

**A lunar water reconnaissance mission**

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# VIPER

The past decade of observations have built a fascinating and complicated story about lunar water

- From “frosts” to buried ice blocks, there appears to be water everywhere, but its nature and distribution is very uncertain

The next steps in exploration require surface assets, including surface mobility

VIPER will conduct exploration science, modeled after terrestrial resource exploration processes and techniques

Passed Mission Critical Design Review (October 19-20, 2021)

VIPER new Science Co-I proposals in review (50 proposals received)


Launch November 2023

<https://www.nasa.gov/viper>







# Artemis: Landing Humans On the Moon




Lunar Reconnaissance Orbiter: Continued surface and landing site investigation






Artemis I: First human spacecraft to the Moon in the 21st century




Artemis II: First humans to orbit the Moon and rendezvous in deep space in the 21st Century



Gateway begins science operations with launch of Power and Propulsion Element and Habitation and Logistics Outpost



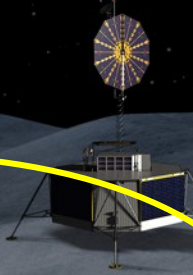
Artemis III-V: Deep space crew missions; cislunar buildup and initial crew demonstration landing with Human Landing System




Early South Pole Robotic Landings  
Science and technology payloads delivered by Commercial Lunar Payload Services providers



Volatiles Investigating Polar Exploration Rover  
First mobility-enhanced lunar volatiles survey



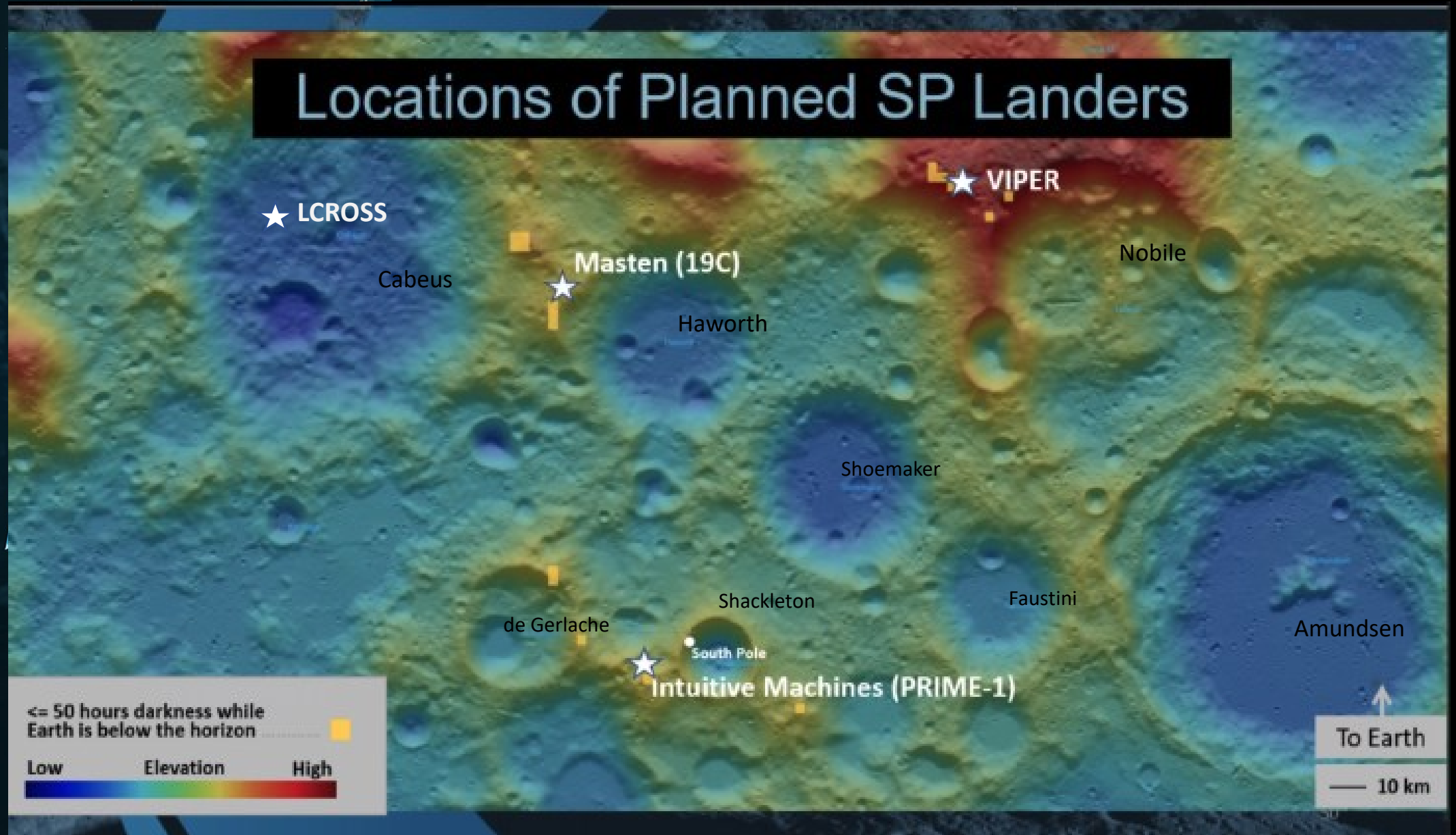
Uncrewed HLS Demonstration



Humans on the Moon - 21st Century  
First crew expedition to the lunar surface

**LUNAR SOUTH POLE TARGET SITE**

# Lunar South Pole Missions (plan)





# Understanding Lunar Water

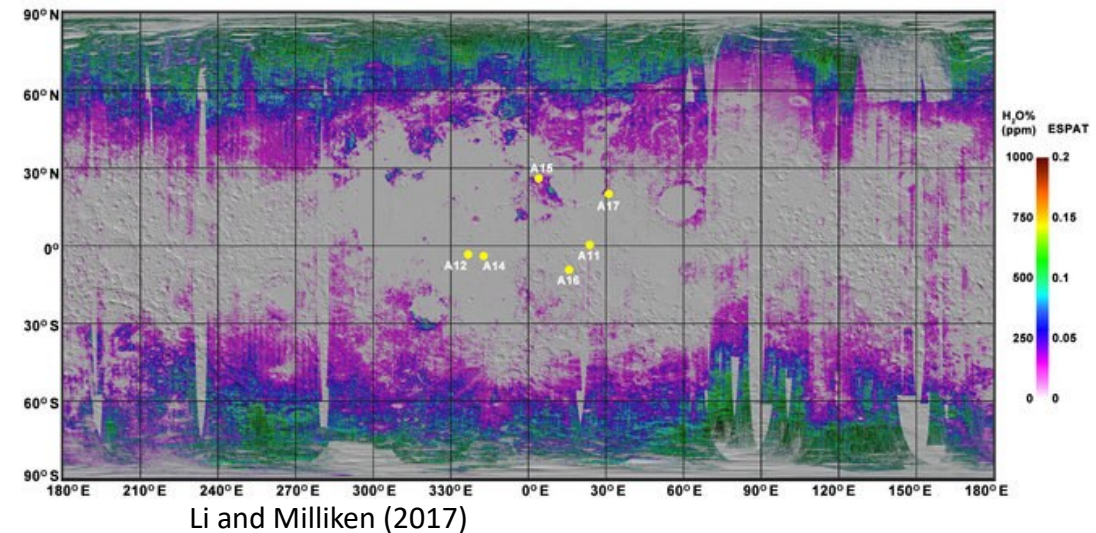
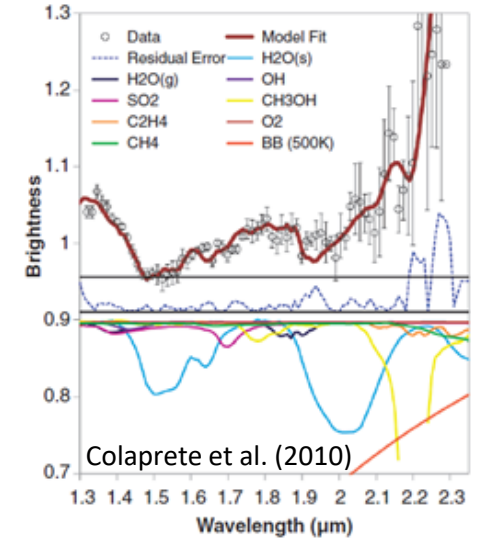
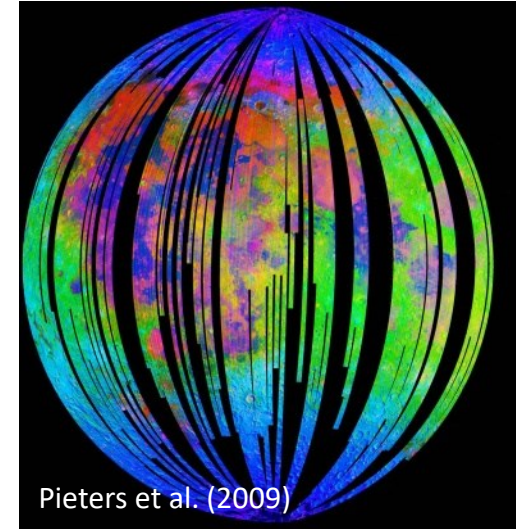
***Moon now known to host all three forms of Solar System water: endogenic, sequestered external and in-situ\****

- Do not yet understand the concentration, evolution and interrelated dynamics of these varied sources of water

***Understanding the distribution, both laterally and with depth, addresses key **exploration and science** questions***

- Surface measurements across critical scales are necessary to characterize the spatial distribution and state of the water

***“Prospecting” for lunar water at poles is the next step in understanding the resource potential and addressing key theories about water emplacement and retention***

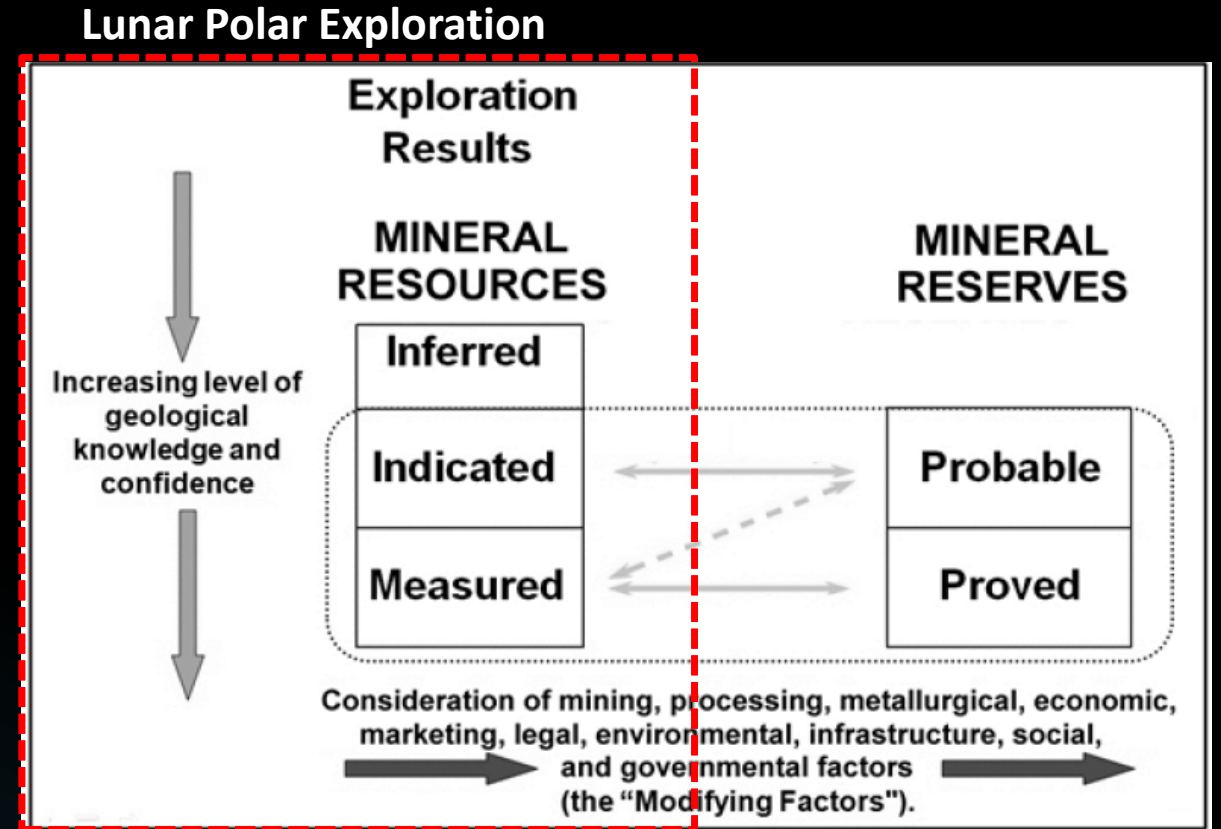


\*From Peters et al. Transformative Lunar Science (2018)

# Lunar Polar Volatile Exploration: Science and Exploration

## Critical Observations Needed

- Volatile **Distribution** (concentration, including lateral and vertical extent and variability)
- Volatile **Physical State** ( $H_2$ , OH,  $H_2O$ ,  $CO_2$ , Ice vs bound, etc).
- The **Context and Correlation**, including:
  - Accessibility/Overburden: How much and type of material needing to be removed to get to ore?
  - Environment: Sun/Shadow fraction, soil mechanics, trafficability, temperatures
  - Distribution and Form vs Environment
  - Extrapolates small scale distributions to global data sets, critical for developing “mineral/resource models”



From "Committee for Mineral Reserves and International Reporting Standards, 2013"

**Distribution. Physical State. Context. Correlation.**

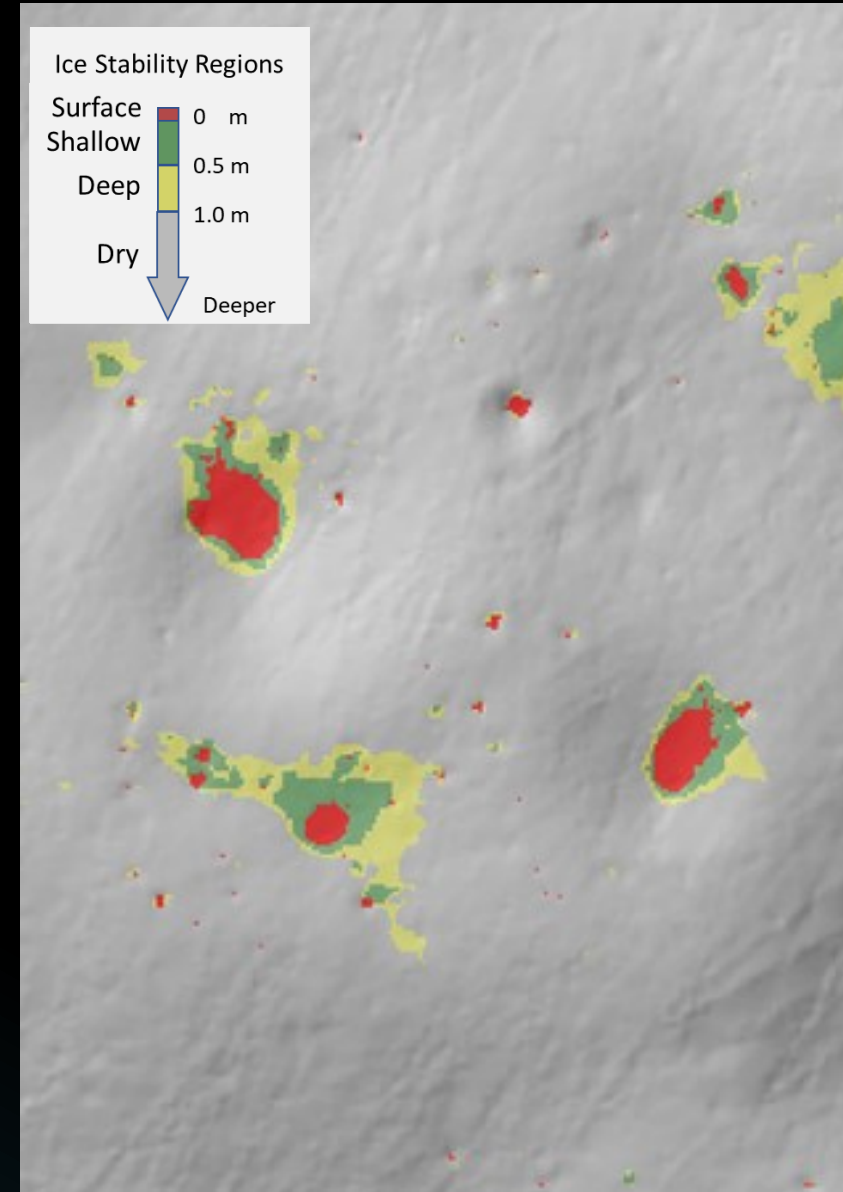
# VIPER Measurements

Rather than “find” the water VIPER methodically characterizes the range of thermal environments and geologic settings to build correlations between volatiles and environments

VIPER will explore four polar “Ice Stability Regions” (ISRs)\*:

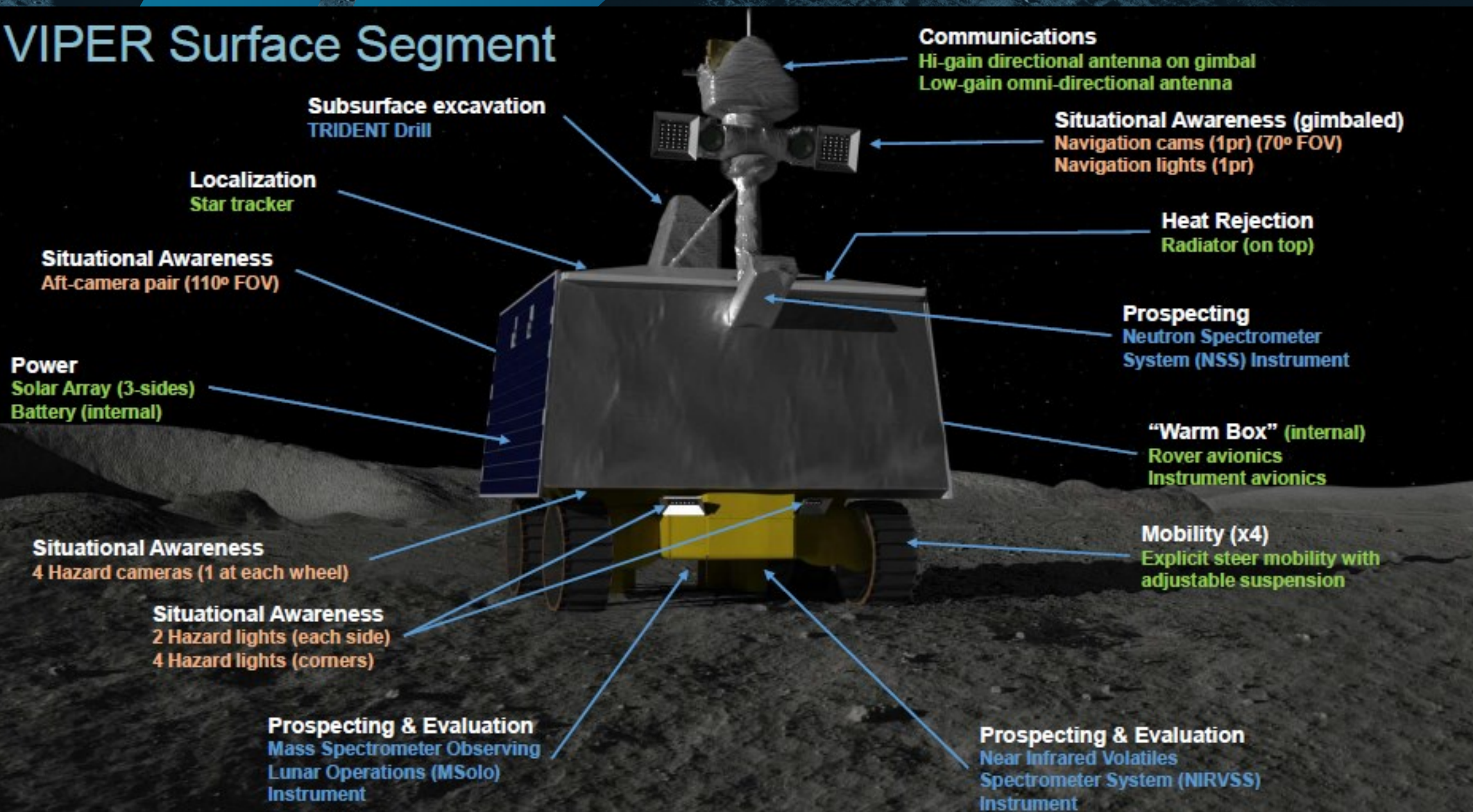
- “**Surface**” - Ice expected stable on the surface (PSRs – Permanently Shadowed Regions)
- “**Shallow**” - Ice expected stable between 0-50cm of the surface
- “**Deep**” - Ice expected stable between 50-100 cm of the surface
- “**Dry**” - Ice *not* expected stable (0-100cm *too warm* to be stable)

\* ISR's are based on the predicted thermal stability of ice with depth



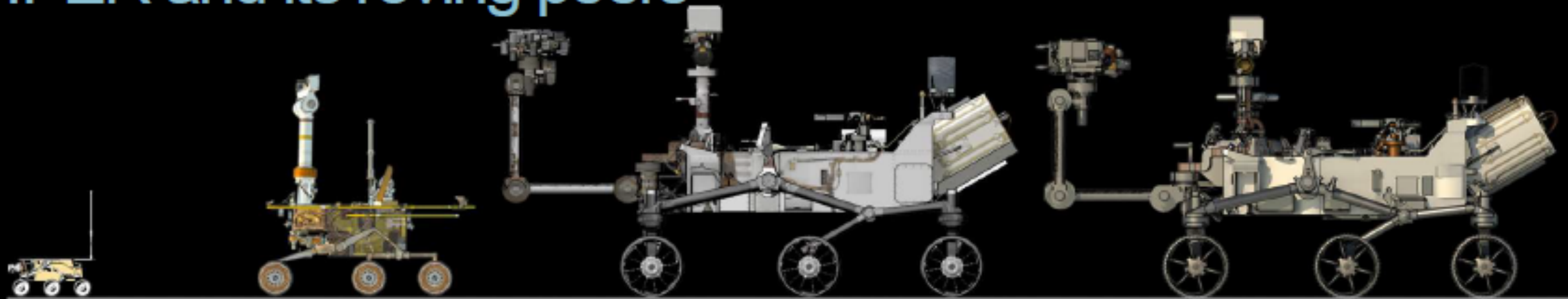


# VIPER Surface Segment





# VIPER and its roving peers



**Sojourner (1996)**

0.6m x 0.5m x 0.3m

11kg

Top Speed: 5cm/s

Plutonium-238 RHUs

**Mars Exploration Rover (2004)**

1.6m x 2.3m x 1.5m

180kg

Top Speed: 5cm/s

Plutonium-238 RHUs

**Mars Science Laboratory (2011)**

3.0m x 2.8m x 2.1m

900kg

Top Speed: 4cm/s

Plutonium-238 MMRTG

**Mars 2020 Rover (2020)**

3.0m x 2.7m x 2.2m

1025kg

Top Speed: 4.2cm/s

Plutonium-238 MMRTG



**Lunokhod 1 & 2 (1970/1973)**

2.3m x 1.6m x 1.5m

840kg

Top Speed: 55cm/s

Polonium-210 heat source

**Lunar Roving Vehicle (1971/1972)**

3.1m x 1.6m x 1.5m

210kg

Top Speed: 500cm/s

2 silver-zinc 36 volt batteries

**Yutu (2013/2019)**

1.5m x 1.1m x 1.1m

140kg

Top Speed: 5cm/s

Plutonium-238 RHUs

**VIPER (2023)**

1.5m x 1.5m x 2.0m

430kg

Top Speed: 20cm/s

Electric heaters only



# VIPER Instrument overview

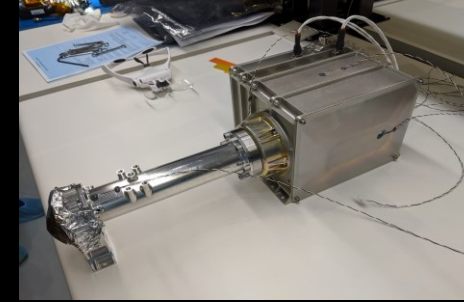
Neutron Spectrometer System (NSS)



Near InfraRed Volatiles Spec.  
System (NIRVSS)



Mass Spec. Observing Lunar  
Operations (MSolo)



The Regolith and Ice Drill  
for Exploring New  
Terrains (TRIDENT)

Instrument	Measurements	Observations
NSS	Thermal and Epithermal Neutrons	Water Equivalent Hydrogen and burial depth along traverse
NIRVSS	NIR reflectance spectra from 1300-4000 nm Imaging (2048 x 2048 pxl max resolution) with 7 color LEDs from 348 to 940 nm Thermal Radiometry at 10, 14, 18 and 6-25 um	Surface composition (mineralogy, hydration, frosts) along traverse and from drill cuttings pile Context imaging below the rover along the traverse; High resolution imaging (<100 um/pxl) at drill sites Surface temperatures under the rover and during drilling down to <100 K
MSolo	Mass spectra between 1-100 amu	Subliming surface volatiles along traverse and from drill cuttings pile Key isotope ratios
TRIDENT	Excavation of subsurface material in 10 cm increments down to 100 cm Subsurface temperatures at 2 locations (separated by 20 cm)	Regolith geomechanically properties, including discerning ice-rich from dry regolith Subsurface temperatures and thermal conduction

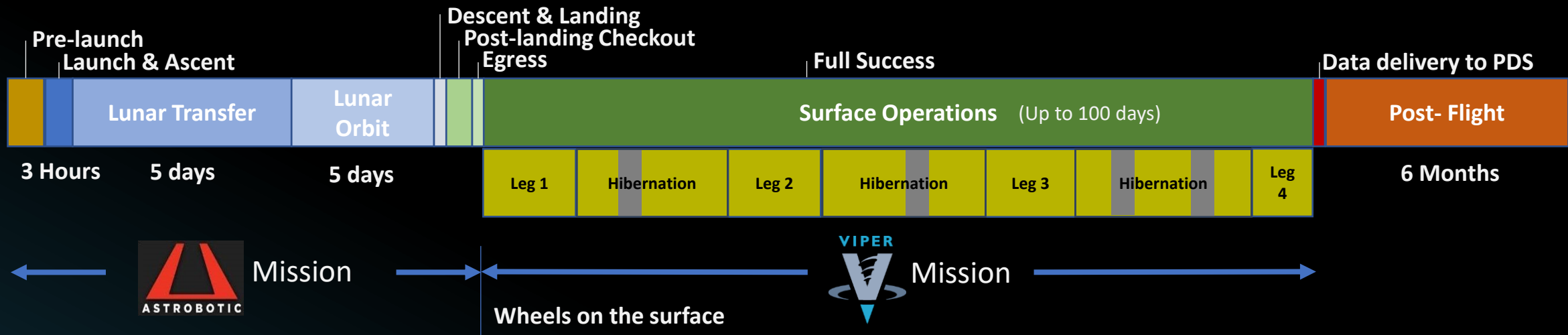


# VIPER Instrument Earlier Flights

VIPER's instruments expected to fly (at least once) on other CLPS Mission opportunities *prior to* the VIPER mission

Instrument:	Mission:	Landing site:	CLPS Task:	Flight:
NSS	Astrobotic Peregrine Mission 1	<i>Lacus Mortis, northern latitude</i>	CLPS-02	2022
NIRVSS				
MSolo				
MSolo	PRIME-1	<i>Shackleton Connecting Ridge, South Pole</i>	CLPS PRIME-1	Nov/Dec 2022
TRIDENT				
NSS	Masten Mission One	<i>Haworth crater, South Pole</i>	CLPS-19C	<del>2022</del>
NIRVSS				Nov/Dec
MSolo				2023

# VIPER Mission Phases



- Surface Ops consist of periods of activity (“traverse legs”) and periods of inactivity (“hibernations”)
  - Traverse legs are in view of Earth and sun (except for planned shadow (PSR) ops (<8 hours))
  - Hibernations are NOT in view of Earth, but in view of sun, with periods of sun shadow (<72hrs)
  - Lunar Day = one Traverse Leg + one Hibernation
- Mission Success:
  - Minimum Mission Success planned by end of Lunar Day 1
  - Full Mission Success planned by end of Lunar Day 2
  - Lunar Days 3 (and 4 if possible) offer either contingency time, or improved science data



NASA CLPS program has selected **Astrobotic Technology** to deliver VIPER to the lunar South Pole in late-2023 aboard their Griffin Lander

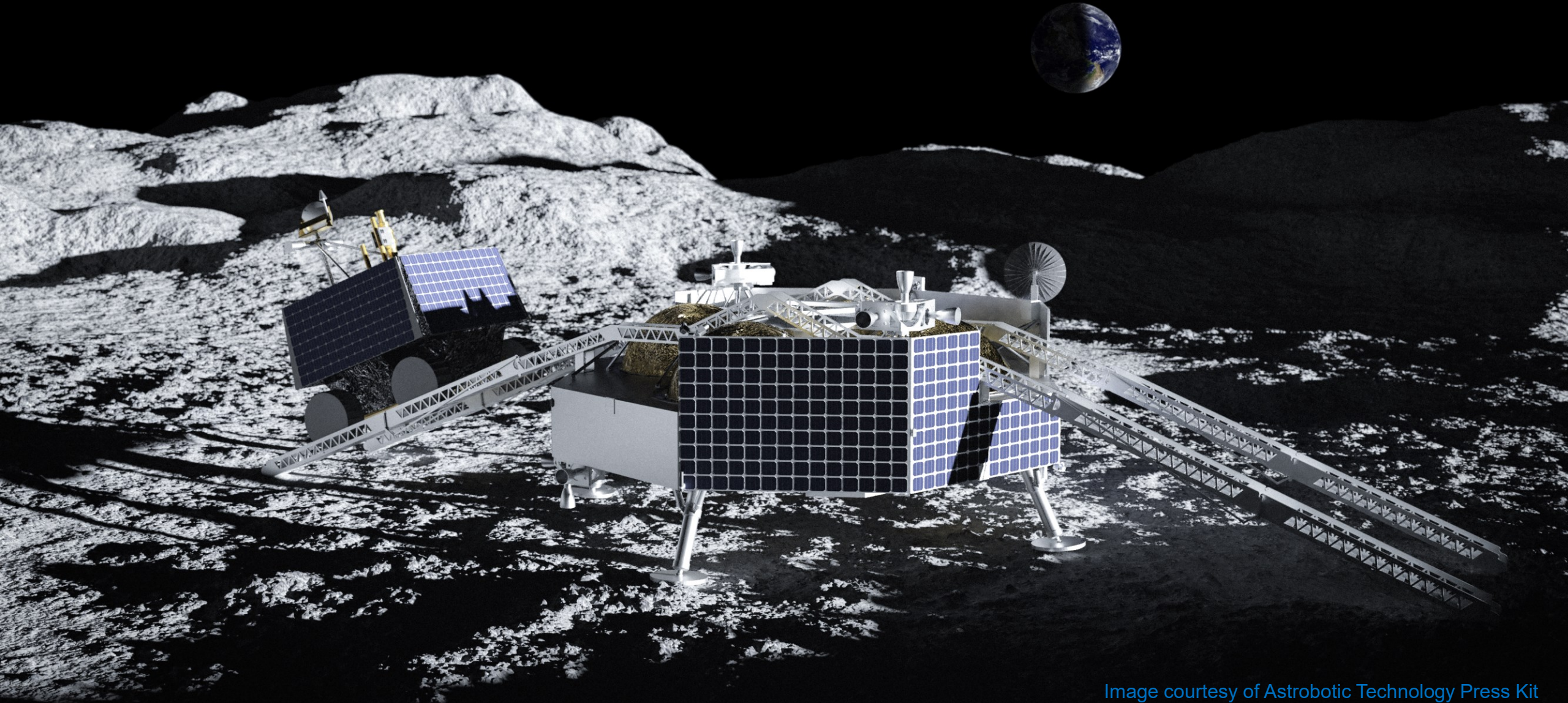
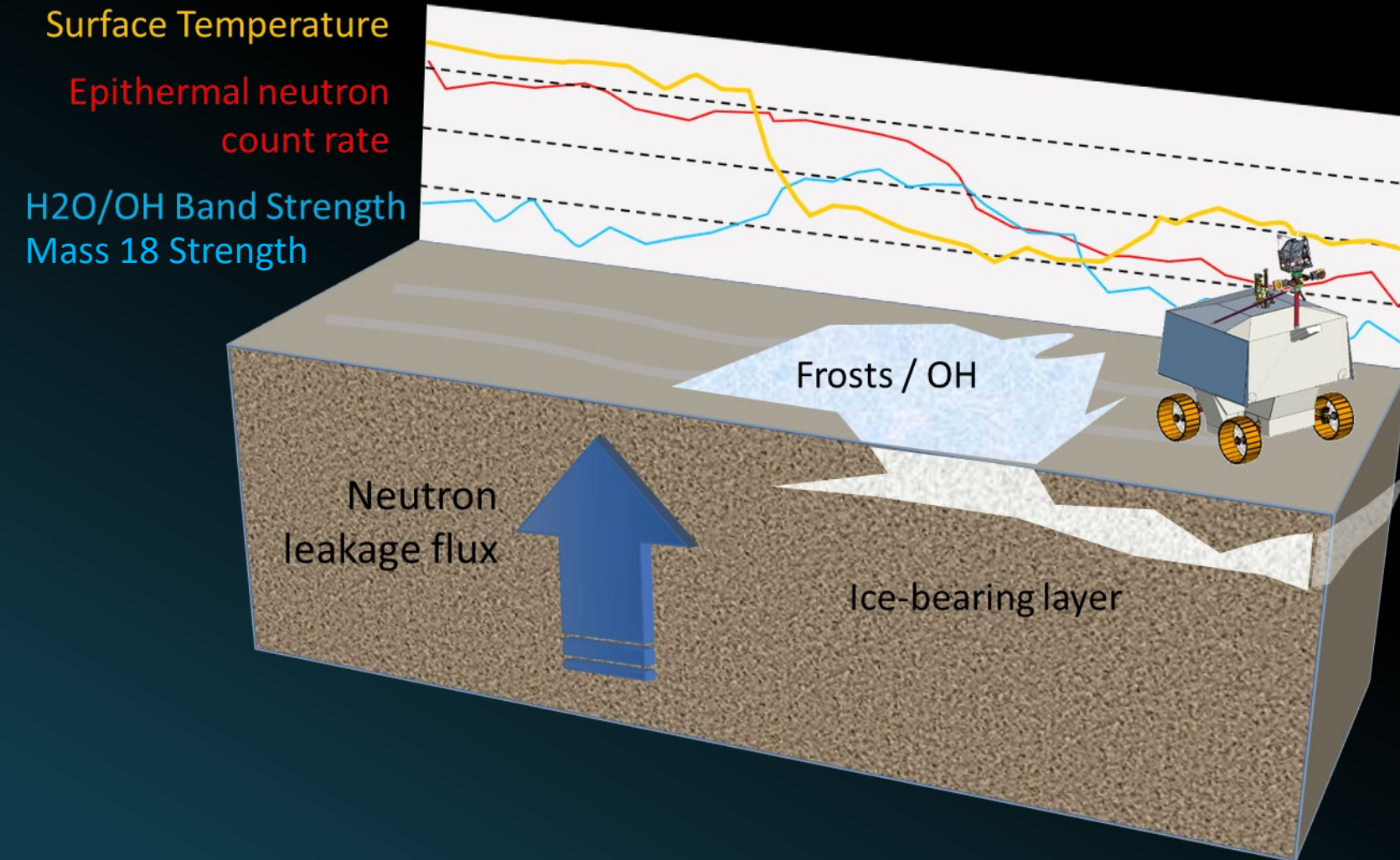


Image courtesy of Astrobotic Technology Press Kit



# Prospecting characterizes regions & identifies points to drill

## Prospecting: NSS, NIRVSS & MSolo

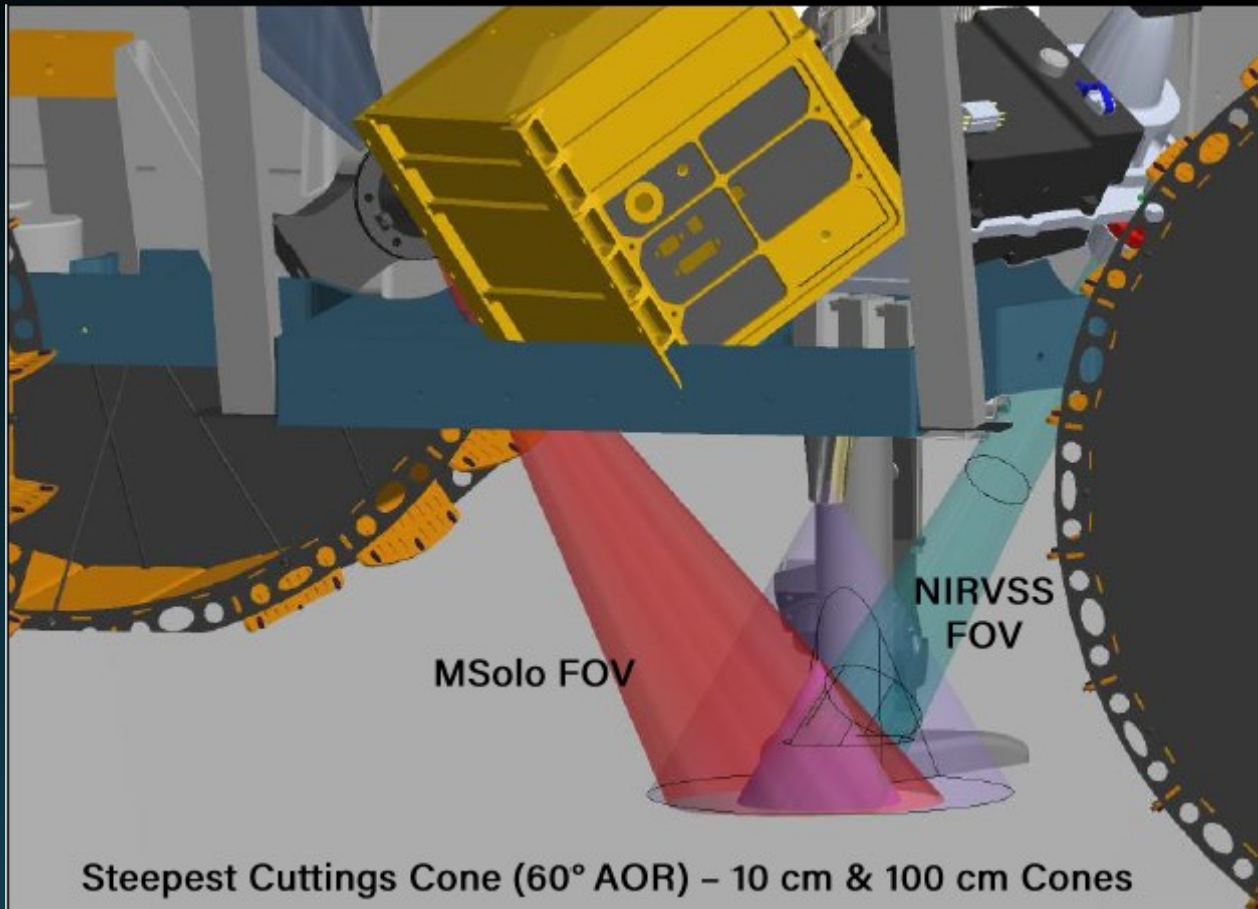


- NSS, NIRVSS & MSolo take data continuously while roving or parked
- NSS Neutron flux variations identify abundance and burial depth of hydrogenous materials
- NIRVSS NIR surface reflectance identifies surface and excavated hydration
- MSolo detects subliming gasses (H<sub>2</sub> or H<sub>2</sub>O vapor) identify surface and excavated hydration



# Sampling: TRIDENT, NIRVSS and MSolo

Sampling via the TRIDENT, MSolo and NIRVSS profile water (and other volatiles with depth, tying down NSS derived concentrations)



- TRIDENT samples in 10 cm “bites” down to 1 meter, using a simple auger bit
- Each 10cm sample can be brushed to the surface for inspection by NIRVSS and MSolo
- NIRVSS images the cuttings at multiple wavelengths (providing context for NIRVSS and MSolo observations) and measures the scene temperature
- This process identifies the stratification of hydrogen bearing volatiles, “tying down” NSS measurements

# VIPER Mission Area

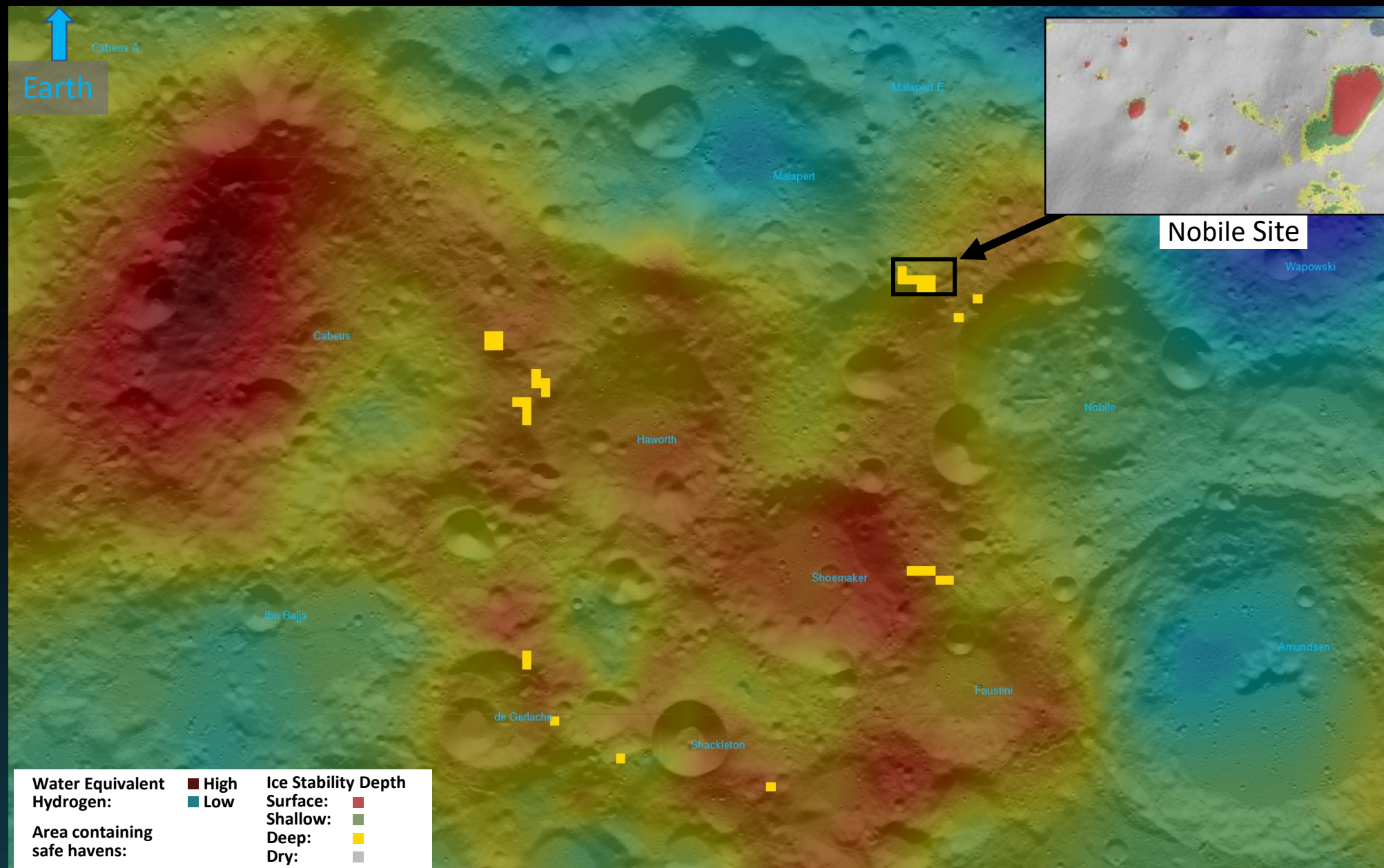
Needed: location with ...

High water-equivalent  
hydrogen  
(background map)

A variety of thermal  
environments using ice  
stability depth as an  
indicator  
(insets)

Periods of shadow short  
enough for the rover to  
survive  
(yellow blocks)

Unobscured line-of-site to  
Earth for communications



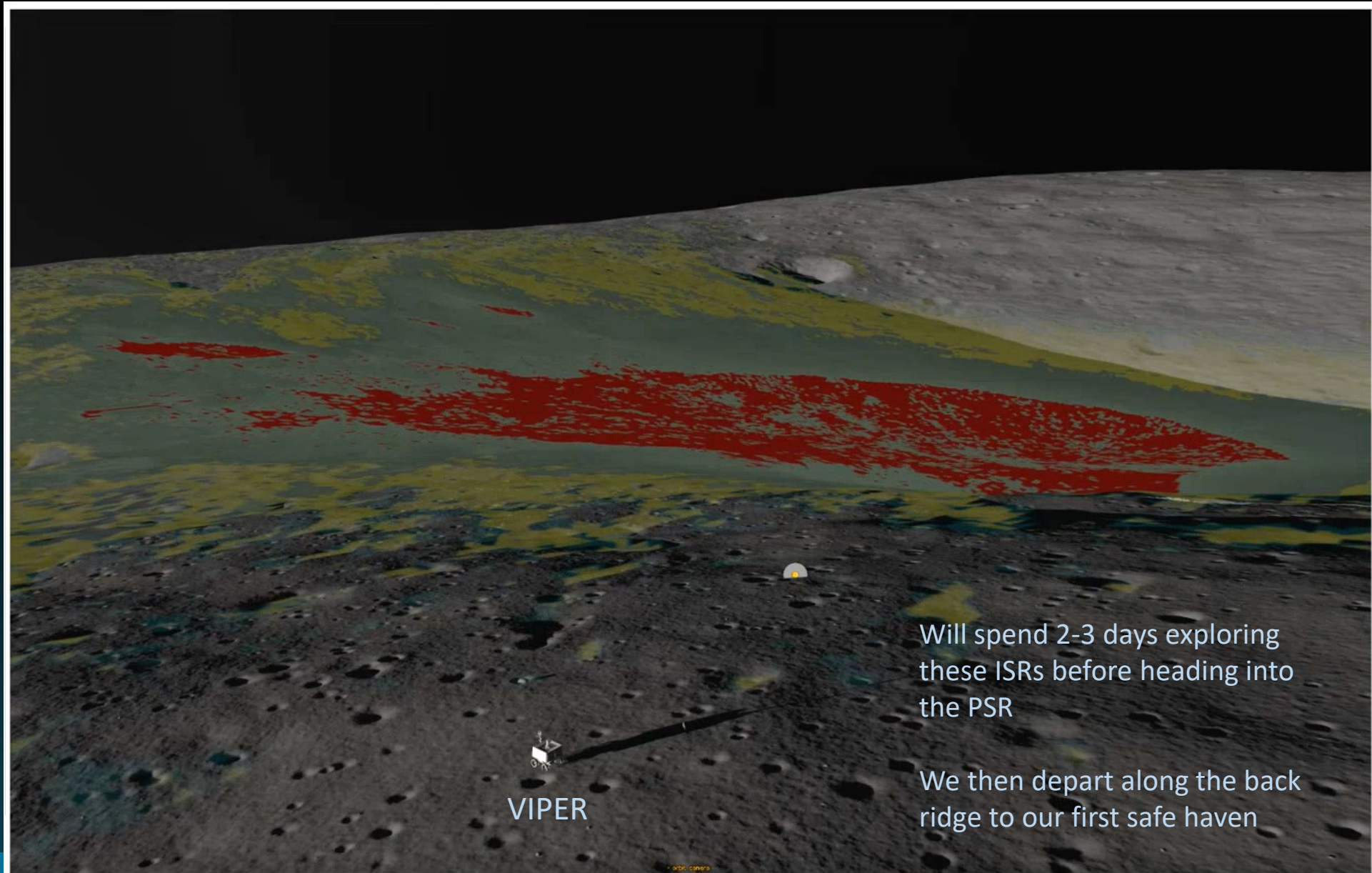


# VIPER Nobile mission region on the Lunar South Pole



Screenshot  
from the  
VIPER  
Traverse  
Planning tool  
/M. Shirley

# VIPER and the four Ice Stability Regions (ISRs)



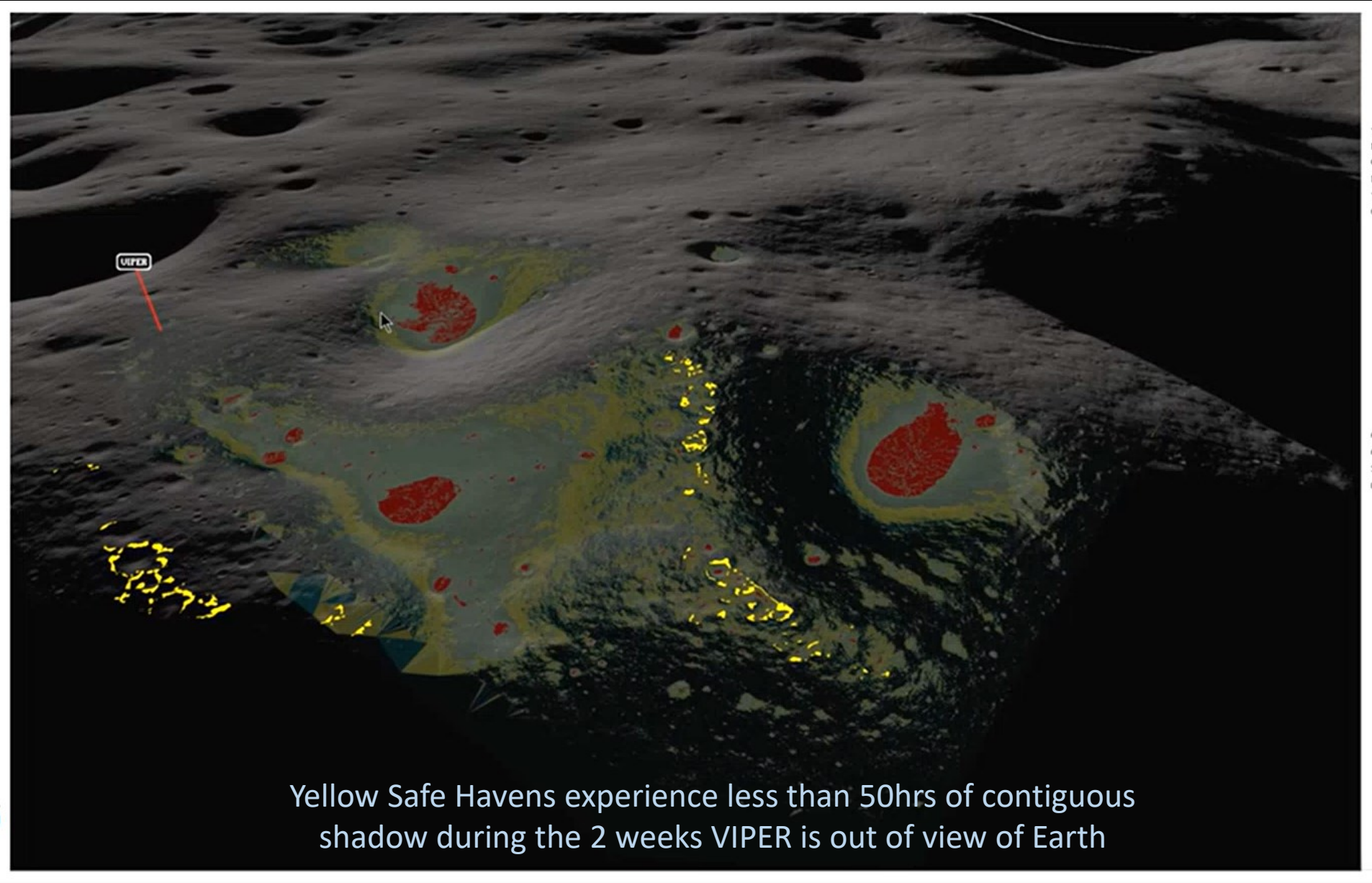
Will spend 2-3 days exploring these ISRs before heading into the PSR

We then depart along the back ridge to our first safe haven

Screenshot from the VIPER Traverse Planning tool /M. Shirley



# Nobile region with Safe Havens

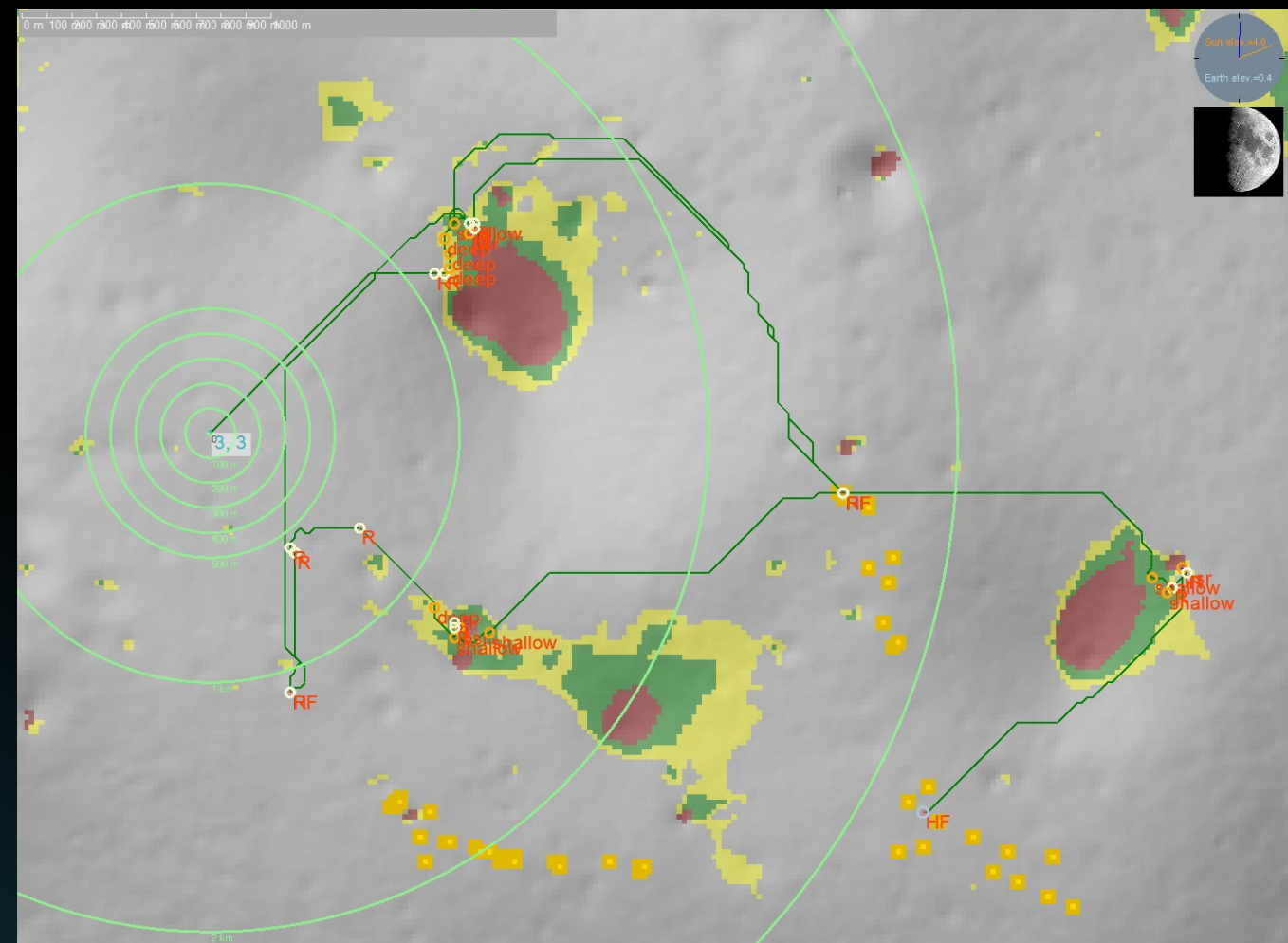


Screenshot  
from the  
VIPER  
Traverse  
Planning tool  
/M. Shirley

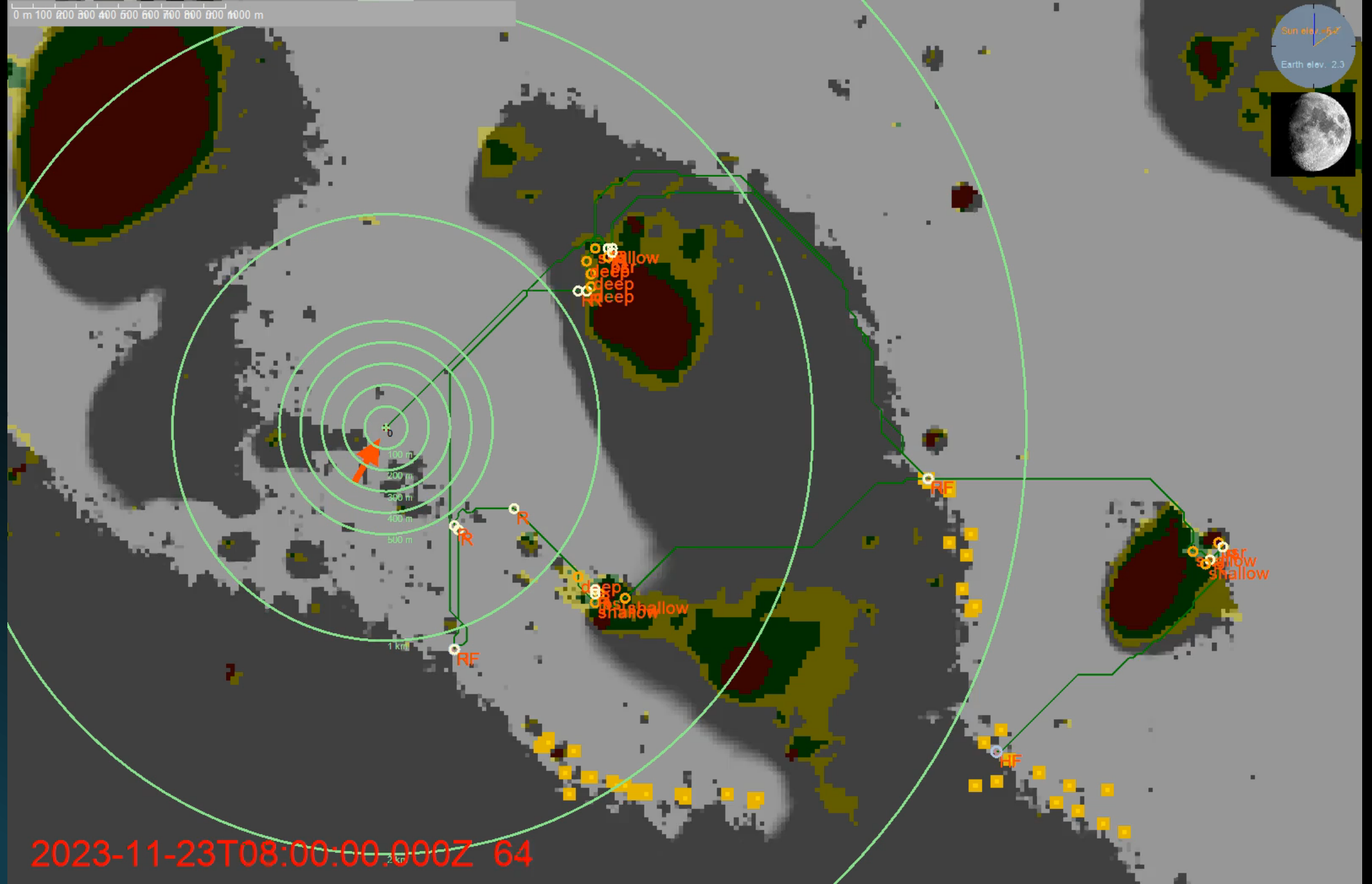


# Top Ranked Nobile Area Traverse

Key Parameter	Value		
Launch Date (est)	3 pm 11/10/2023 (all times UTC)		
Lunar transfer duration	5 days		
Lunar Orbit Insertion (est)	10:45pm 11/15/2023		
Lunar orbit duration	7 days		
Landing time	8 am 11/23/2023		
Total mission duration	106 days + option for 28 more		
Surface mission duration	94 days + option for 28 more		
Active days on the surface	45 days + option for 10 more (but limited science)		
Landing location	85.449452S, 31.064135E		
Average slope at landing site	5°		
Light and comm at landing site	12 days		
Total driving distance	4.4 km prospecting, 27.4 total		
Max distance from landing site	3 km		
Science Stations	12	2 psr	4 shallow
		4 deep	2 dry
Full mission success reached	Day 37, near end of 2 <sup>nd</sup> lunar day		
Driving Speed	0.813 cm/s normal 0.613 cm/s sunward		



In the Nobile Area





Rover lander egress testing with full-scale lander mockup and test rover at JSC





# VIPER

Rover build pathfinder at JSC



Rover thermal test unit in TVAC at MSFC



Questions?





# VIPER Instrument overview

**Neutron Spectrometer System (NSS)**  
**NSS (NASA ARC, Lockheed Martin ATC)**  
PI: Rick Elphic (NASA ARC)



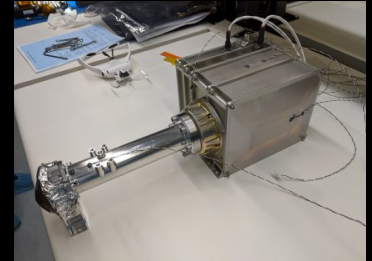
**Instrument Type:** Two channel neutron spec

**Key Measurements:** NSS assesses hydrogen and bulk composition in the top meter of regolith, measuring down to 0.5% (wt) WEH while roving

**Operation:** On continuously while roving

**Specs:** 1.9kg, 1.6w, 21x32x7cm (sensor) / 14x18x3cm (Data proc. module)

**Mass Spec. Observing Lunar Operations (MSolo)**  
**MSolo (KSC, INFICON)**  
PI: Janine Captain (NASA KSC)



**Instrument Type:** Quadrupole mass spectrometer

**Key Measurements:** Identify low-molecular weight volatiles between 1-100 amu, unit mass resolution to measure isotopes including D/H and  $O^{18}/O^{16}$

**Operation:** Views drill cuttings, volatile analysis while roving and during drill activities

**Specs:** 6.0kg, 35w, 16x20x46cm

**Near InfraRed Volatiles Spec. System (NIRVSS)**  
**NIRVSS (ARC, Brimrose Corporation)**  
PI: Anthony Colaprete (NASA ARC)



**Instrument Type:** NIR Point Spectrometer, 4Mpxl Panchromatic Imager w/7 LEDs, 4-ch thermal radiometer

**Key Measurements:** Volatiles including  $H_2O$ , OH, and  $CO_2$  & mineralogy, surface morphology/temps

**Operation:** On continuously while roving and during drill operations

**Specs:** 3.6kg, 29.5w, 18x18x9cm (spec) / 20x13x15cm (Obs bracket)

**The Regolith and Ice Drill for Exploring New Terrains (TRIDENT) Drill**  
**TRIDENT (Honeybee Robotics)**  
PI: Kris Zacny (Honeybee)



**Instrument Type:** 1-meter hammer drill

**Key Measurements:** Excavation of subsurface material to 100 cm; Subsurface temperature vs depth; Strength of regolith vs depth

**Operation:** Subsurface assays to 100 cm in <1 hr, depositing cuttings at surface

**Specs:** 18kg, 20w/175w (nom/max), 27x22x177cm