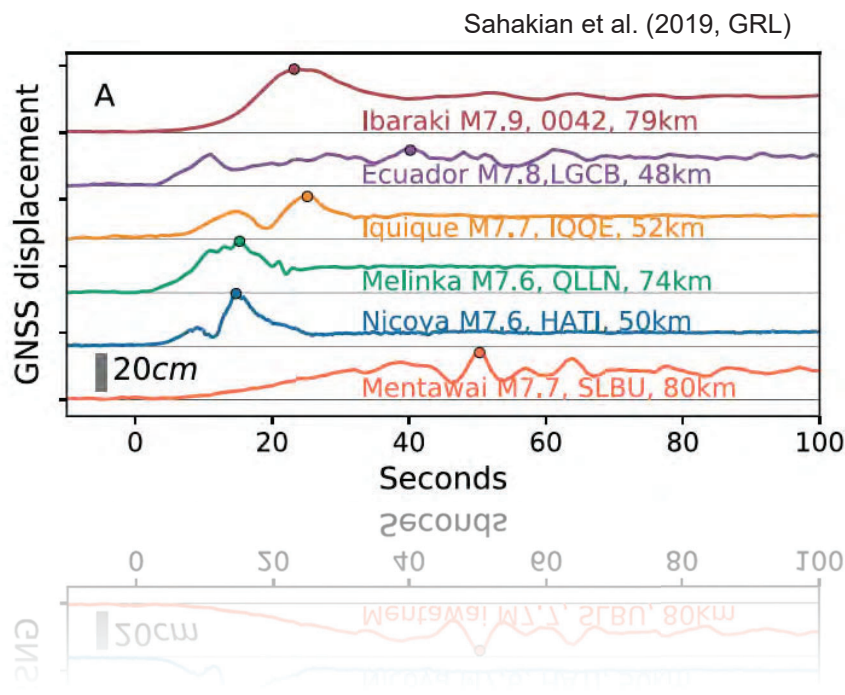
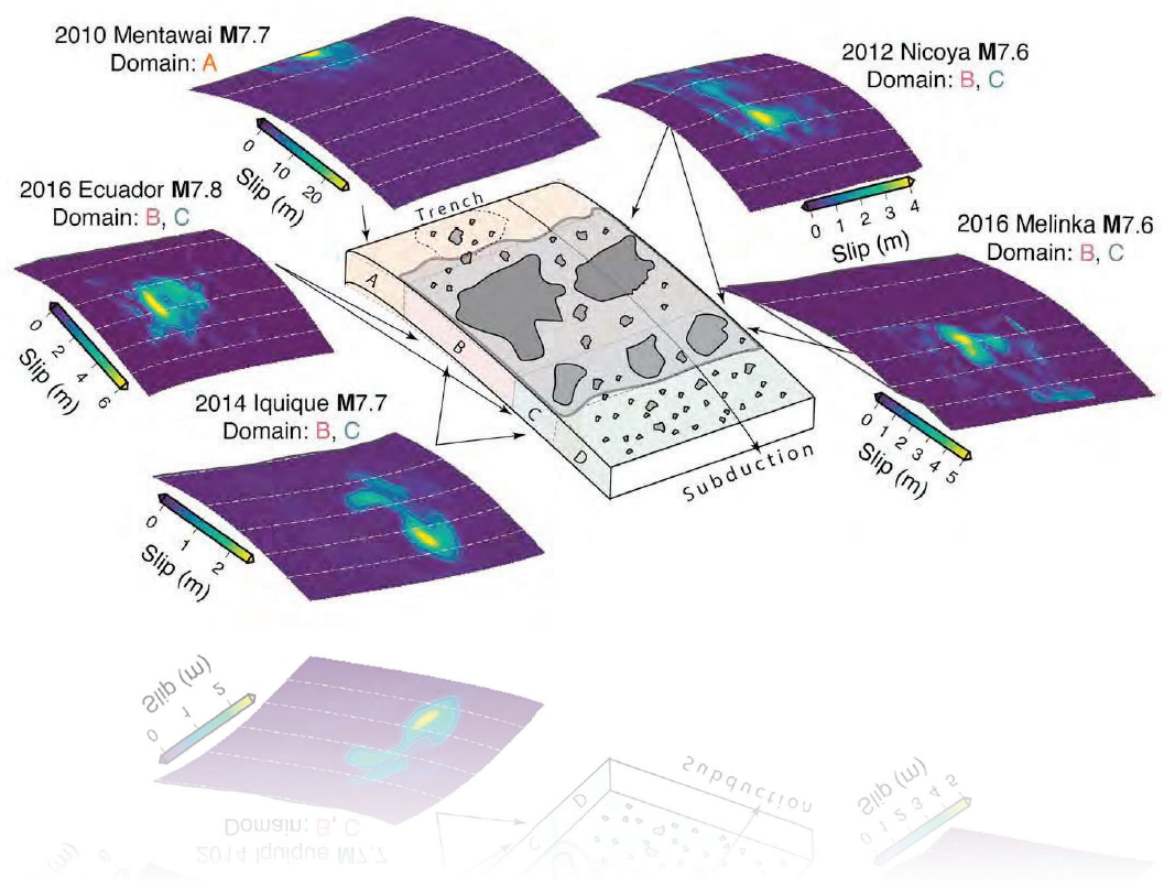
These events **shake like a magnitude 6** but make a **tsunami like a magnitude 9**



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OREGON

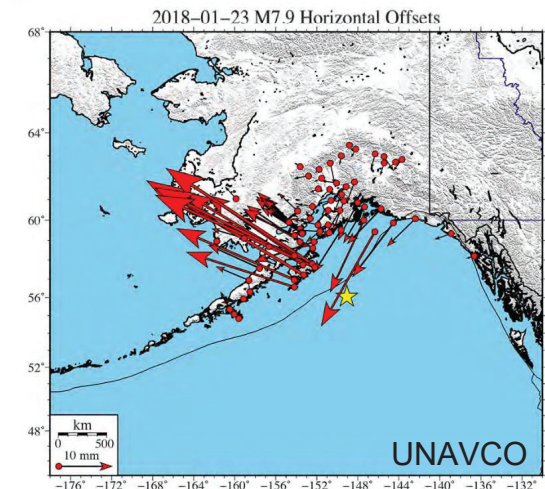
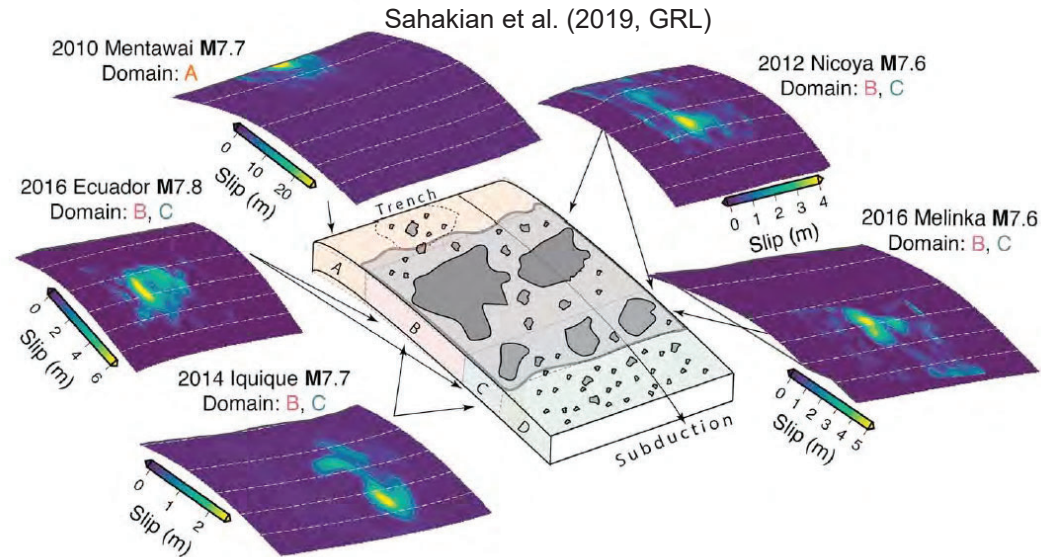


GNSS identifies tsunami earthquakes too



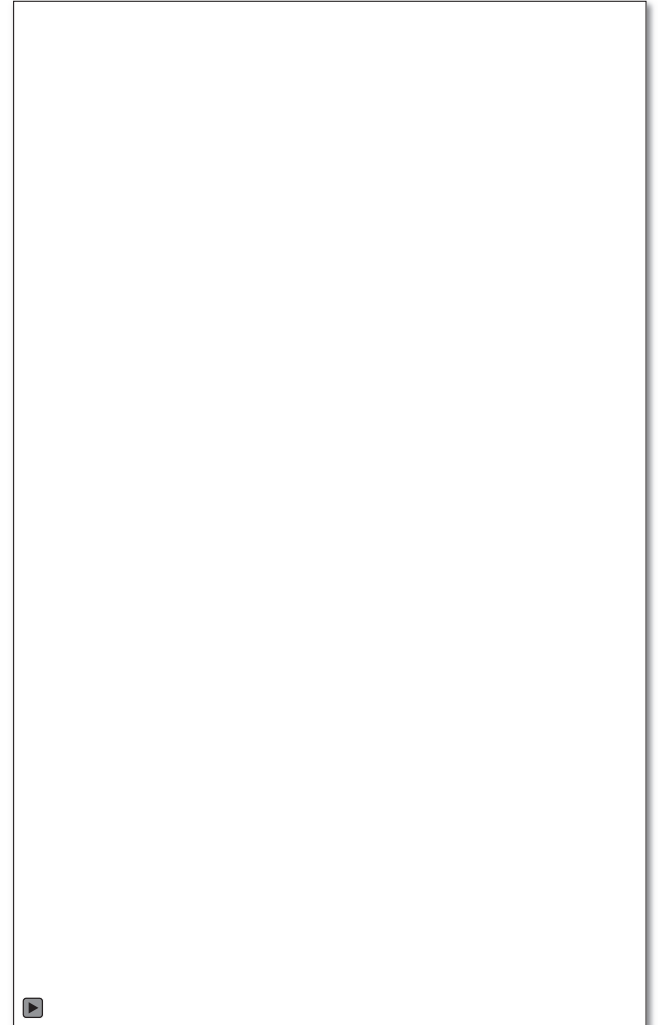
We need a flexible algorithm

- Our working hypothesis is that **time-dependent** GNSS can be used to **forecast** tsunami impacts
- GNSS contains information that **correlates** strongly to the deformation of the **seafloor**
- But the relationship is not simple and **traditional** seismological algorithms do not perform well for all potential situations

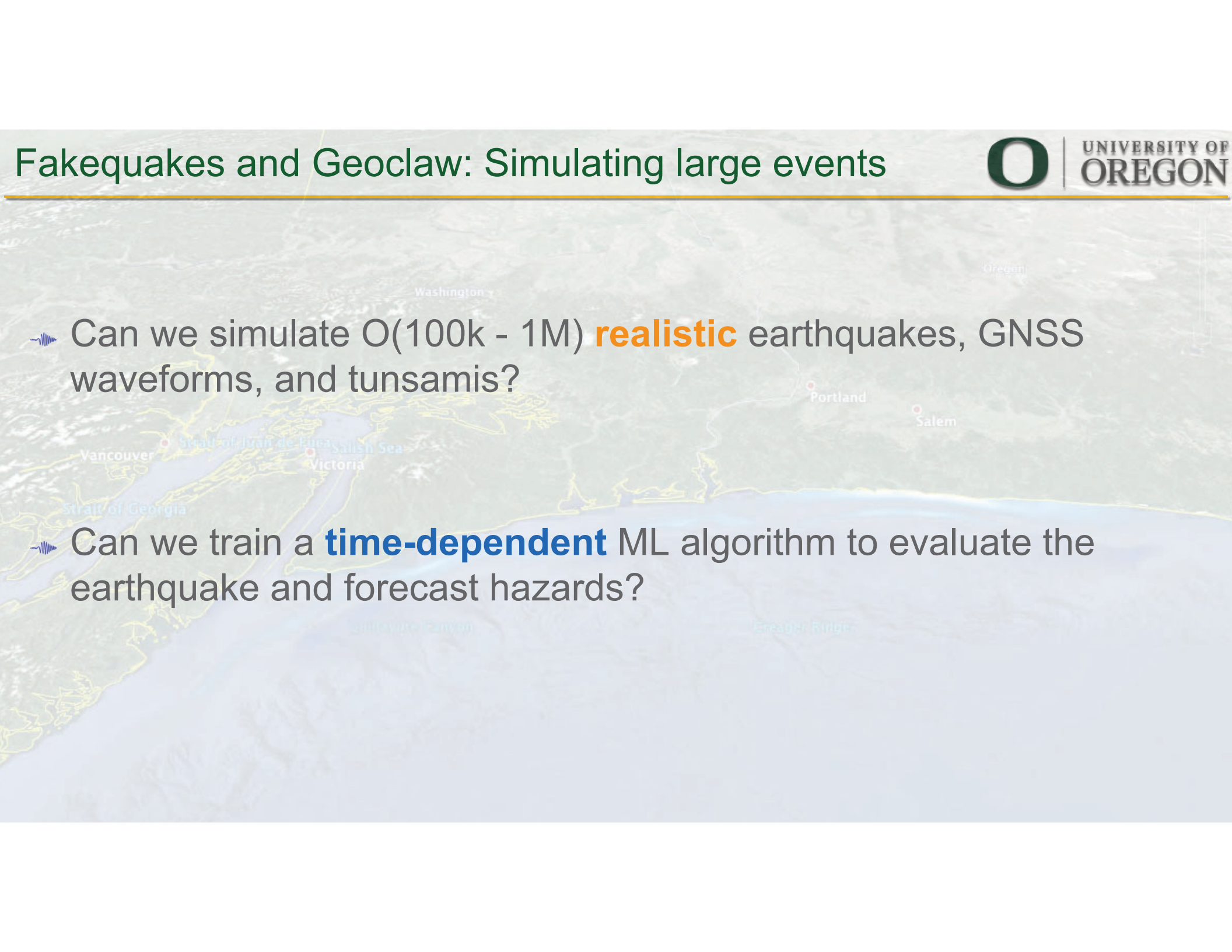


We need a flexible algorithm

- Our solution is to use machine learning
- The challenge is to develop a large enough dataset for training
- We solve this through simulation



Fakequakes and Geoclaw: Simulating large events

- 
- ▶ Can we simulate $O(100k - 1M)$ **realistic** earthquakes, GNSS waveforms, and tunsamis?
 - ▶ Can we train a **time-dependent** ML algorithm to evaluate the earthquake and forecast hazards?

Fakequakes:

- **Stochastic** slip models based on findings by Mai & Beroza (2002)
- **Kinematic** parameters modified from Graves & Pitarka (2010)
- Parameter space is defined by what has been observed in **real events**
 - Correlation lengths & Hurst exponent
 - Rupture speeds
 - Rise times
 - Stress drops
 - Etc.

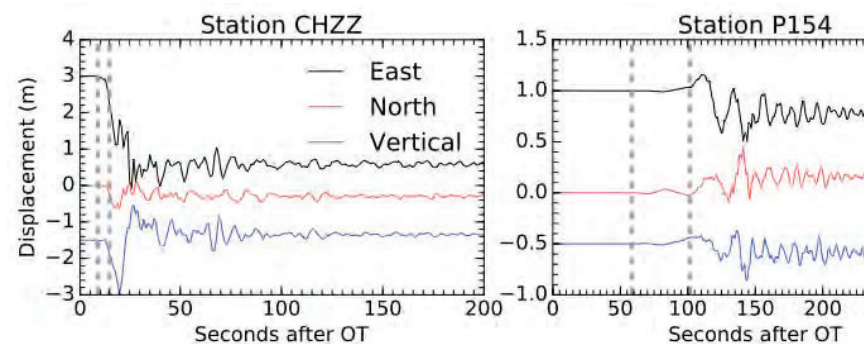


Fakequakes and Geoclaw: Simulating large events

Cascadia M8.6

Fakequakes:

- **Parallelized** and efficiently g
GNSS across a large network
- Assumes some reference Ea
includes **deterministic** propa

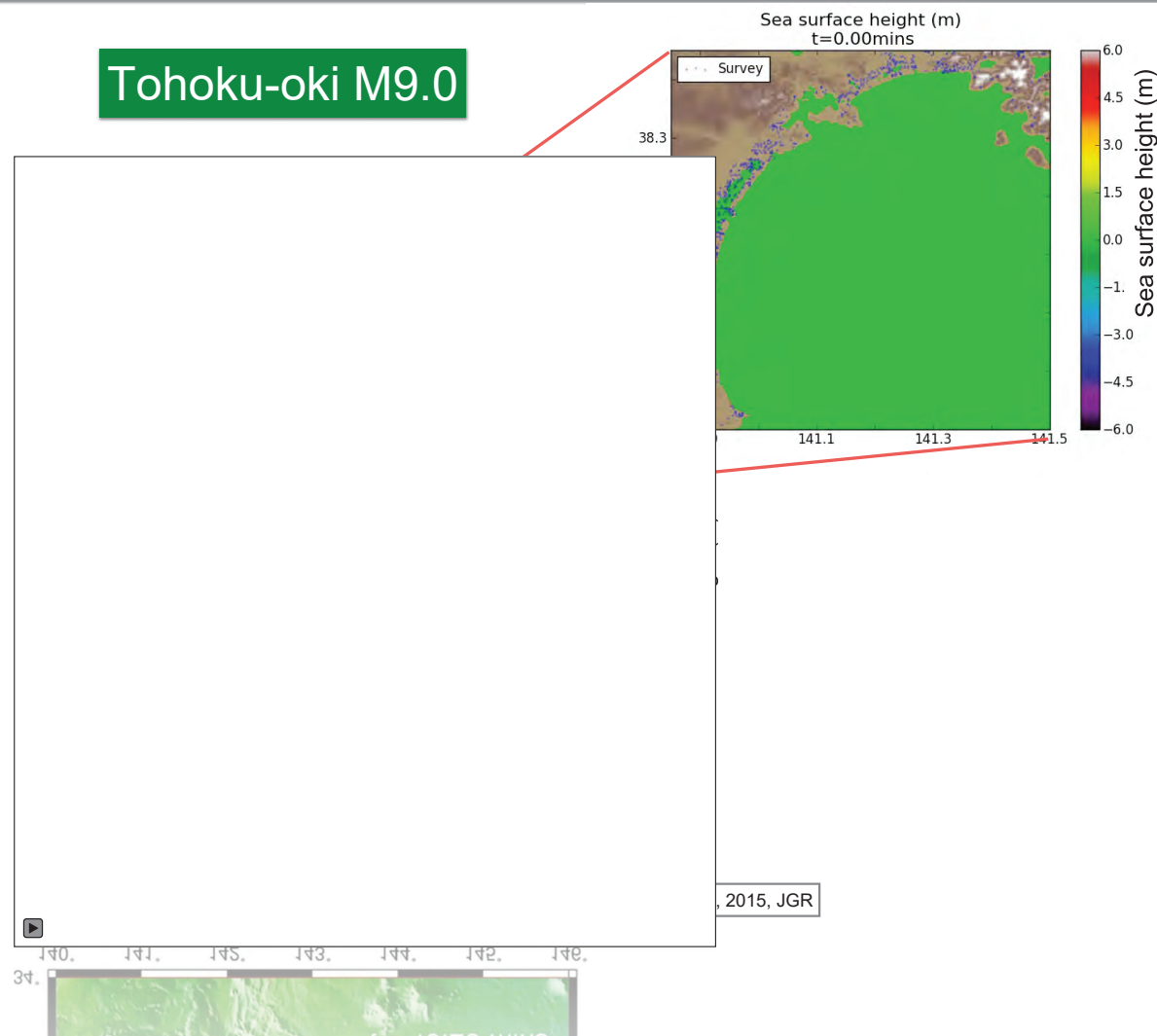


Fakequakes and Geoclaw: Simulating large events

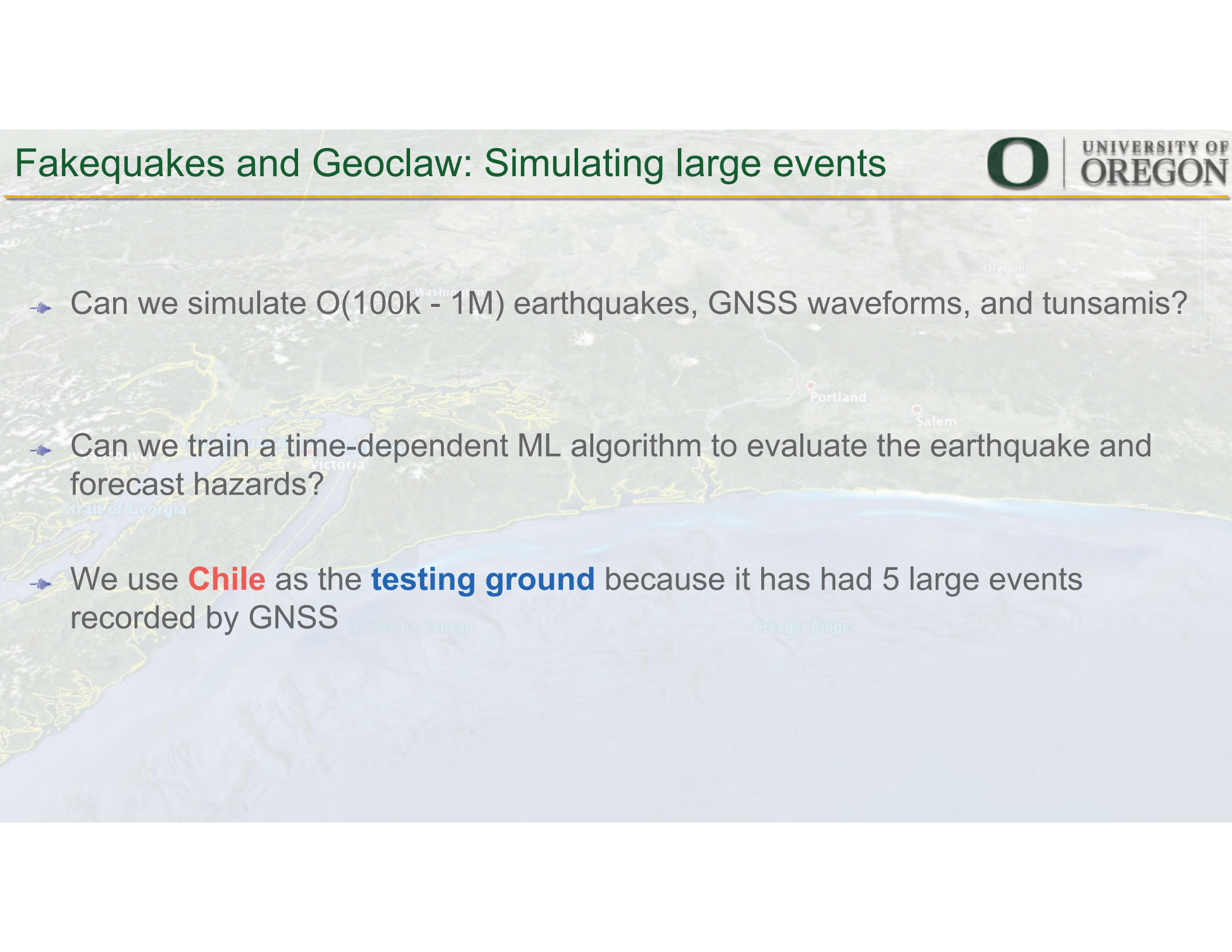
GeoClaw:

- GPU/CPU code that solves the shallow water equations (Qin & Leveque, 2019)
- Uses adjoint methods for efficiently guiding the mesh refinement (Davis et al., 2016)
- Includes inundation effects

Tohoku-oki M9.0

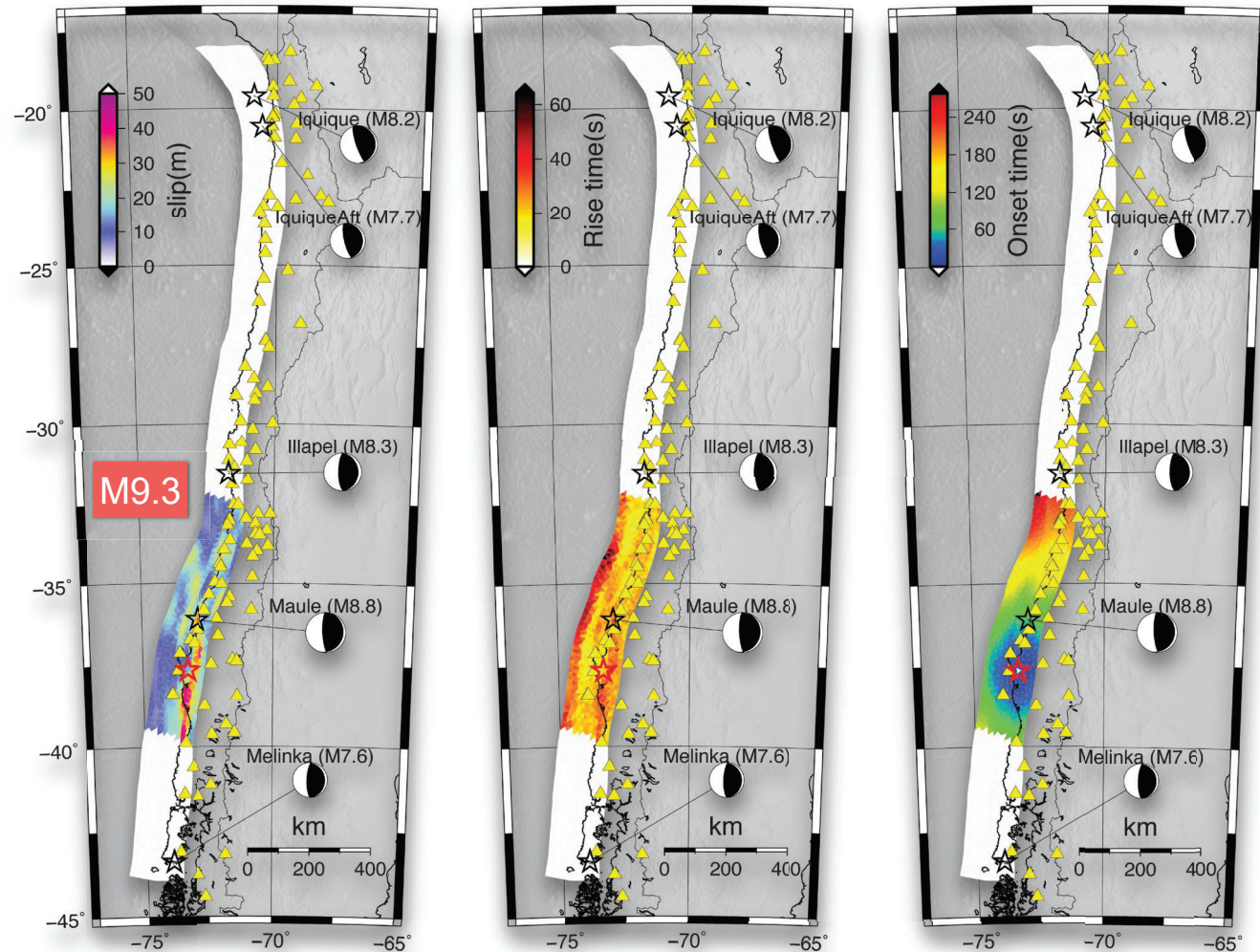


Fakequakes and Geoclaw: Simulating large events

- 
- ▶ Can we simulate $O(100k - 1M)$ earthquakes, GNSS waveforms, and tunsamis?
 - ▶ Can we train a time-dependent ML algorithm to evaluate the earthquake and forecast hazards?
 - ▶ We use **Chile** as the **testing ground** because it has had 5 large events recorded by GNSS

Simulations in Chile

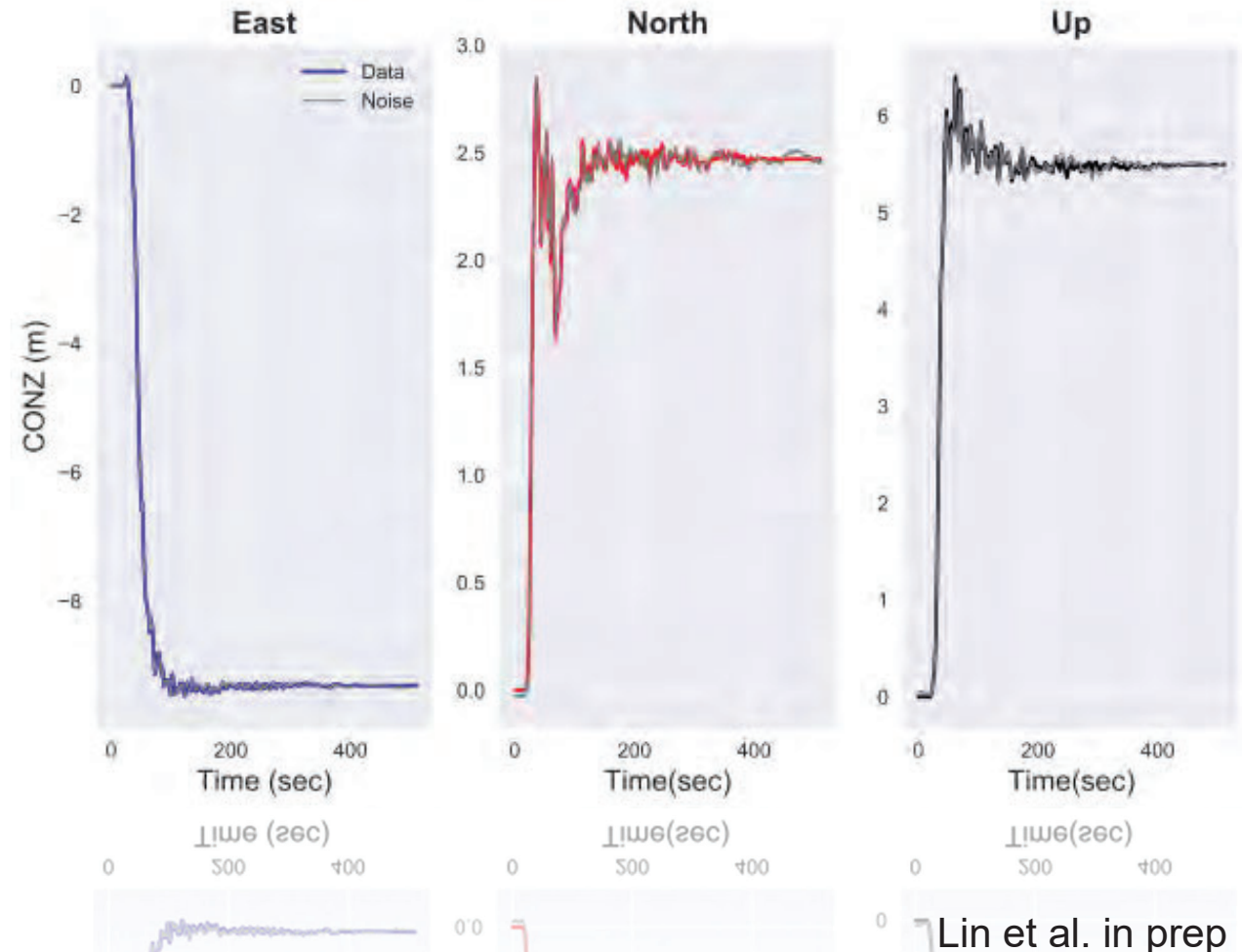
- Subduction geometry from **Slab 2** (Hayes et al., 2019)
- **50,000** simulated earthquakes (M7.5-M9.5) range
- GNSS data at 121 locations from the **operational network**
- **5 real events** that can be used as validation



Lin et al. in prep

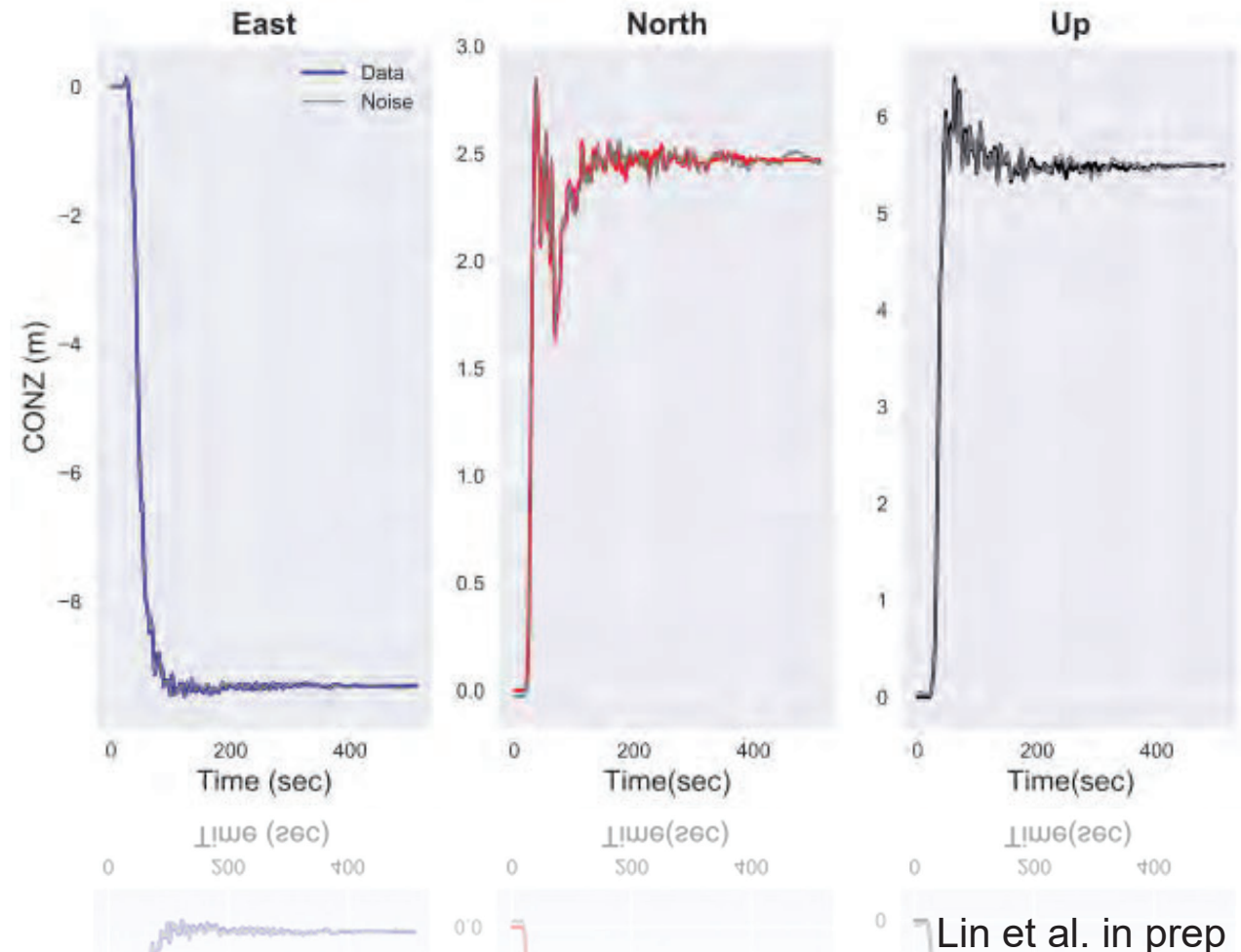
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Building an RNN

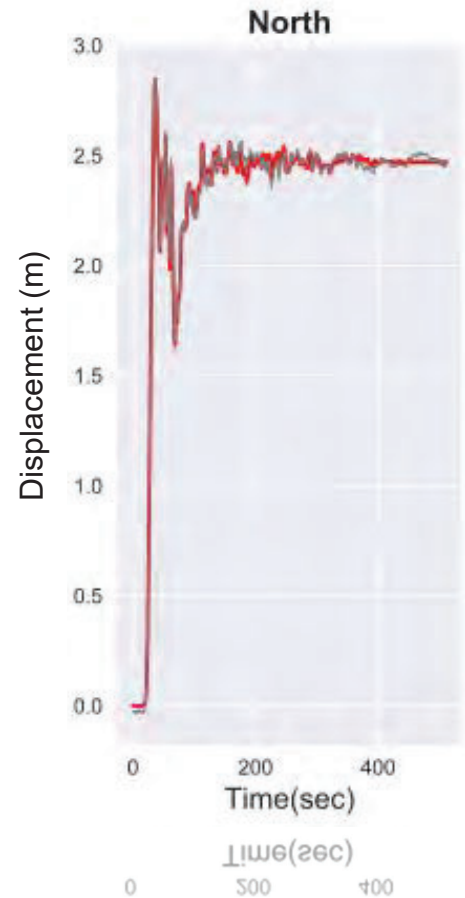
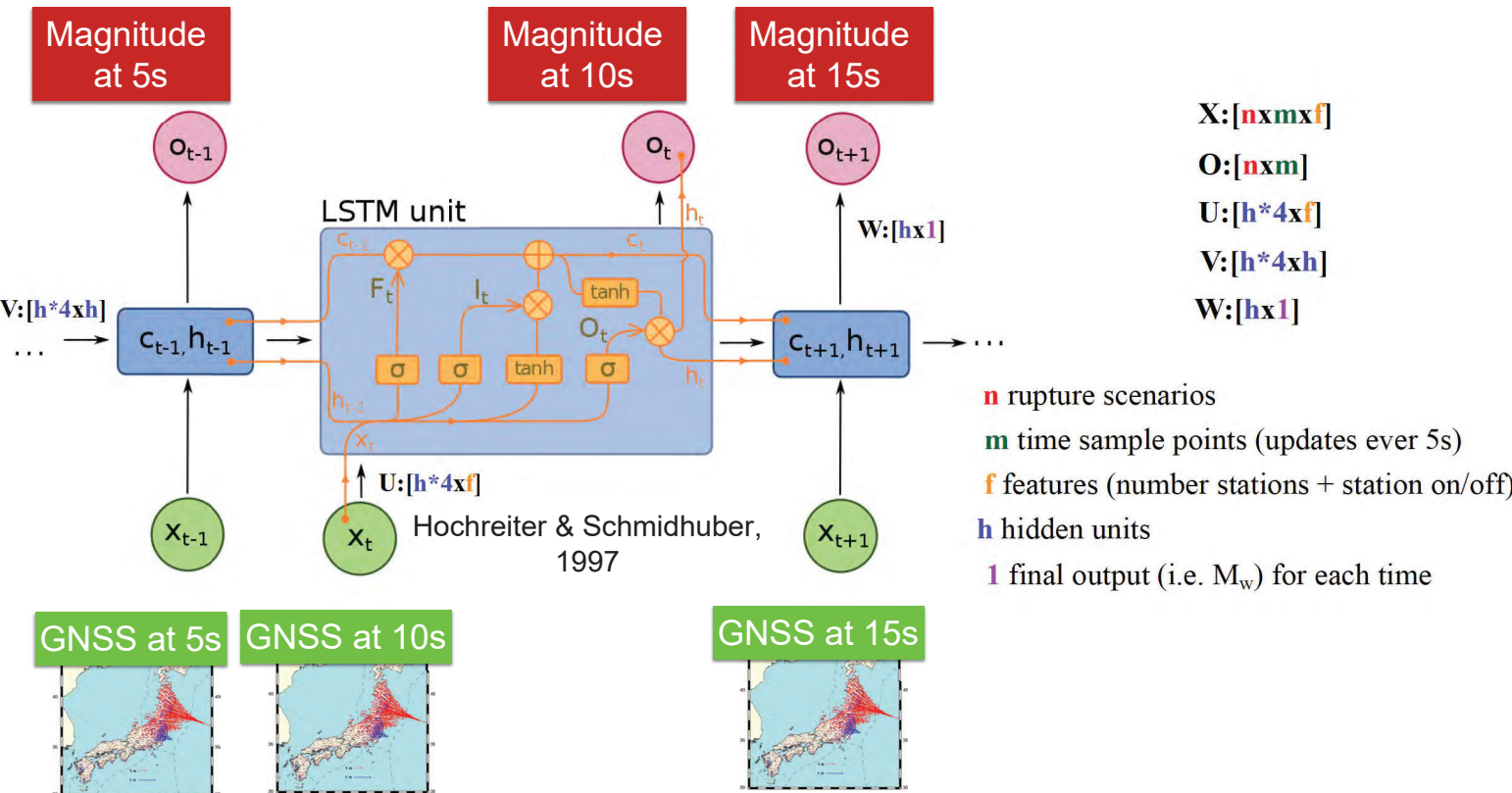
- ▶ We need a **temporally dynamic** algorithm.
- ▶ It's not just about what is happening now.
- ▶ The short-term **history** of the event has value
- ▶ We use a standard **recurrent** neural network architecture



Lin et al. in prep

Building an RNN

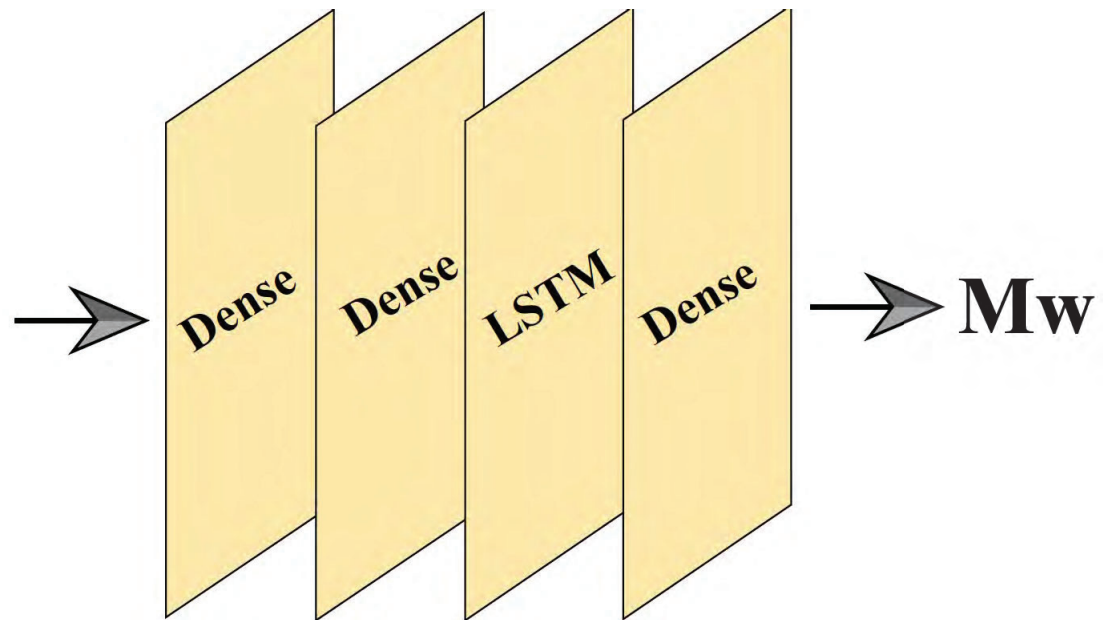
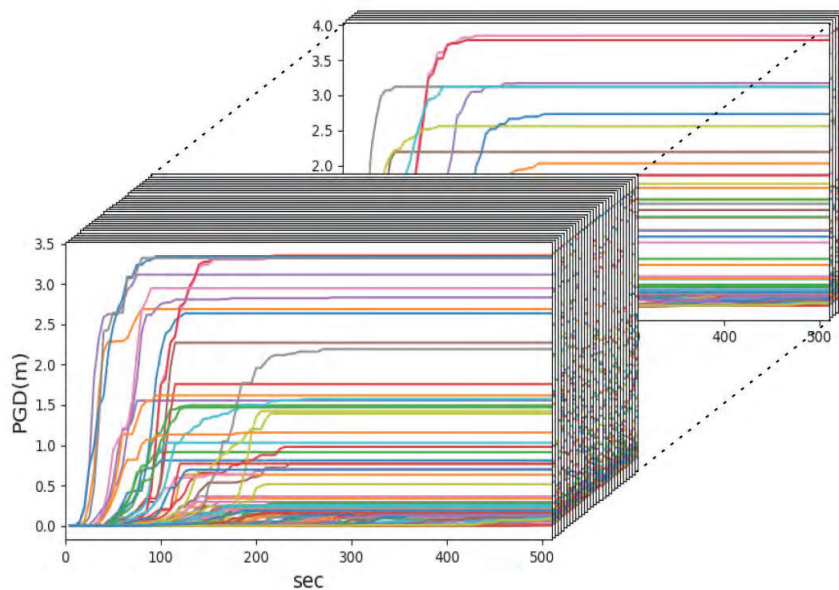
- First we simply predict magnitude
- Data is provided at 5s increments



Lin et al. in prep

Building an RNN

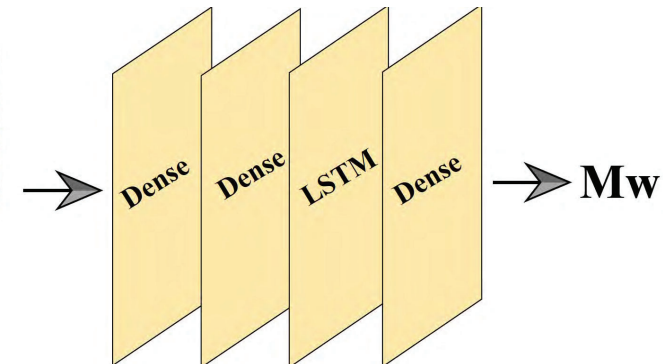
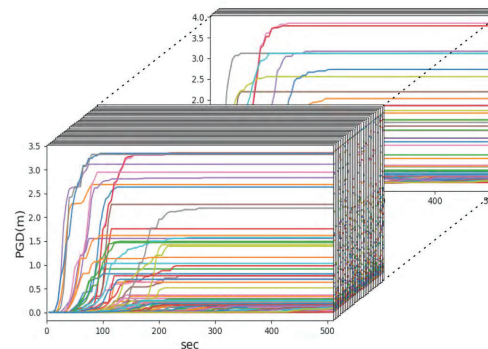
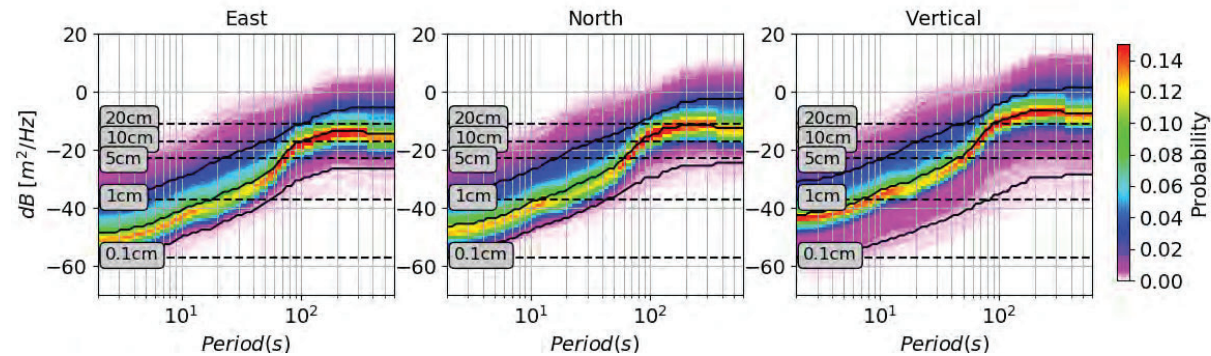
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256 events for a batch, total 10,000 epochs.
2,560,000 events, 121 stations, 512 seconds.

RNN training steps

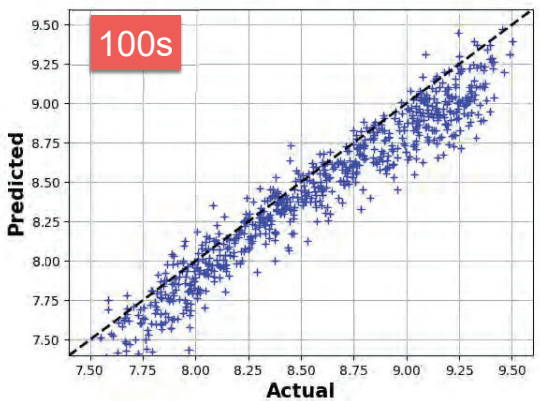
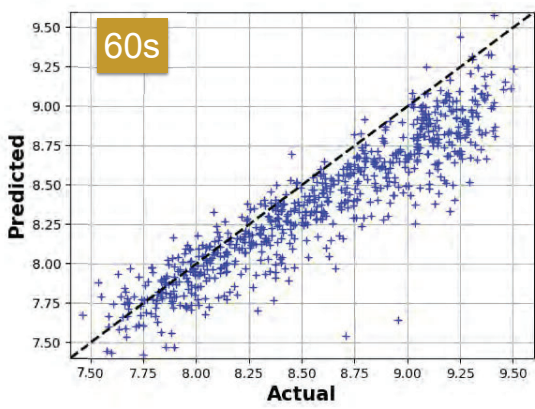
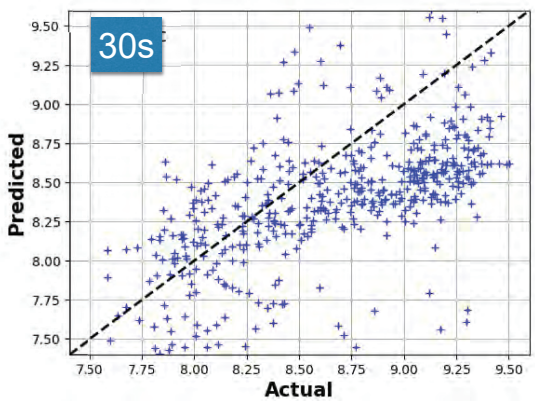
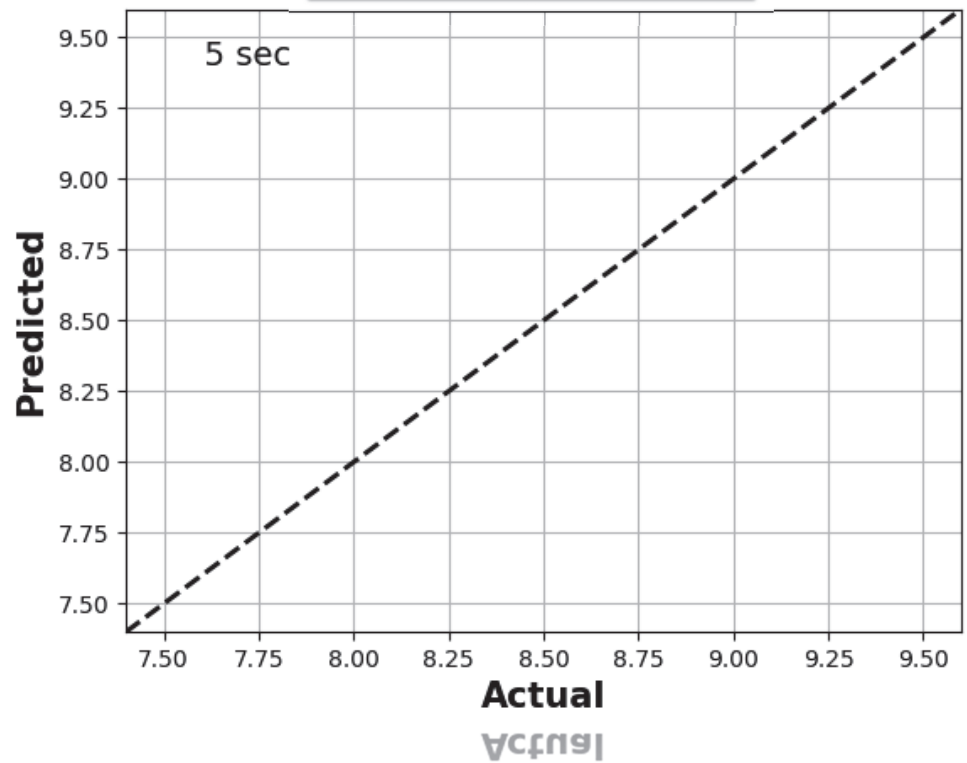
- 1) Pick rupture from available **simulations**
- 2) Add realistic GNSS **noise**
- 3) Randomly **remove stations** (set existence code)
- 4) **Repeat** steps 1-3 for 256 times to generate a minibatch
- 5) **Train** with 10,000 mini batches
 - Train with 80% validate with 20%
- 6) Labels are the **final** magnitudes of the events



256 events for a batch, total 10,000 epochs.
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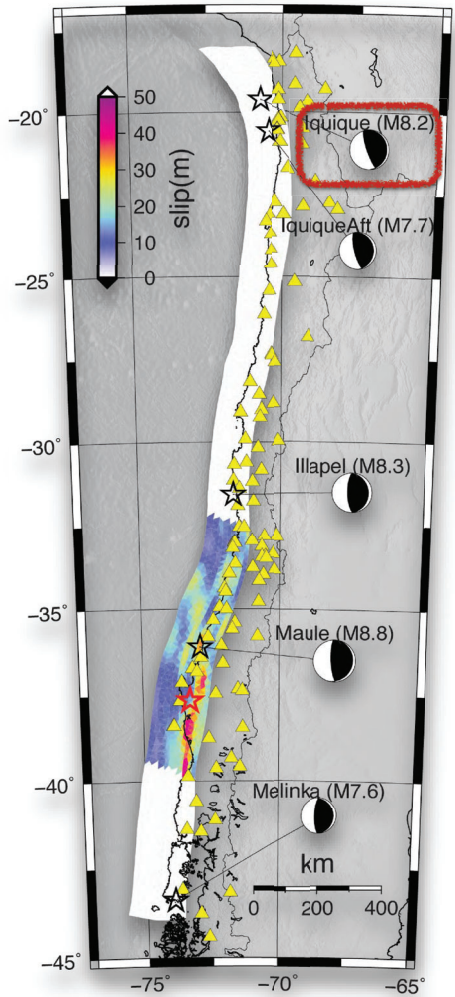
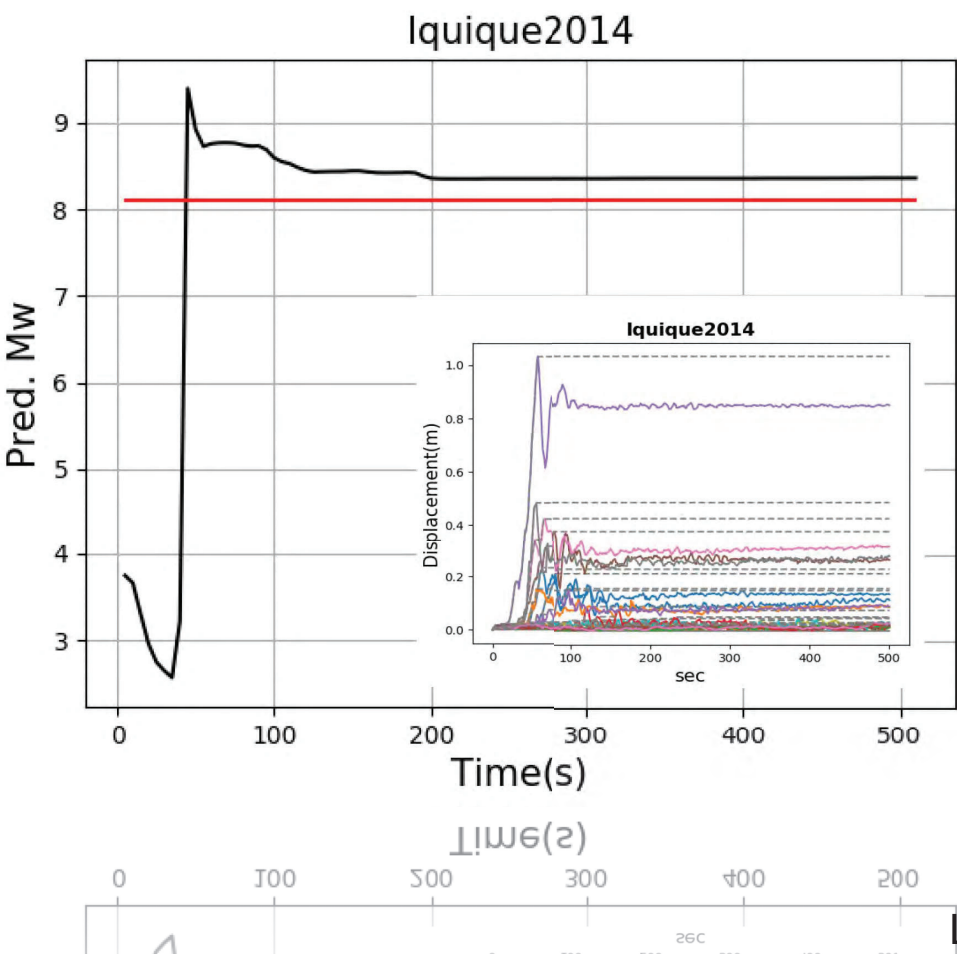
RNN Performance on Validation Data

Magnitude prediction



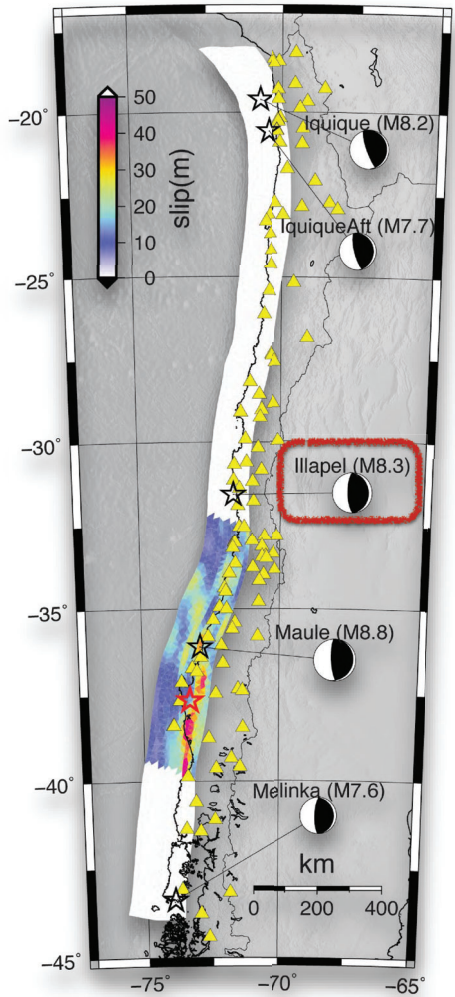
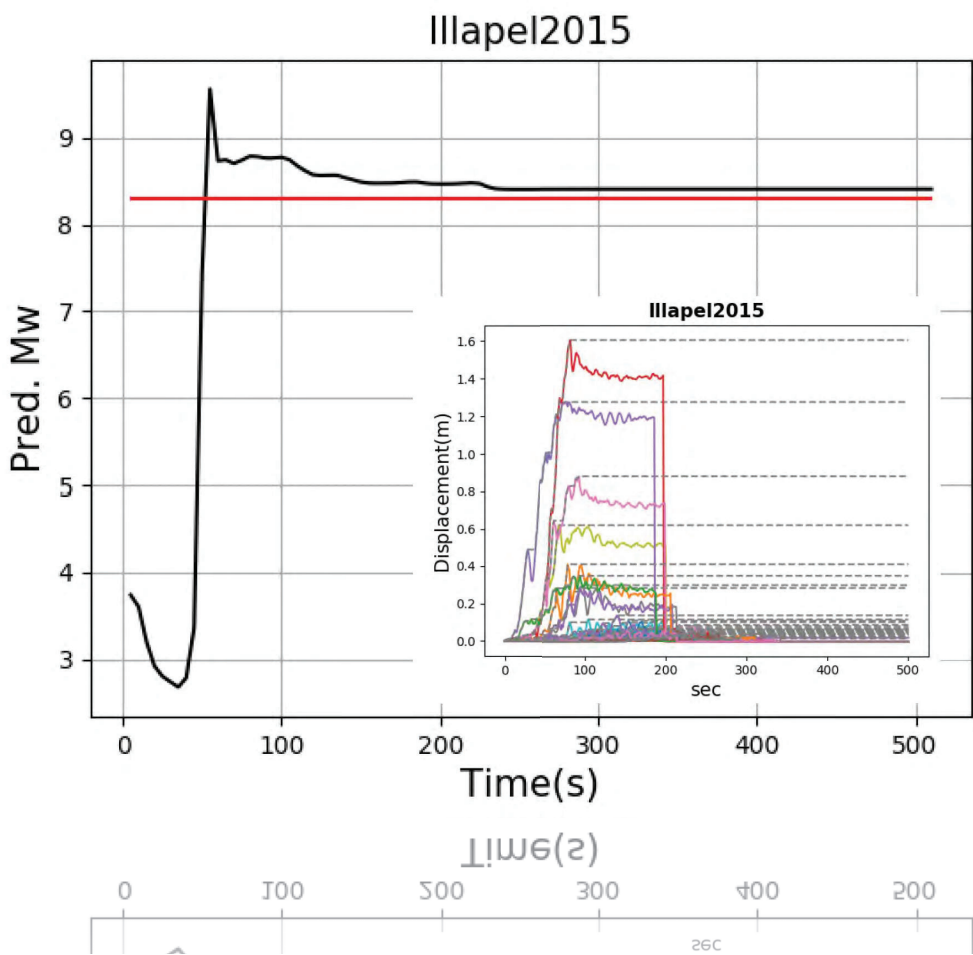
Lin et al. in prep

RNN Performance on real events



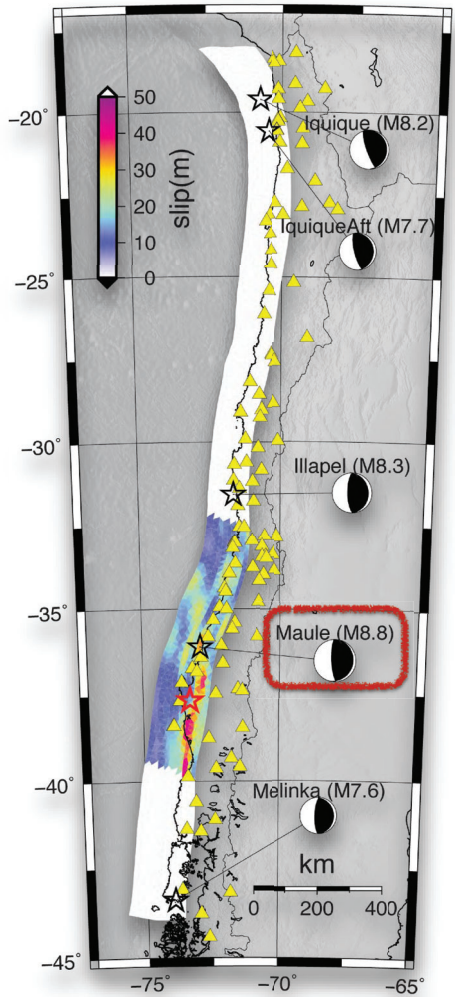
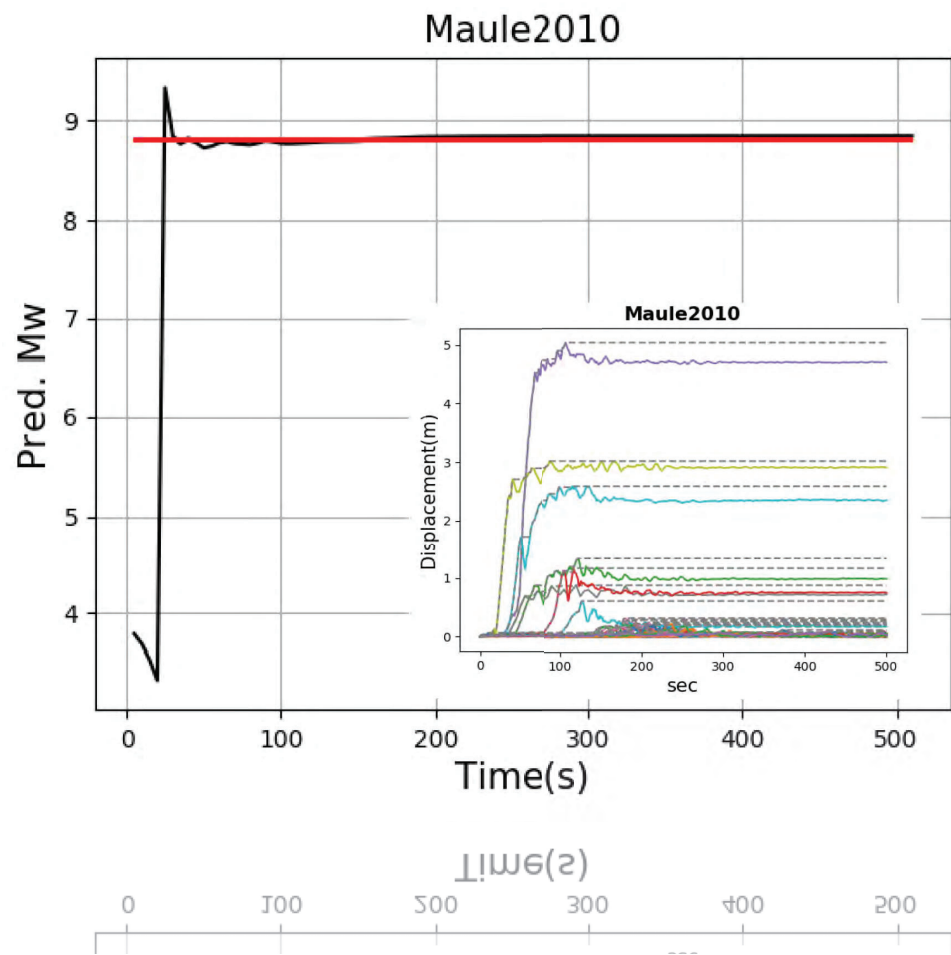
Lin et al. in prep

RNN Performance on real events



Lin et al. in prep

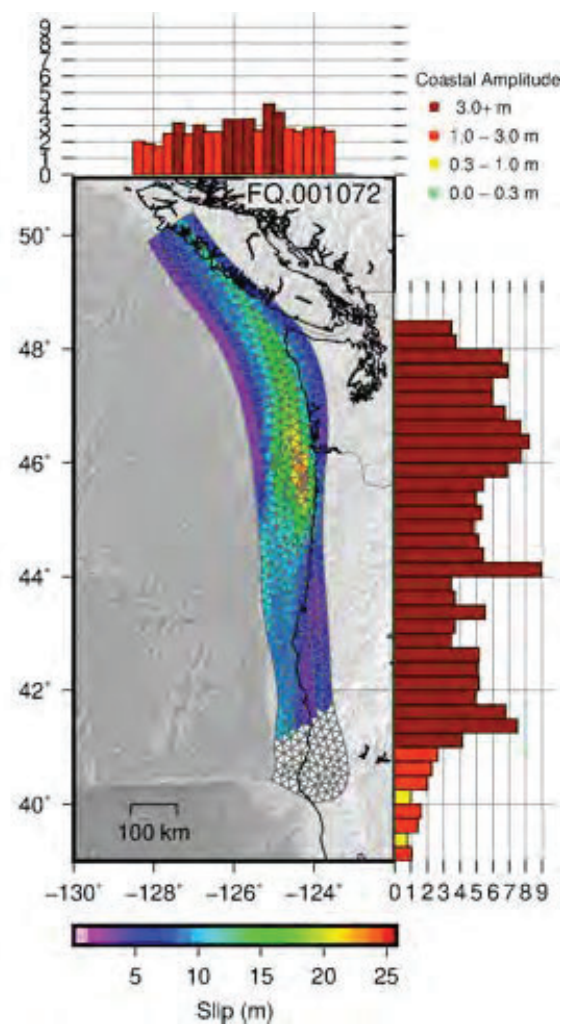
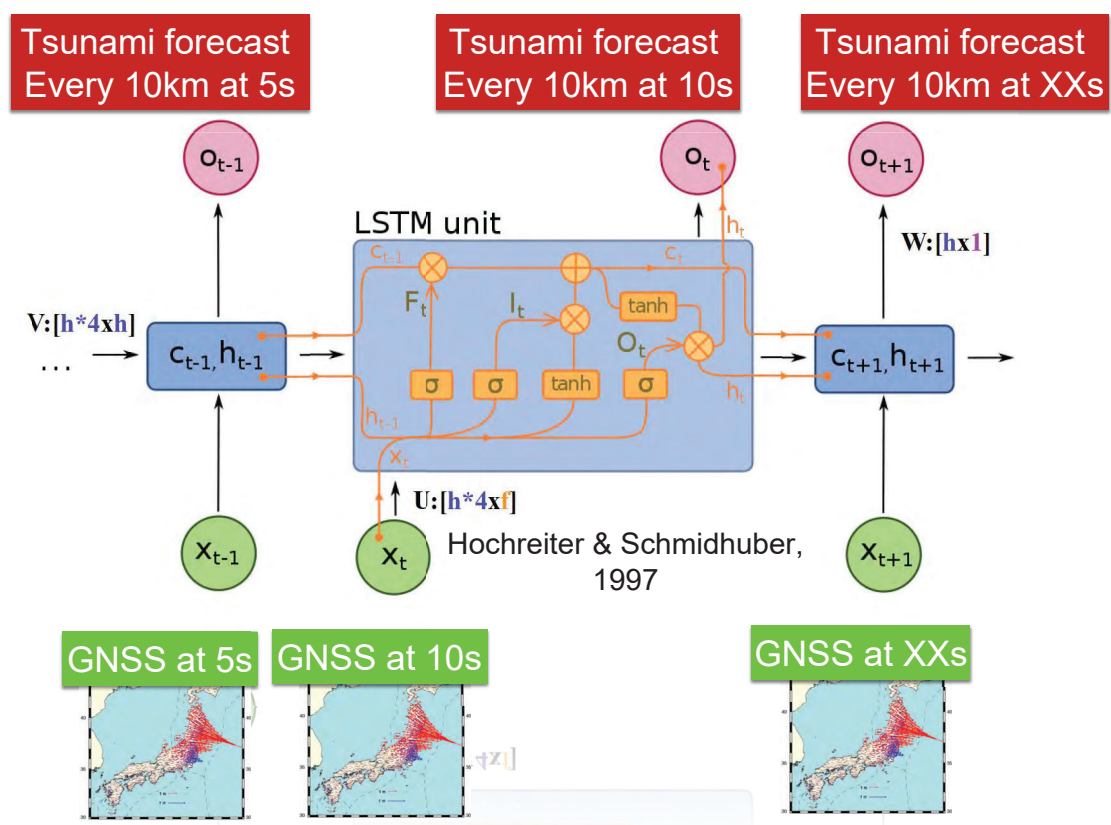
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Lin et al. in prep

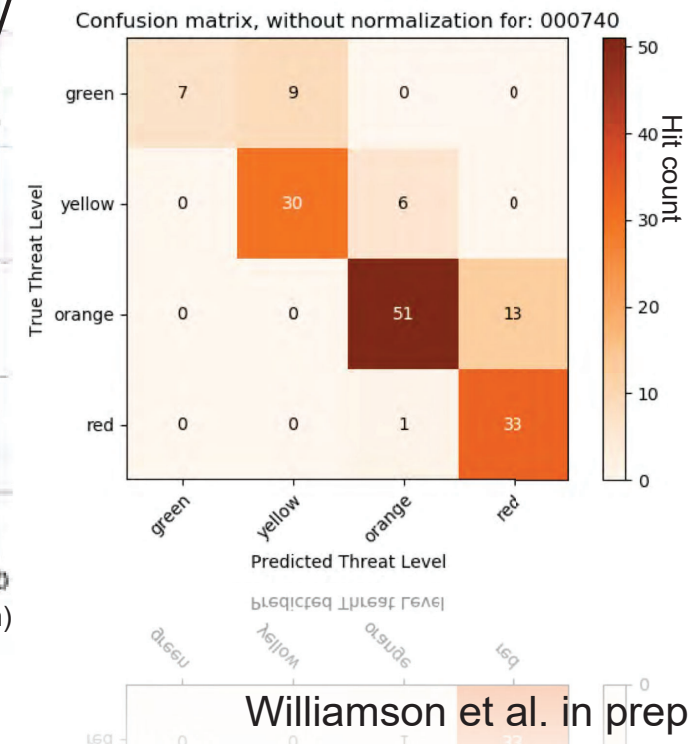
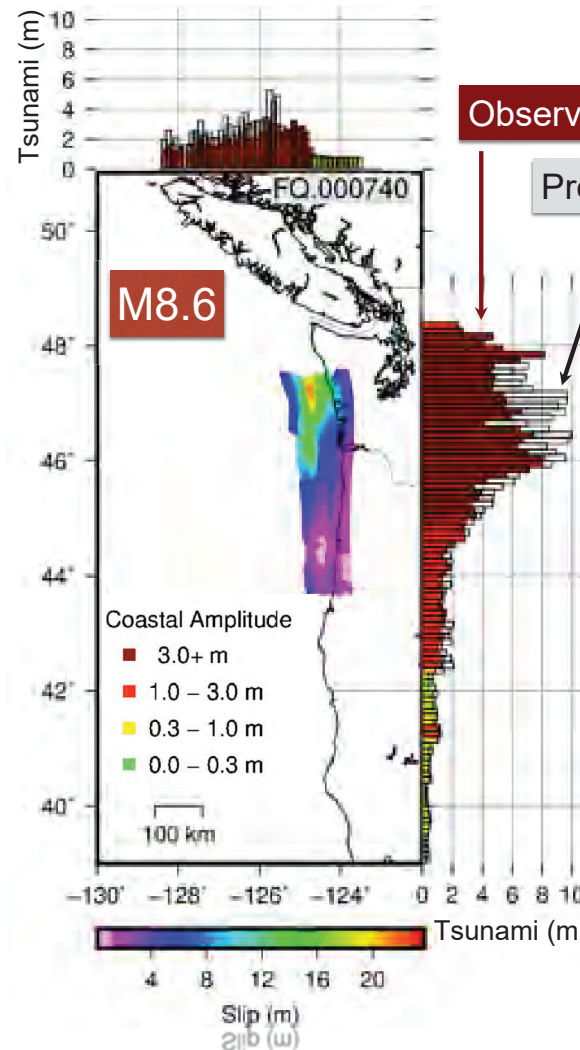
But who cares about the earthquake?

Train the RNN to **forecast the hazard**. In this context properties of the earthquake source are **unimportant**



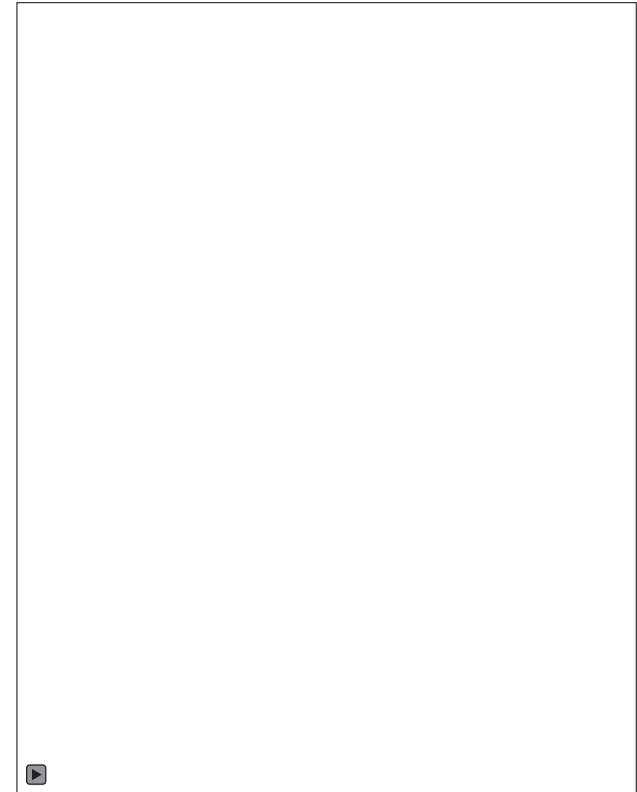
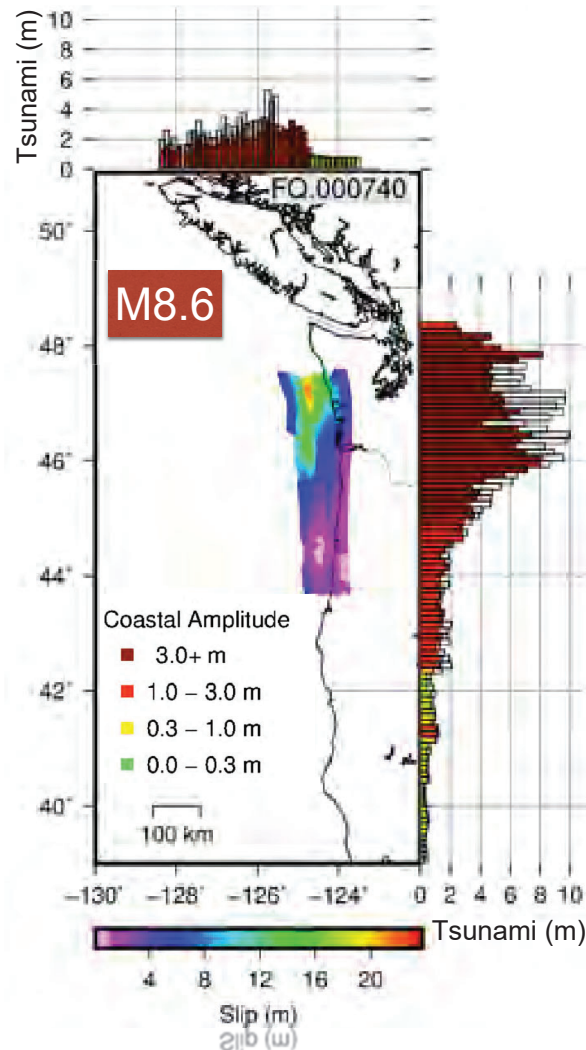
Can we forecast the tsunami? First results

- **Predict** the tsunami amplitude at the coastline
- Take the peak value over **10km** bins
- Use **threat levels** defined by NOAA (different for JMA)
- Only **tested on Cascadia** simulations, now expanding to Chile data set
- **Validation** is challenging but we have surveys/tide gauges



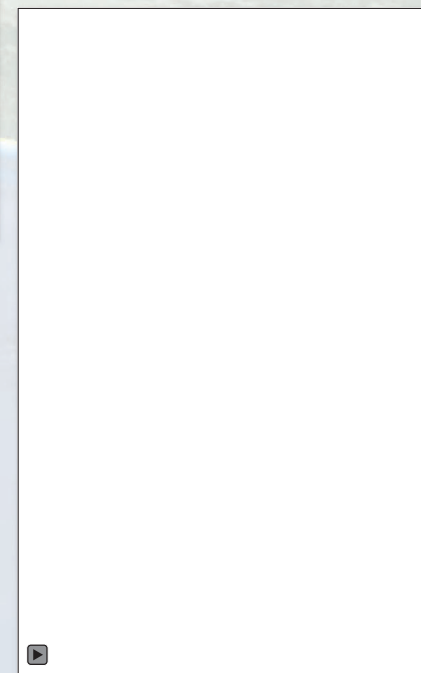
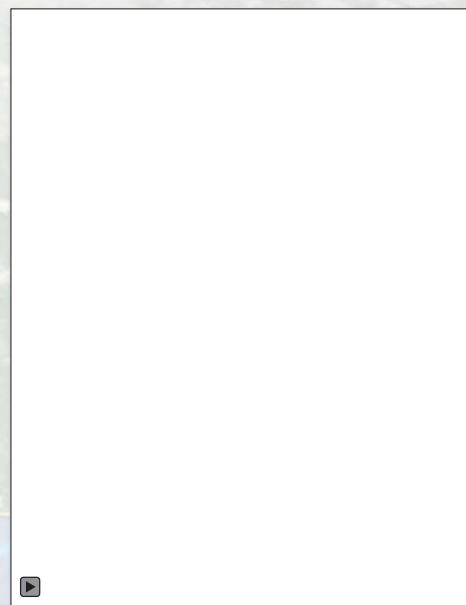
The holy grail: Inundation modeling

- The ultimate goal is to forecast **inundation** and eventually damage
- This is exceedingly difficult in a rapid response setting
- It is very sensitive to **fine scale** structure of the tsunami
- Requires more complex computations



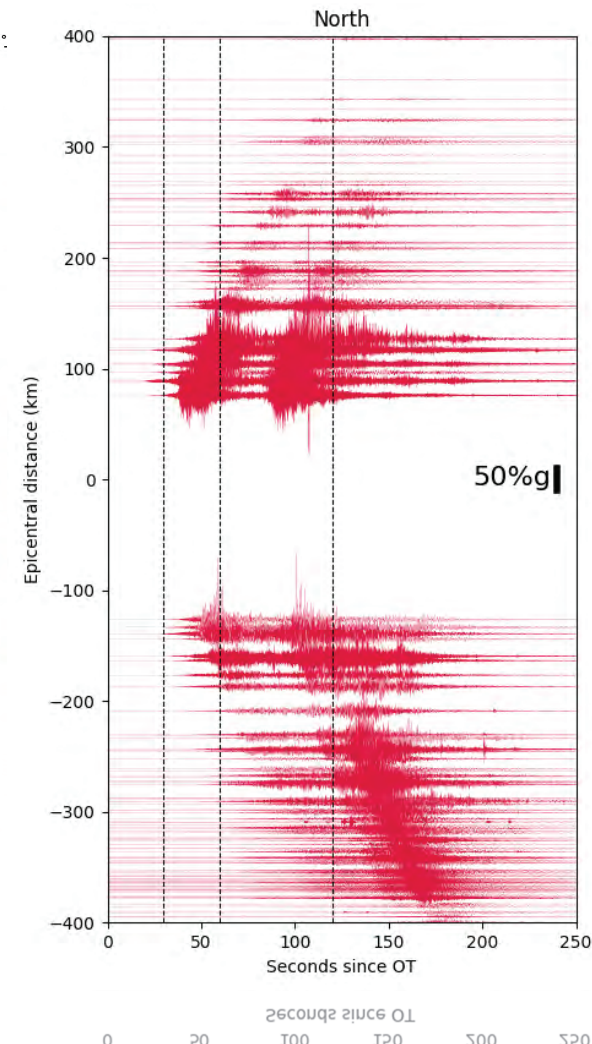
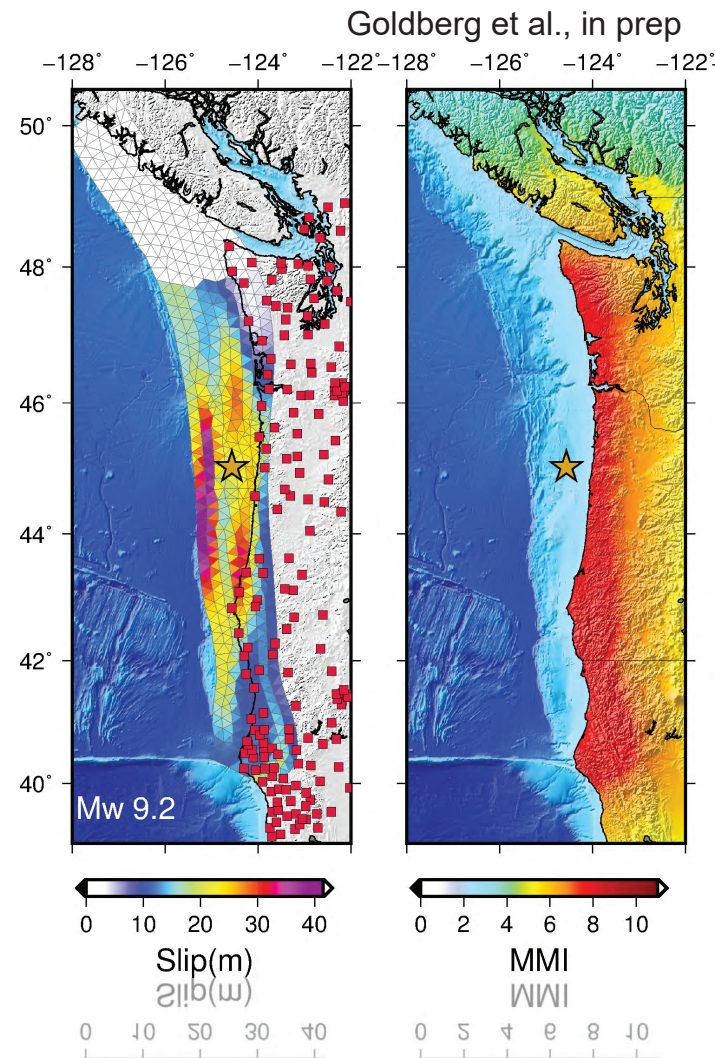
Why does this (tentatively) work?

- Because the **physics** is (fairly) well understood
- The different modeling steps are robust and validated. They **map well to reality**
- And we can efficiently run **many simulations** and adequately sample the range of possible behaviors

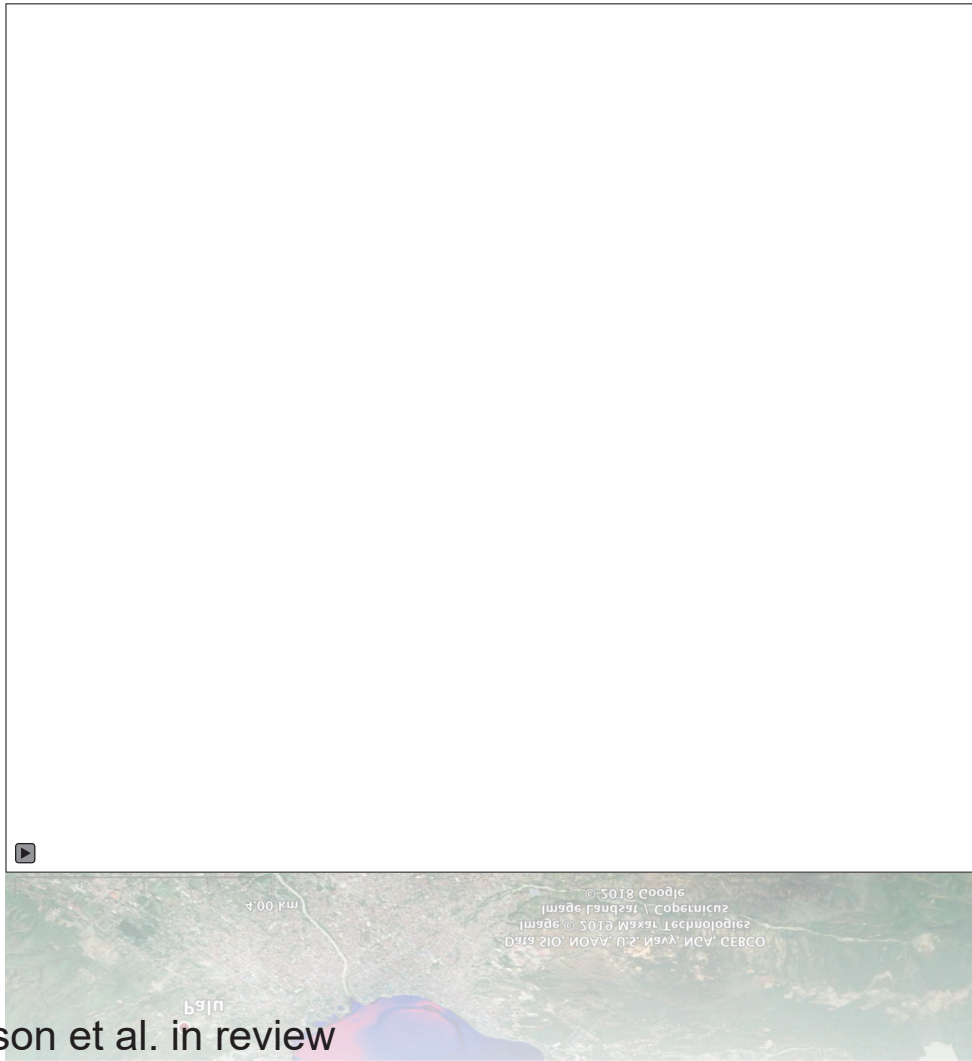
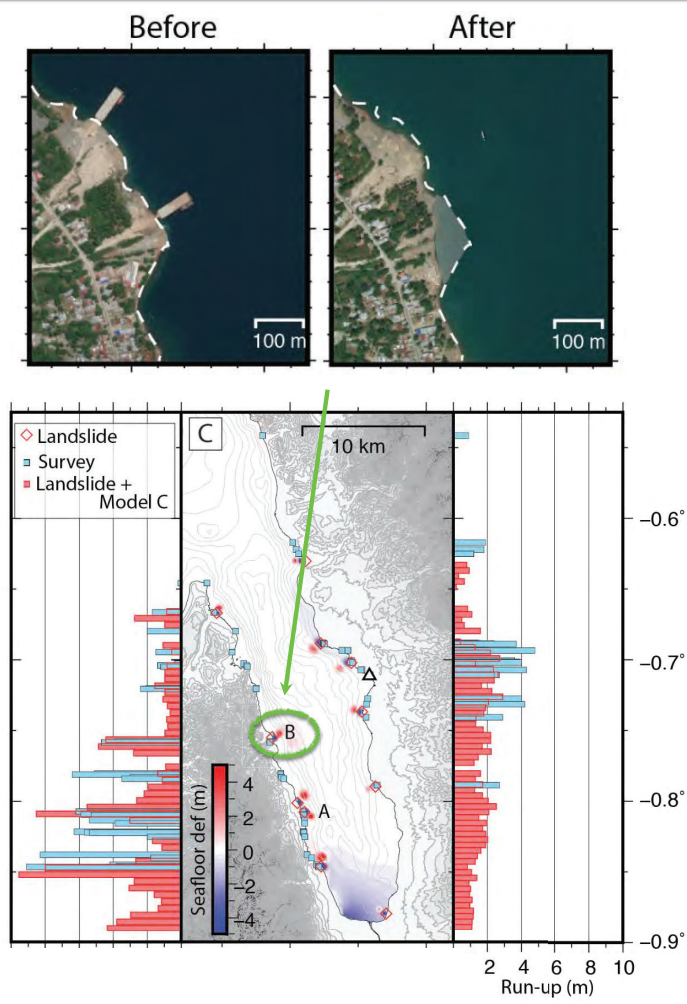


Other hazards: Towards shaking forecasts

- Combine GNSS with **seismic** data
- We can generate broadband seismograms
- It's **slower** but possible
- Details of the source and path are much more important
- Relies on **approximate** (semi-stochastic) methods
- Do we know enough about the process for this to be **meaningful**?



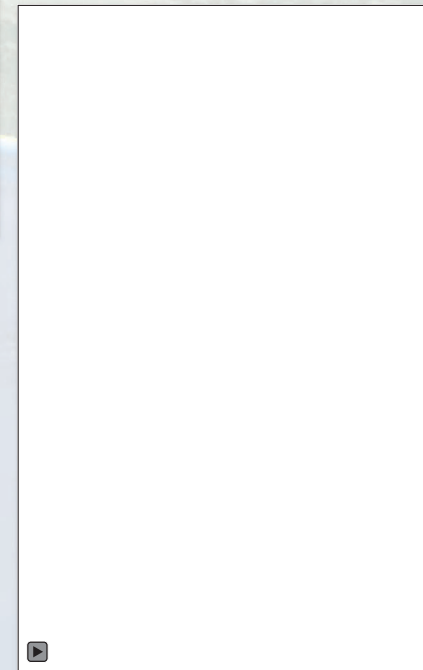
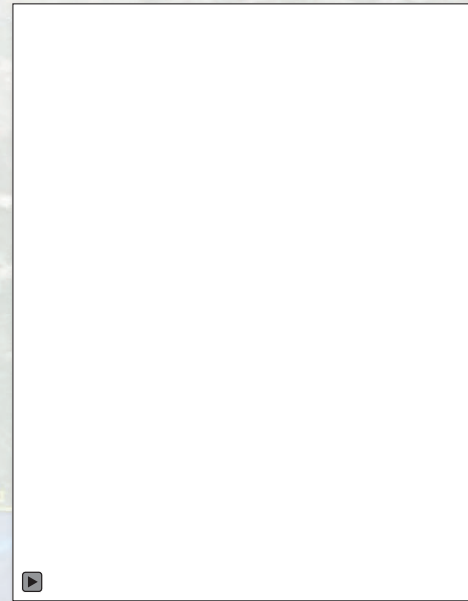
Without a physical understanding there is no forecast



Williamson et al. in review

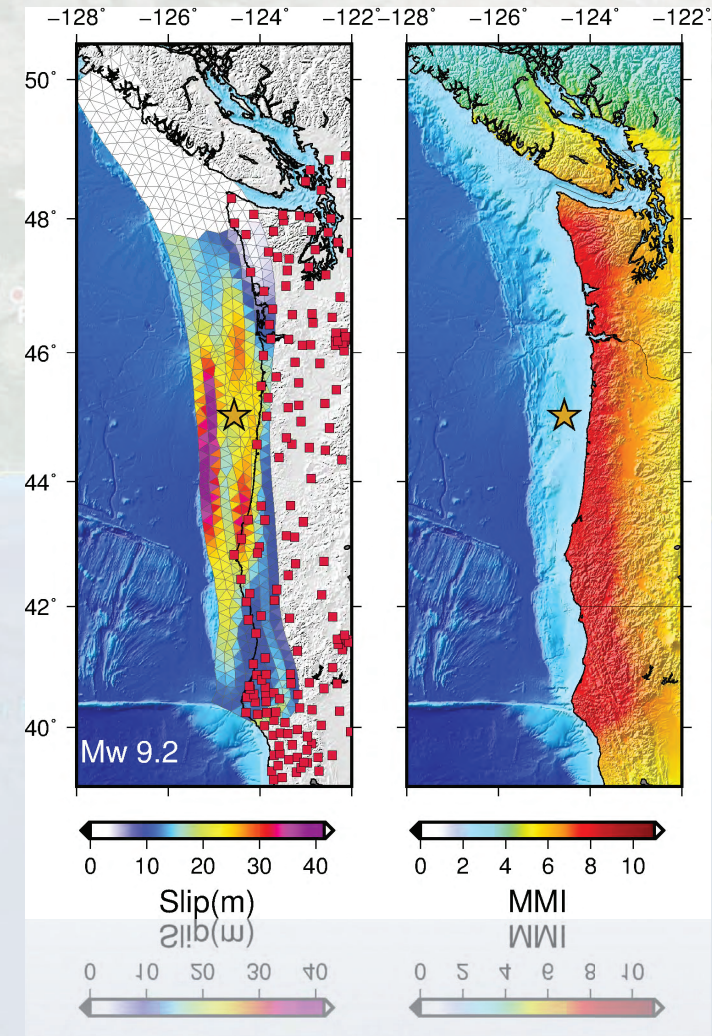
Summary

- Machine learning provides a great way to establish **complex correlations** between GNSS **observations** and earthquake **hazards**
- For tsunamis this works well because the underlying physics is well understood
- And so we can efficiently run **many simulations** and adequately sample the range of possible behaviors



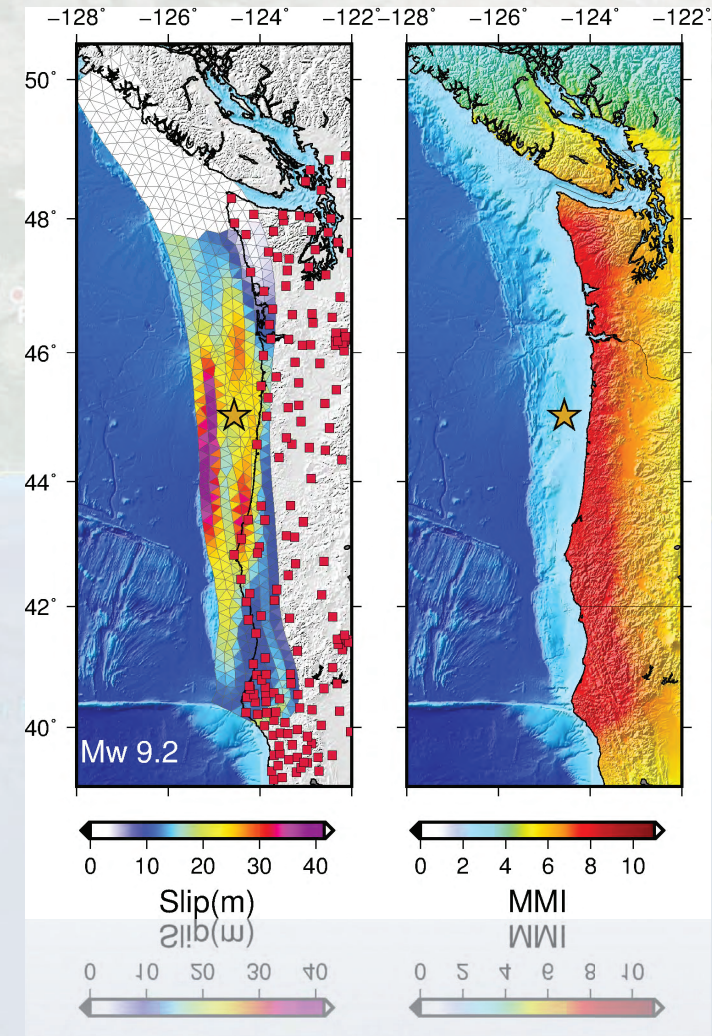
Summary

- The **physical connections** between earthquakes and other hazards are less well understood
- But as our knowledge of these improves these methods will become important
- GNSS is comparatively simple but in the future a **diversity** of geophysical data feeding algorithms will be the norm.



Challenges

- For earthquake hazards in particular:
 - How does the wedge deform?
 - Where is strong shaking generated?
 - How does shaking trigger subaerial/submarine land sliding?
- **Multiphysics** simulations that capture all the relevant phenomena
- Large events are comparatively **rare**. The simulation -> ML path requires very efficient codes. (1×10^5 simulations)
- **Capacity building**. There are still barriers to entry for massive parallel computing and machine learning methods





Thanks!

Thanks!