

**Designing optical instruments
for space applications**

Multiphysics topology optimization

Ryan Watkins

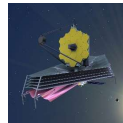
Adam Duran, Jenny Hua, Josh Ravich

November 19th, 2019

**Optical instruments are one of the most common
instruments flown by JPL and NASA**

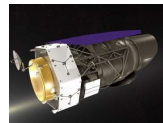
Telescopes

Ex: JWST, Hubble



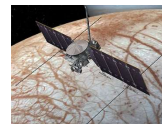
Coronagraphs

Ex: WFIRST CGI



Magnetometers

Ex: Juno, Europa Clipper

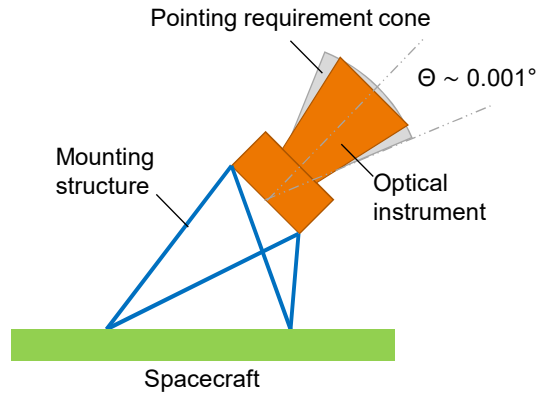


Star trackers

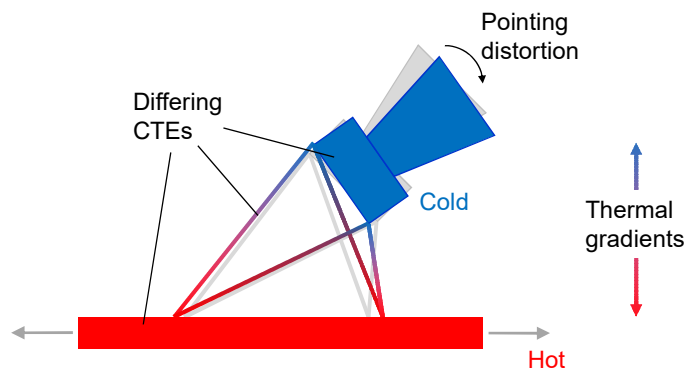
Ex: Nearly all missions



To function properly, optical instruments have tight pointing requirements



Pointing requirements are difficult to achieve due to extreme temperature conditions in space



*CTE: Coefficient of Thermal Expansion

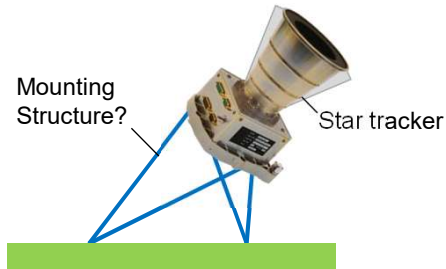
Came across a star tracker system that is struggling to meet tight pointing requirements

Can Topology Optimization (TO) design this bracket?

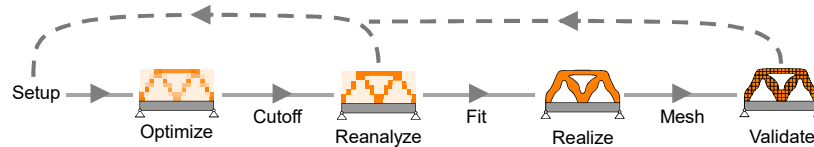
Pointing requirement as a constraint in TO

Can the structure be additively manufactured?

Manufacture complex design quickly and at low cost

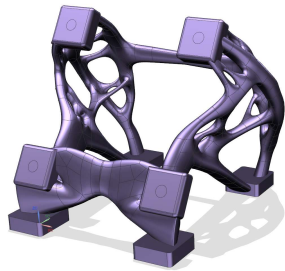


For this coupled thermoelastic problem,
SIMP-based TO struggles to produce a *realized* design
that meets *all* design requirements



Designing optical instruments for space applications

Multiphysics topology optimization



TO in the context of JPL

Institutional relevance

Design problem

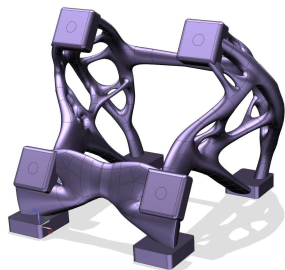
Requirements/formulation

Intricacies of TO

Solving a real world problem

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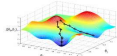
A little bit about me...



From upstate NY
Saratoga Springs – horse racing town



PhD in experimental and theoretical mechanics
Studied shape memory alloys at the University of Michigan



Doing optimization for about a decade
Roommate from college is a mathematician in the field

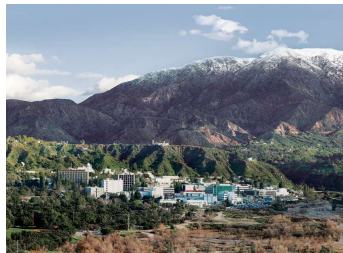


At JPL for 4 years
Worked as a structural analyst and hardware engineer

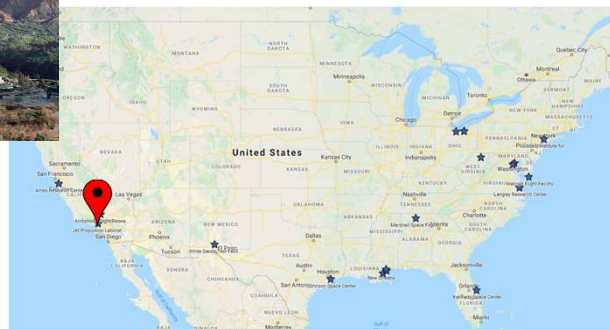


Spearheading use of topology optimization at JPL
Working on this topic since arriving at JPL

JPL is a NASA-based Federally Funded Research and Development Center (FFRDC)



Approximately 6,000 employees
Engineers, scientists, manufacturing, ...



JPL specializes in robotic space and Earth science missions

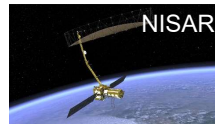
Interplanetary



Mars rovers



Earth science



TO is well suited for the design problems commonly faced at JPL

Interplanetary missions are highly driven by mass

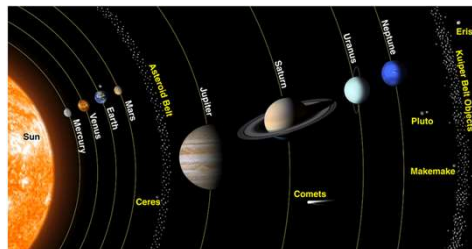
Ex: ~40 kg propellant needed to get 1 kg to Jupiter

Each spacecraft is uniquely designed

Continually solving new problems

Low manufacturing quantity

Viable to make high complexity parts



JPL has been actively attempting to infuse TO into flight projects for four years

Primarily use OptiStruct (Inspire and HyperMesh)
Based on software comparison and benchmark testing

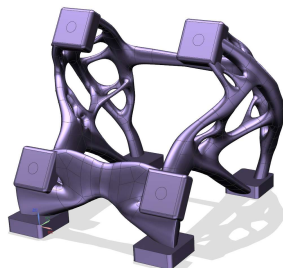
Recently completed Project Gamma development
Collaboration with Autodesk to design a lander concept

Investigating noncommercial code for “hard” problems
Government (Sandia’s Plato) and university collaboration



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Institutional relevance

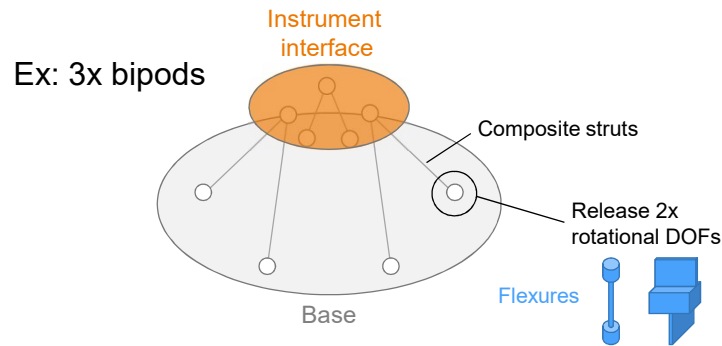
Design problem
Requirements/formulation

Intricacies of TO
Solving a real world problem

Optical mounts are typically made of low CTE materials that perfectly constrain the instrument



Perfect constraint → No elastic strain
Low CTE materials → Minimize gradient effects



Why use TO when a methodology already exists for this design problem?

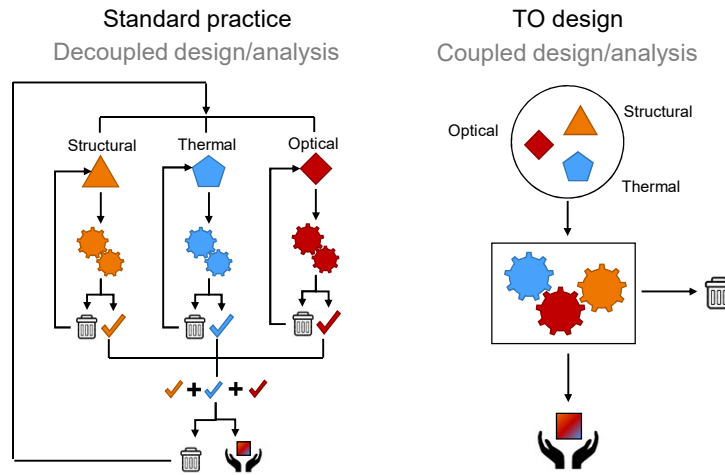
Flexures only simulate desired DOF release
Only minimize over constraint

Flexures require precision machining
Tend to be fatigue sensitive

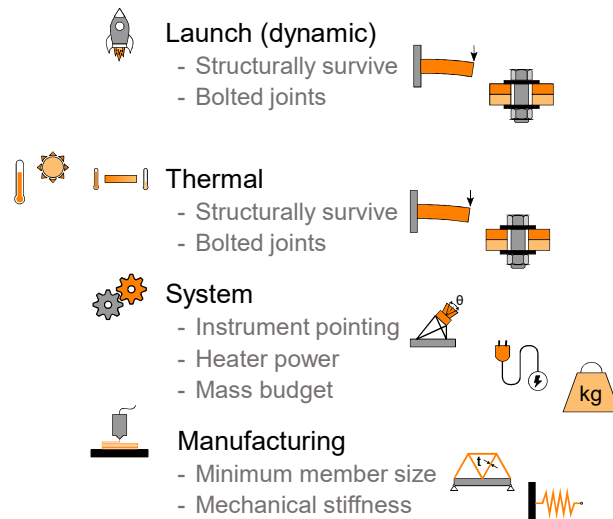
Composites are high cost and long lead time
Require bonding and additional analysis/testing

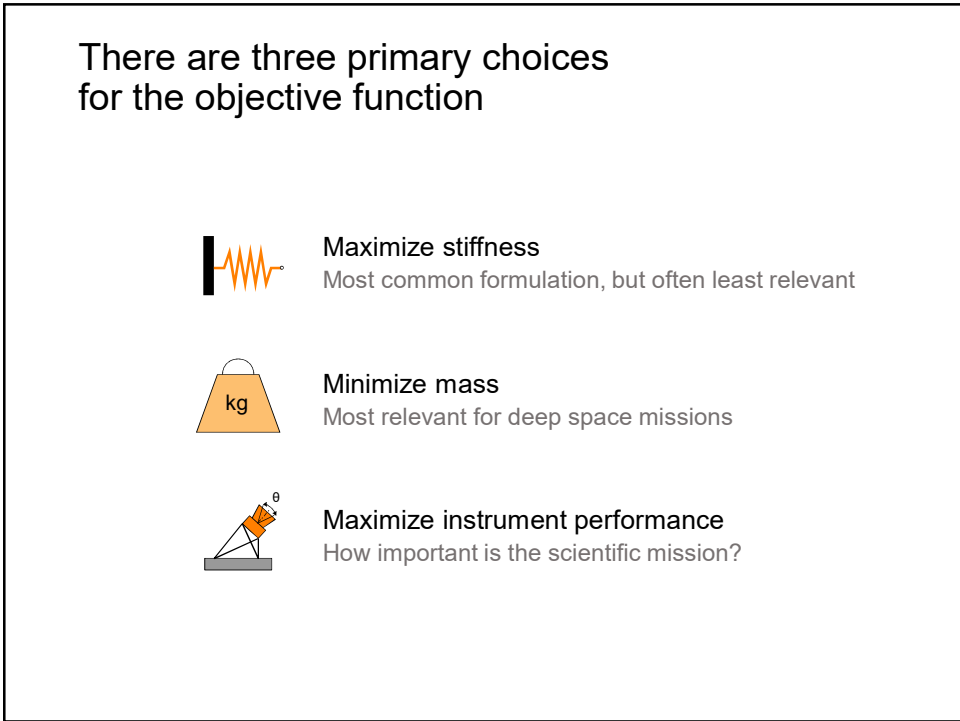
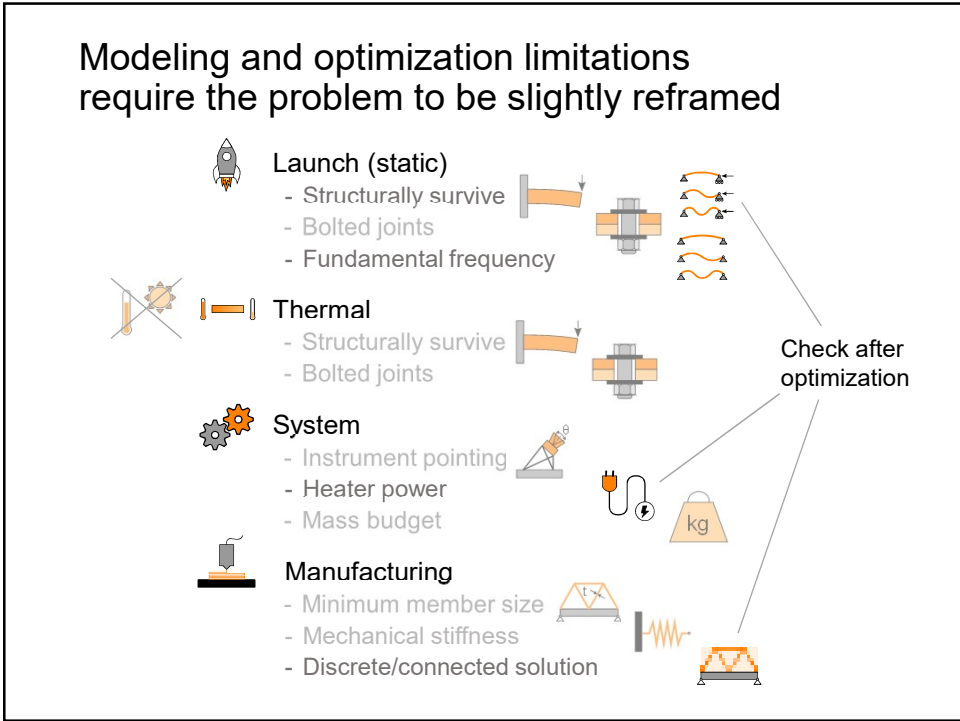
May not be possible to achieve kinematic mount
Predefined interfaces, limited space, etc.

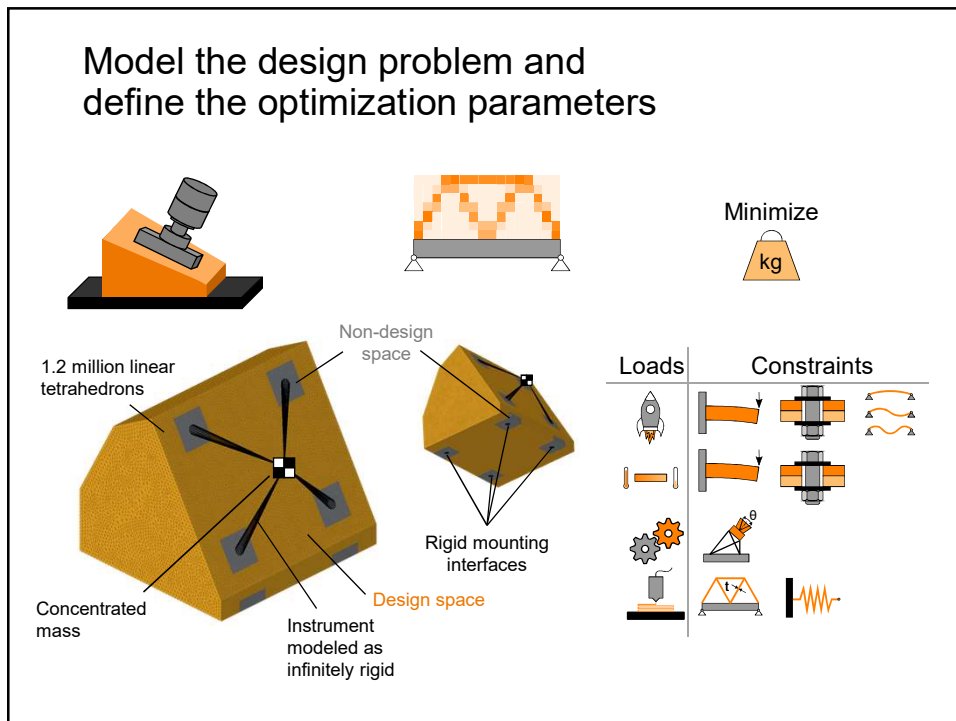
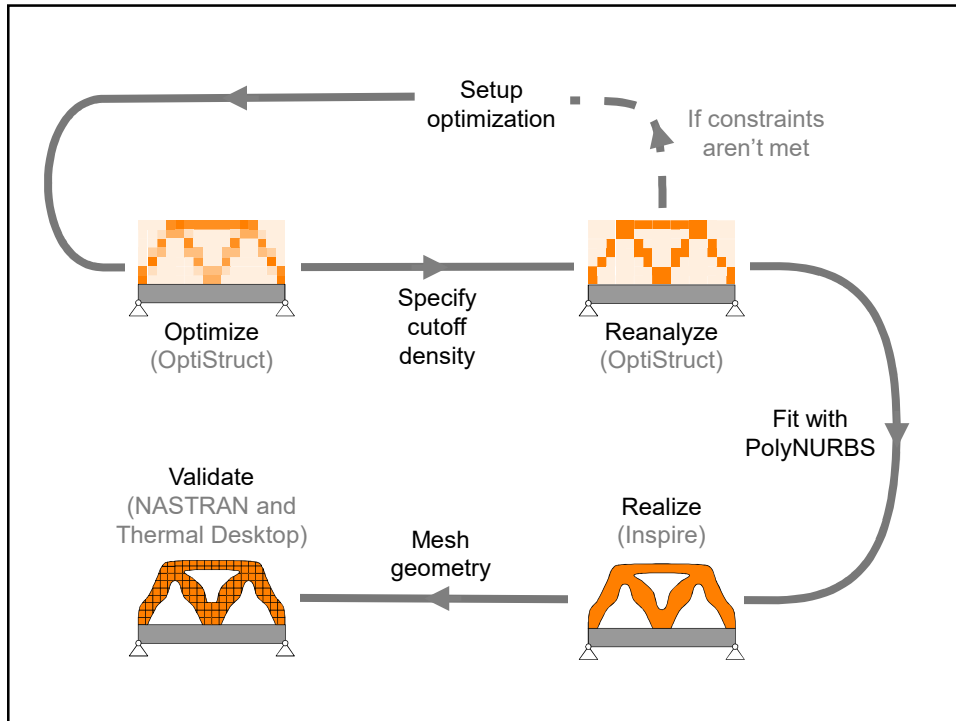
Why use TO when a methodology already exists for this design problem?



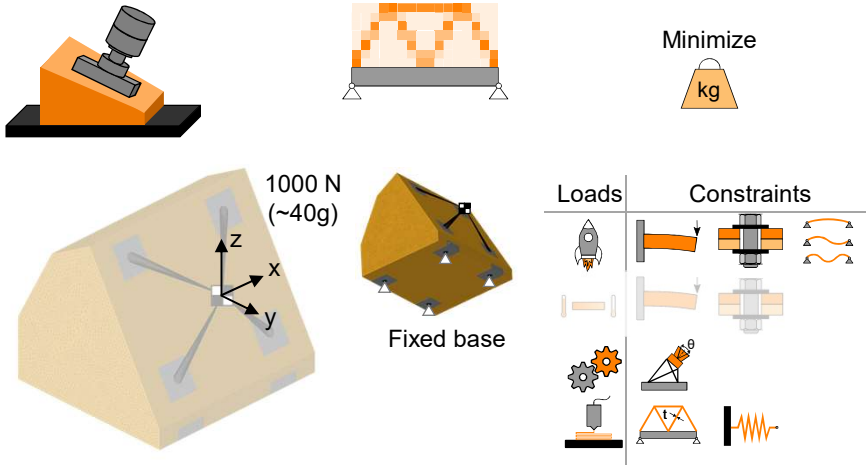
Instrument design is governed by launch, thermal, system, and manufacturing requirements















Impose three launch cases:
 static load in three orthogonal directions



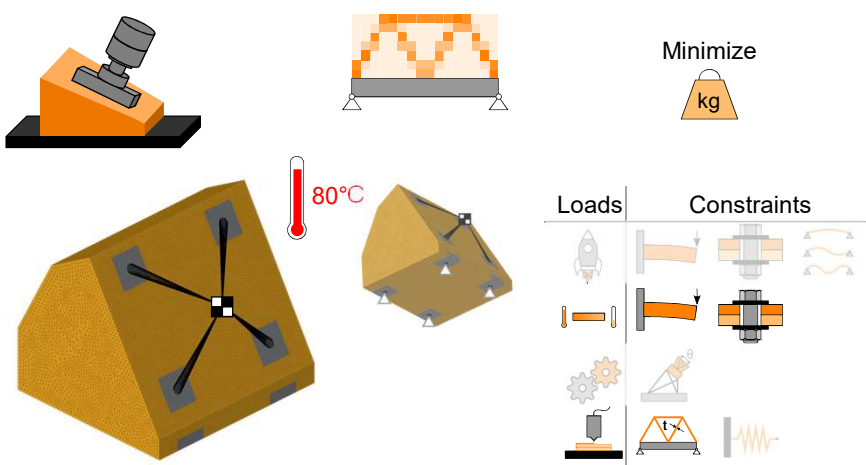
1000 N (~40g)

Fixed base

Minimize kg

Loads	Constraints
	
	
	
	









Impose a worst-case thermal load case:
 Bulk steady state (SS) thermal soak

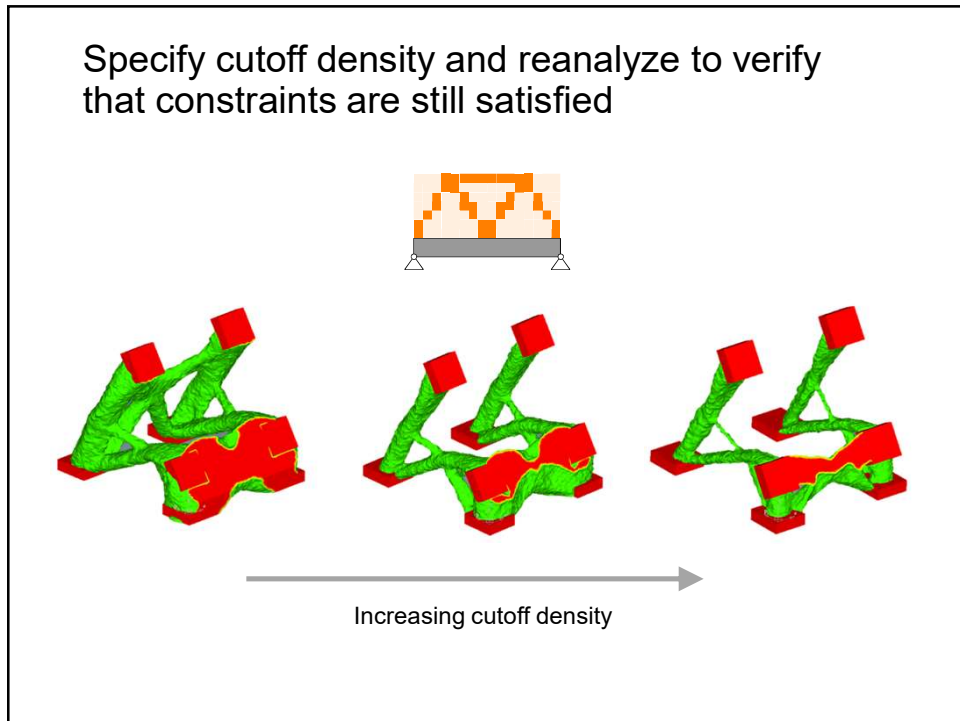
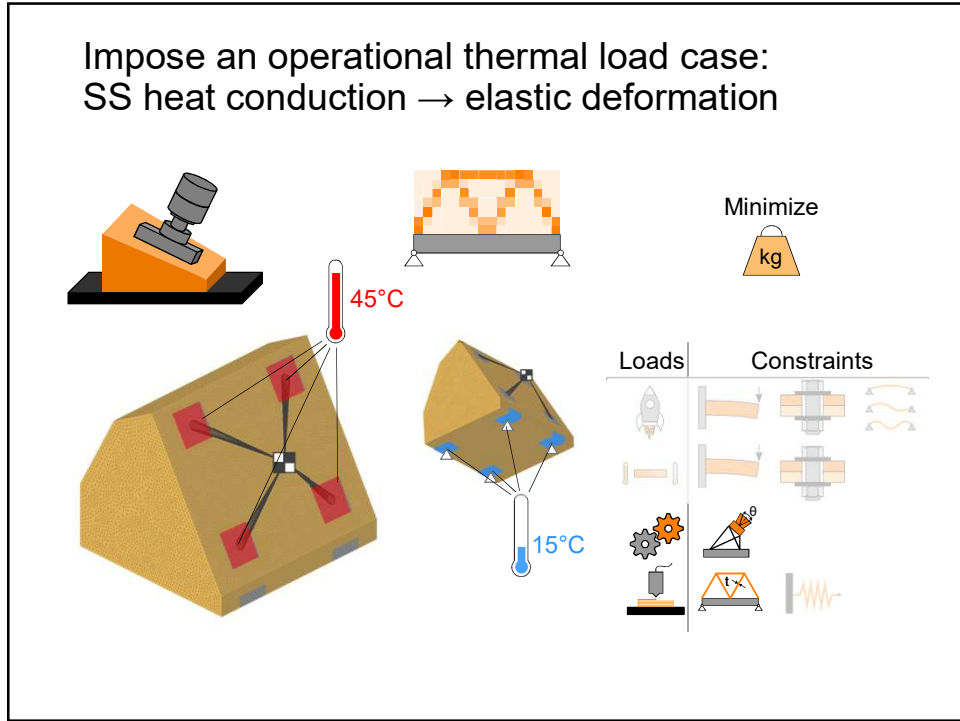


80°C

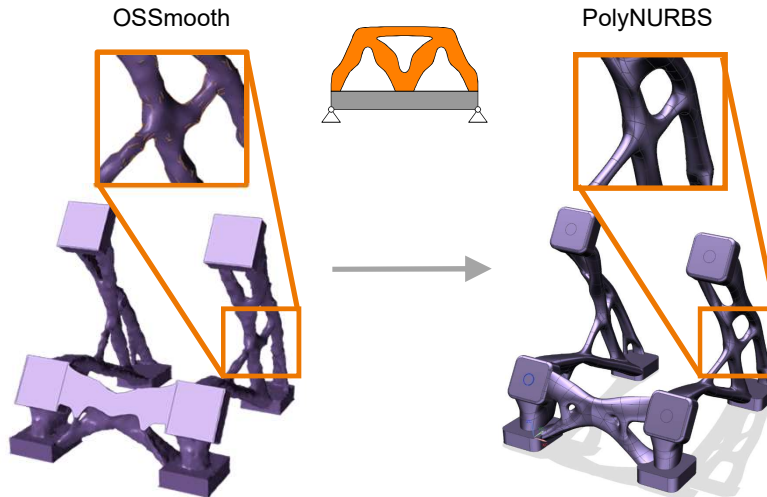
Fixed base

Minimize kg

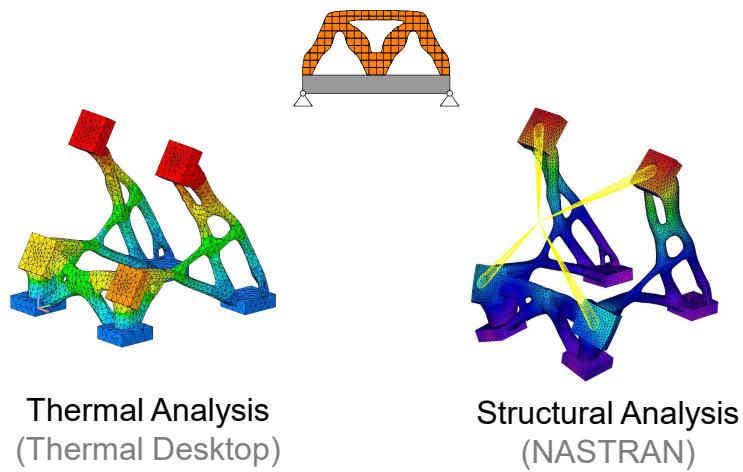
Loads	Constraints
	
	
	
	



Export geometry with OSSmooth
and fit with PolyNURB surfaces in Inspire

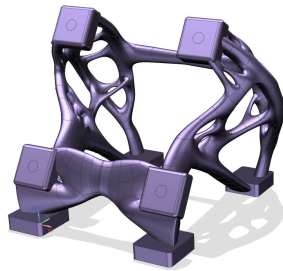


Validate realized design using
standard JPL flight analysis practices



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TO in the context of JPL
 Institutional relevance

Design problem
 Requirements/formulation

Intricacies of TO
 Solving a real world problem

In general, the penalty *continuation method* did not produce discrete/connected results

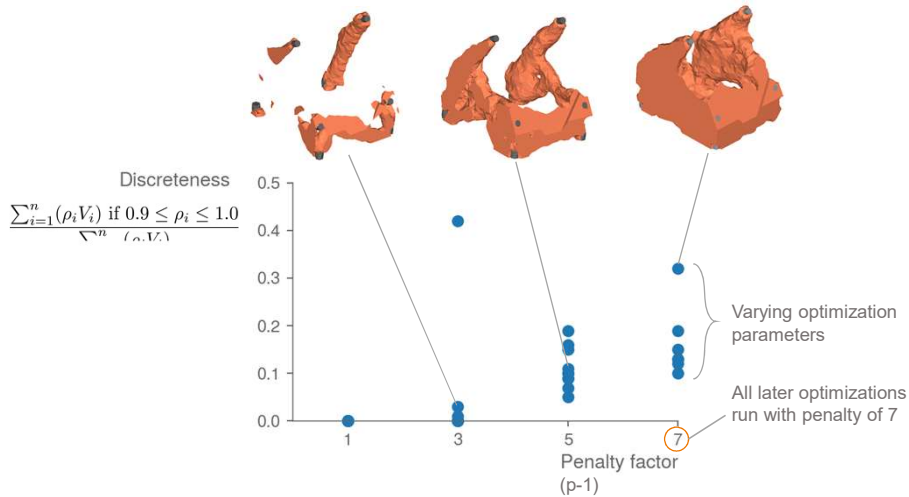
$$E^* = \rho^{p+1} E$$

Density range	Step 1 p = 1	Step 2 p = 2	Step 3 p = 3
0.0-0.1	 9.1 %	 9.1 %	 9.1 %
0.1-0.2	 90.8 %	 90.8 %	 90.8 %
0.2-0.3	 0.0 %	 0.0 %	 0.0 %
0.3-0.4	 0.0 %	 0.0 %	 0.0 %
0.4-0.5	 0.0 %	 0.0 %	 0.0 %
0.5-0.6	 0.0 %	 0.0 %	 0.0 %
0.6-0.7	 0.0 %	 0.0 %	 0.0 %
0.7-0.8	 0.0 %	 0.0 %	 0.0 %
0.8-0.9	 0.0 %	 0.0 %	 0.0 %
0.9-1.0	 0.0 %	 0.0 %	 0.0 %

*Note: results questionable due to limited knowledge of solver formulation

*Note: results are for a slightly different optimization formulation

A penalty factor of 7 consistently resulted in discrete and connected solutions



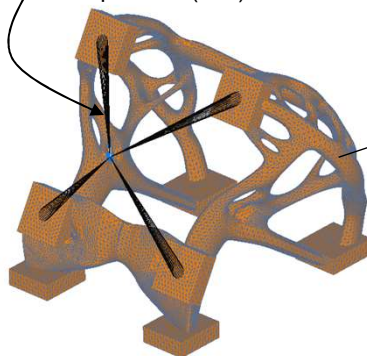
*Note: results are for a slightly different optimization formulation

It can be challenging to bound interface uncertainties in multiphysics optimizations

Instrument provided by foreign partner
 Unknown stiffness properties



Requirement:	6.00 arcsec
Infinitely rigid:	6.26 arcsec
Interpolation (soft):	5.23 arcsec



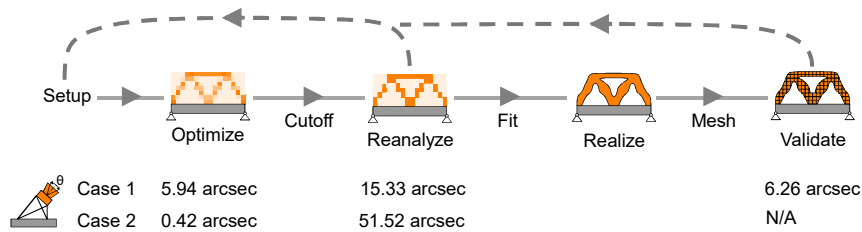
Design generated assuming infinitely rigid instrument

A successful optimization run does not necessarily result in a “real” viable design

“Gray” solutions behave different than real structures
 Optimizer is fundamentally solving a different problem

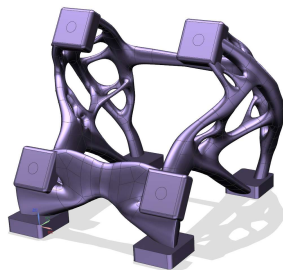
Realizing a design is user dependent
 Defining cutoff density and smoothing the results

Multiphysics problem is non-intuitive
 This is less of an issue for purely structural problems



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Ultimately, TO was able to come up with a design that nearly met requirements

Optimized a multiphysics design problem
Thermal and mechanical load cases

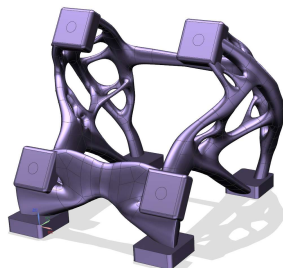
SIMP struggled to generate a fully compliant design
Issues realizing a design from density formulation

Driving requirement was instrument pointing
Current design violates requirement by 5%

Complete free shape optimization in future work
Hone TO solution to be compliant with requirements

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